KOGANEI

Catalog No.BK-C0038

http://www.koganei.co.jp



Smallest Lightest Compact Basic Cylinders BC Cylinders

Possible to create all assembly processes with just BC cylinders Wide range of variations from $\phi \in [0.236 \text{ in}]$ to $\phi = 125 [4.9 \text{ in}]$

NEW Heat resistant specification, clean room specification, with locating pin hole, and more!



Corrosion resistant, heat resistant, scraper specifications
 Clean system compatible cylinders
 With locating pin hole (option)

Double rod cylinders: Selectable thread type
 Piston rod end shape (order made)

NEW Step 2 variations

Corrosion resistant specification -

- Piston rod
- Snap ring: Electroless nickel plated
- Guide: H1 grease
 Packing: NBR

Compatible cylinders

- Double acting type ϕ 6 [0.236] to ϕ 125 [4.9] 23 Page
- Single acting push type, single acting pull type ϕ 6 [0.236] to ϕ 50 [1.969] 2 Page
- Double rod end cylinders ϕ 6 [0.236] to ϕ 125 [4.9] $\overline{\boldsymbol{w}}$ Page
- Cylinder with guide ϕ 6 [0.236] to ϕ 40 [1.575] \bigcirc Page

Heat resistant specification ·

Up to a maximum of 150°C [302 °F].

Packing: fluoro rubber

Note: Sensor switch cannot be attached.

Compatible cylinders

• Double acting type ϕ 6 [0.236] to ϕ 125 [4.9] 2 Page

• Cylinder with guide ϕ 8 [0.315] to ϕ 40 [1.575] 5 Page

Scraper specification -

Compatible with environments where dust and water droplets are present.

Compatible cylinders



With dust collection port: Class 5 equivalent Without dust collection port: Class 6 equivalent

Compatible cylinders

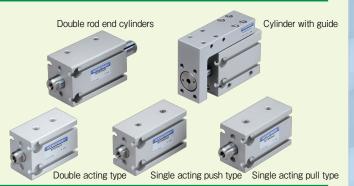
- Double acting type (With dust collection port) $\phi 6$ [0.236] to $\phi 63$ [2.480] Page
- Double acting type (Without dust collection port) ϕ 10 [0.394] to ϕ 63 [2.480] 0 Page
- Cylinder with guide (Without dust collection port) ϕ 8 [0.315] to ϕ 40 [1.575] (2) Page

With locating pin hole (option) ·

Cylinder body: Pin holes in three sides Table: Pin holes in two sides

Compatible cylinders

Cylinder with guide φ8 [0.315] to φ40 [1.575]
 (2) Page







Double acting type

Cylinder with guide





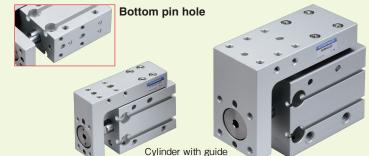
Double acting type



Double acting type



With dust collection port



Guide to recommended related products!

For details, see our homepage. http://www.koganei.co.jp

F series solenoid valves (F10•F15•F18)

Low-current type and single/double dual-use valves offer energy savings and a low price.

- Switch the manual override button to select single solenoid valve or double solenoid valve functions on the 2-position valve of the F series.
- Different tube sizes for piping are possible with dual-use different size fittings.

iB-Cyclone

High-speed cyclone type water separator!

- •Half the volume ratio and 99% higher moisture separation rate when compared with equivalent equipment.
- •No element used for maintenance-free operation.
- Auto drain function (NC and NO) available.
- Specifications for ozone resistance, NCU specifications (copper free) compatible as standard.

Smaller size FRZB filter regulator

FRZB filter regulator with moisture and fluid removal function!

- Compact size with short face-to-face dimensions.
- •With drain cock and easy to use moisture and fluid removal function.
- •Auto drain function (NC and NO) available.
- •Bowl guard available.

FRZ Series Air filter.Oil mist filter.Micromist filter

Downsized! Short face-to-face dimensions! Visible filter element!

- Compact size with short face-to-face dimensions.
- It is easy to check the state of the filter element.
- •Auto drain function (NC and NO) available.





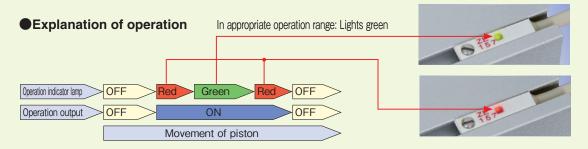


5 KOGANEI



Two-color LED sensor switches

Two-color LED sensor switches that can be easily positioned and adjusted. Appropriate operation range can be determined by the color of the LED indicator!



MTV Series water removal valves

Our answer to counteracting condensation! Prevent condensation from developing inside the piping to pneumatic grippers and small cylinders!

Simply connect it in the pipes! Easy mounting!

iB-Flow Digital flow controller

Constantly monitors cylinder tact times and adjusts automatically!

- Digitally set cylinder tact times (operation cycle times).
- •Tact time controller is always monitoring and adjusting.
- Safety mechanism prevents needle from loosening.
- •Numeric setting of needle opening (0 to 100%).

Quick fitting series

Wide range of variations such as many types of quick fittings and speed controllers with quick fittings!

- Standard types, mini types, and SUS specifications available.
- Diverse variations available such as quick fittings with stop valves, hand valves, check valves, throttle valves, and power reducers.





Before selecting and using the products, please read all the safety precautions carefully to ensure proper product use. The safety precautions described below are to help you use the product safely and correctly, and to prevent injury or damage to you, other people, and assets. Always observe these safety precautions and the following safety regulations: ISO4414 (Pneumatic fluid power - General rules and safety requirements for systems and their components) and JIS B 8370 (General rules relating to systems).

The directions are ranked according to degree of potential danger or damage: "DANGER", "WARNING!", "CAUTION!", and "ATTENTION!".

	Indicates situations that can be clearly predicted as dangerous. Death or serious injury may result if the situation is not avoided. It could also result in damage or destruction of assets.
WARNING Indicates situations that, while not immediately dangerous, could become dangerous. Death or serious injury may result if the situation is not avoided. It could also result in damage or destruction of assets.	
	Indicates situations that, while not immediately dangerous, could become dangerous. Failure to avoid the situation creates the risk of minor or semi-serious injury. It could also result in damage or destruction of assets.
	While there is no chance of injury, these points should be observed for appropriate use of the product.

This product was designed and manufactured for use in general industrial machinery.

When selecting and handling equipment, the system designer or another person with sufficient knowledge and experience should always read the safety precautions, catalog and other literature before commencing operation. Improper handling is dangerous.

After reading the catalog, and other documentation, always place them in a location that allows easy availability for reference to users of this product.
 Whenever transferring or lending the product to another person, always attach the catalog, and other information to the product where they are easily visible in order to ensure that the new user can use the product safely and properly.

The danger, warning and caution items listed under these safety precautions do not cover all possible contingencies. Read the catalog carefully, and always keep safety first.

- Do not use the product for the purposes listed below:
 - 1. Medical equipment related to maintenance or management of human lives or bodies
 - 2. Machines or equipment designed for the purpose of moving or transporting people
 - Critical safety components in mechanical devices This product has not been planned or designed for purposes that require high levels of safety. Using the product in any of the ways described above creates the risk of loss of human life.
- Do not use the product in locations with or near dangerous substances such as flammable or ignitable substances. This product is not explosion-proof. Doing so creates the risk of ignition and fire.
- When mounting the product and workpiece, always make sure they are firmly supported and secured in place. Falling, dropping, or abnormal operation of the product creates the risk of personal injury.
- Persons using a pacemaker or other similar medical devices should maintain a distance of at least one meter [3.28 ft] away from the product. Getting too close to the product creates the risk of malfunction of a pacemaker due to the strong magnet built into the product.
- Never attempt to modify the product in any way. Doing so creates the risk of injury, electric shock, fire, etc. due to abnormal operations.
- Never attempt inappropriate disassembly, assembly or repair of the product relating to basic construction, or to its performance or to functions. Doing so creates the risk of injury, electric shock, fire, etc.
- Do not allow water to splash on the product. Water spraying on the product, washing the product, or using the product under water creates the risk of malfunction, leading to injury, electric shock, fire, etc.
- While the product is in operation, avoid touching it with your hands or otherwise approaching too close. Also, do not attempt to make any adjustments to internal or attached mechanisms (sensor switch mounting location, disconnection of piping tubes or plugs, etc.) while the product is in operation. This may cause an unintended cylinder movement resulting in injury.
- When operating the product, always install speed controllers, and gradually loosen the needle valve from a choked state to adjust the increase in speed.

Failure to make this adjustment could result in the air supply causing sudden movements, which may put human lives at risk.

- Do not apply excess bending or buckling force to the piston rod. Doing so may cause abnormal wear or damage to the rod or tube and reduce the product's operating life.
- Always link the direction of motion of the load with the axis of the piston rod. If they are not the same, the undue force on the tube and piston rod may cause abnormal wear or damage.

- Do not use the product in excess of its specification ranges. Doing so creates the risk of product breakdown, loss of function, or damage. It could also drastically reduce the product's operating life.
- Before supplying air or electricity to the device and before starting operation, always conduct a safety check of the area where the machine is operating. Unintentional supply of air or electricity creates the risk of electric shock or injury due to contact with moving parts.
- Do not touch terminals or switches while power is turned on. Doing so creates the risk of electric shock and abnormal operation.
- Always check the catalog and other reference materials for correct product wiring and piping. Improper wiring and piping creates the risk of abnormal operation of the cylinder.
- Do not allow the product to be thrown into fire.

Doing so creates the risk of explosion and the release of toxic gases.

 Do not sit on the product, place your foot on it, or place other objects on it.

Doing so creates the risk of injury due to tripping or the product tipping over or falling, resulting in product damage, malfunction or runaway operation.

 Before conducting maintenance, inspection, repair, replacement, or any other similar procedure, always completely cut off all air supply and confirm that residual pressure inside the product or in piping connected to the product is zero.

In particular, be aware that residual air will still be in the air compressor or storage tank. The cylinder may move abruptly, if residual air pressure remains inside the piping, causing injury.

- Do not use the cylinder as a device to absorb the shock or vibration of machinery. Doing so may create the risk of injury or the breakdown of the machinery.
- Do not allow lead wires of sensor switches or other cords to become damaged.

Allowing a cord to become damaged, bent excessively, pulled, rolled up, placed under heavy objects, or squeezed between two objects creates the risk of current leaks or defective continuity that can lead to fire, electric shock, or abnormal operation.

- Do not apply external magnetic field to sensor switches while the cylinder is in operation. Unintended operations could damage equipment or cause injury.
- Use the product within the recommended load and operating speed specifications. Using the cylinder in excess of the recommended load and operating speed specifications could damage the cylinder causing damage to equipment or injury.
- Use safety circuits or design a system that prevents damage to machinery and personal injury when the machine is shut down due to an emergency stop or electrical power failure, etc.
- Install relief valves or other devices to ensure that the cylinder does not exceed its rated pressure when the pressure is increased by external forces on the cylinder. Excessive pressure could lead to a breakdown and damage.
- When the product has been idle for over 48 hours or has been in storage, it is possible that the contacting parts may have become stuck leading to operating delays or sudden movements. Before initial operations, always run a test to check that operating performance is normal.
- Do not use the product near the ocean, in direct sunlight, near mercury vapor lamps, or near equipment that generates ozone. Deterioration of rubber parts caused by ozone may reduce performance and functions or stop functions.
- Because Koganei products may be used under a wide variety of conditions, decisions concerning conformance with a particular system should be made upon the careful evaluation by the person in charge of system design. Assurances concerning expected system performance and safety are the responsibility of the designer who decides system conformity. Be sure to use the latest catalogs and technical materials to study and evaluate specification details, to consider the possibility of machine breakdown, and to configure a system that ensures fail-safe safety and reliability.
- Do not apply force to cylinder rods and tables outside the ranges of allowable lateral load, allowable kinetic energy, allowable moment, and other values shown in the catalog and other documentation. Doing so may cause wear or damage to the rod or tube and reduce the product's operating life.

- Do not use the product in locations subject to direct sunlight (ultraviolet radiation), in locations with dust, salt, or iron particles, or in locations with media and/or ambient atmosphere that include organic solvents, phosphate ester type hydraulic oil, sulfur dioxide gas, chlorine gas, acids, etc. Such uses could lead to loss of functions within a short period, sudden degradation in performance, or reduced operating life. For details on materials used in the product, refer to the description of materials used in major parts.
- When mounting the product, leave room for adequate working space around it. Failure to do so will make it more difficult to conduct daily inspections or maintenance, which could eventually lead to system shutdown or damage to the product.
- When transporting or mounting a heavy product, firmly support the product using a lift or support, or use multiple people to ensure personal safety.
- Do not bring any magnetic media or memory within one meter [3.28 ft] of the product. Doing so creates the risk of damage to data on the magnetic media due to magnetism.
- Do not use the sensor switch in locations subject to large electrical currents or strong magnetic fields. It could result in erratic operation.

Also avoid using magnetic material for any parts used for mounting. Doing so creates the risk of magnetism leakage that causes malfunctions.

- Do not bring the product too close to magnetic material. The sensor switch may malfunction or operate erratically if the product is located near a magnet or where a magnetic field is generated.
- Never use another companies' sensor switches with these products.

Doing so may cause malfunctions or runaway operation.

Do not scratch, dent, or deform the actuator by sitting or standing on the product, or by placing objects on it. Doing so creates the risk of damage to or breakage of the product, resulting in operational shutdown or degraded performance.

- Always post an "operations in progress" sign for installations, adjustments, or other operations, to avoid unintentional supplying of air or electrical power, etc. Unintended power or air supply can cause electric shock and sudden cylinder movement, creating the risk of personal injury.
- Do not subject any cords, such as the sensor switch lead wires, to excessive loads by pulling on them, lifting the product by them, or placing heavy objects on them. Doing so may cause current leakage or defective continuity leading to fire, electric shock, or abnormal operation.
- Using extremely dry air with a dew point lower than -20°C [-4°F], may affect the quality of the lubricating oil used. This may cause loss of functions, shorter operating life, degraded performance or other problems.
- Be sure to wash your hands thoroughly after touching the heat resistant specification and clean room specification grease. Smoking a cigarette with hands soiled with grease creates the risk of emission of toxic gas when grease adhering to the cigarette burns. (Though the grease is very stable at normal temperature, it emits toxic gas when its temperature exceeds 260°C [500°F].)

- Whenever considering use of this product in situations or environments not specifically noted in the catalog, or in applications where safety is an important requirement such as in aircraft facilities, combustion equipment, leisure equipment, safety equipment, and other places where human life or assets may be greatly affected, take adequate safety precautions such as allowing plenty of margin for ratings and performance, or fail-safe measures.
- Be sure to contact Koganei before use in such applications.
- Moving parts of machinery should be isolated with protective covers so as not to come into direct contact with human bodies.
- Do not configure controls that would allow workpieces to fall if power fails.
 Configure the control system to provent workpieces or tables

Configure the control system to prevent workpieces or tables from falling if the machinery stops during an emergency stop or power outage.

- When handling the product, wear protective gloves, safety glasses, safety shoes, and other protective clothing whenever necessary.
- When the product can no longer be used or is no longer necessary, dispose of it appropriately as industrial waste.
- Pneumatic equipment can exhibit degraded performance and function over its operating life. Always conduct daily inspections of the pneumatic equipment, and confirm that all requisite system functions are satisfied, to prevent accidents from happening.
- For inquiries about the product, consult your nearest Koganei sales office or Koganei Overseas Department. The addresses and telephone numbers are shown on the back cover of this catalog.

<u> Other</u>

- Always observe the following items.
 - 1. When using this product in pneumatic systems, always use genuine Koganei parts or compatible parts (recommended parts).

When conducting maintenance and repairs, always use genuine Koganei parts or compatible parts (recommended parts).

Always observe the prescribed methods and procedures.

 Never attempt inappropriate disassembly or assembly of the product in relation to its basic construction, performance, or functions.

Koganei cannot be held responsible for any problems that occur as a result of these safety precautions not being properly observed.



Design and selection

1. Check the specifications.

Read the specifications carefully to ensure correct use within the product's specified voltage, current, temperature, and shock ranges, failure to do so could result in a breakdown or defective operation.

2. Be careful when mounting cylinders in close proximity to each other.

Refer to page **(9)** if you are mounting more than two cylinders, with sensor switches, in parallel. The magnetic field interference may cause the sensor switches to malfunction.

3. Be careful of how long the sensor switch is on when detecting the position in mid-stroke.

Be aware that, when the sensor switch is mounted at an intermediate point of the cylinder stroke to detect the passing of the piston, if the piston is moving too fast, the length of time the sensor switch operates is too short to delete the piston passing (so loads such as programmable controllers are not operated). The highest detectable cylinder speed is

I ne nignest detectable cylinder speed is

V mm/s [in/sec]= Sensor switch operating range mm [in] Time required for load operation [ms] ×1000

4. Keep wiring as short as possible.

Lead wires for solid state sensor switches should be within 30 m [98 ft] as stipulated by EN standards. For reed sensor switches, longer wiring (10 m [33 ft] or longer) will lead to a larger capacitive surge, which reduces the operating life of sensor switches. When longer wiring cannot be avoided, provide the protective circuit described in the catalog. For details, see page **(3)**.

If the load is inductive or capacitive, provide the appropriate protective circuit as described in the catalog. For details, see page ⁽³⁾.

5. Avoid repeated bending or excessive pulling of lead wires.

Applying repeated bending stress or tension force on the lead wires could break them.

6. Check for leakage current.

With 2-lead wire solid-state sensor switches, current (leakage current) flows to the load to activate the internal circuit even when turned off. Ensure that the circuit satisfies the following inequality.

Input off current of programmable controller > Leakage current If the above inequality cannot be satisfied, select a 3-lead wire solid state sensor switch. And, if n sensor switches are connected in parallel, the leakage current increases by n times.

7. Do not use reed sensor switches at low speeds below 30 mm/s [1.2 in/sec]. Doing so may cause erratic operation or loss of functions.

1. Check for internal voltage drop of sensor switches. Connecting reed sensor switches with indicator lamps, or 2-lead wire solid state sensor switches, in series causes increasing internal voltage drop and the load may fail to activate. Connecting n switches will drop the internal voltage by n times as much.

Ensure that the circuit satisfies the following inequality:

Supply voltage – Internal voltage drop x n > Minimum operating voltage of the load In relays with rated voltage of less than 24 VDC, check that the above inequality is satisfied even when n=1.

If the above inequality cannot be satisfied, select a reed sensor switch without an indicator lamp.

2. Do not use Koganei sensor switches with other companies' cylinders.

The sensor switches are designed for use with Koganei cylinders only. They may not function correctly if used with other companies' cylinders.



Installation and adjustment

1. Do not apply an external magnetic field to the sensor switch while the cylinder is in operation.

This may cause unintended operation, thereby damaging the device or causing injury.

1. Be aware of the environment in which you install the sensors and cylinders.

Do not use the sensor switch in locations subject to large electrical currents or strong magnetic fields. It could result in erratic operation.

Also avoid using magnetic material for any parts used for mounting. It could result in erratic operation.

2. Install sensor switches in the center of their operating range.

Adjust the mounting position of a sensor switch so that the piston stops in the center of its operating range (the range while the sensor is ON). Operations will be unstable if mounted at the end of the operating range (at the boundary near on and off). Also be aware that the operating range will vary with changes in temperature.

3. Follow the tightening torque guidelines for mounting sensor switches.

Over-tightening beyond the allowed tightening torque may damage the mounting threads, mounting brackets, sensor switches and other components. However, insufficient tightening torque may cause the sensor switch position to change, resulting in unstable operation. Follow the instructions on page **①** concerning the tightening torque.

4. Do not carry the cylinder by its mounted sensor switch's lead wires.

After mounting a sensor switch on the cylinder, do not carry the cylinder by grabbing the lead wires. Never do this, as it may damage not only the lead wires but may also apply stress to the inside of the sensor switch that may damage internal elements.

5. Do not drop the sensor switches or bump them against other objects.

While handling sensor switches, do not subject them to excessive shock (294.2 m/s² [30 G] or larger) by hitting, dropping or bumping them.

In the case of reed sensor switches, such behavior may cause the contact to malfunction, thereby giving a signal output or turning off the signal instantaneously. And, this may change the contact interval, thereby deteriorating the sensor switch's sensitivity. As such, this may cause the device to malfunction. Even if the sensor switch case is not damaged, the inside of the sensor switch may be damaged, causing erratic operation.



1. Prevent nearby moving objects from coming into contact with sensor switches.

When cylinders equipped with sensor switches are moving or when moving objects are nearby, do not let them come into contact with each other. In particular, lead wires may become worn or damaged causing unstable operation of the sensor switch. In the worst case, this may result in current leaks or electrical shock.

2. Always turn off the power before doing wiring work. Doing wiring work while the power is on may result in electric shock. Also, incorrect wiring could damage the sensor switch in an instant. Turn on the power only after the wiring work is complete.

- 1. Check the catalog and other materials to ensure that the sensor switch is wired correctly.
- Incorrect wiring may result in abnormal operation.
 2. Do not share wiring with power or high voltage lines. Avoid wiring in parallel to or in the same conduit with power lines and high-voltage lines. Noise from such wiring could cause the sensor switch and control circuit to operate erratically.
- 3. Avoid repeated bending or excessive pulling of lead wires.

Applying repeated bending stress or tension force on the lead wires could break them.

4. Check the wiring polarity.

Be sure that the wiring connections are correct for sensor switches that specify polarity (+, -, output). Incorrect polarity could result in damage to sensor switches.

1. Avoid short circuiting loads.

Turning on the sensor switch while the load is short-circuited causes overcurrent, which will damage the sensor switch in an instant.

Example of short-circuit load: Sensor switch's output lead wire is directly connected to the power supply.

2. Position sensor switches in the center of their operating range.

Operating output may be unstable, depending on the operating environment, if positioned at the edge of the operating range.

- **3.** Solid state sensor switches that are compliant with the EMC standards (EN61000-6-2 and EN60947-5-2) are not resistant to surges from lightning. Use countermeasures on the machine to protect them from lightning surges.
- **4.** Use an internal element to absorb surges for direct activation of loads that generate surges.

Handling Instructions and Precautions



General precautions

Piping

Before installing piping to the cylinder, thoroughly flush the inside of the pipes (with compressed air). Machining chips, sealing tape, rust and other debris remaining from the piping work may result in air leaks and malfunctions.

Air supply

- 1. Use air as the medium. For the use of any other medium, consult your nearest Koganei sales office.
- 2. Air used for the cylinder should be clean air that contains no degraded compressor oil, etc. Install an air filter (filtration of 40 μ m or less) near the cylinder or valve to remove dust and accumulated liquid. Also drain the air filter periodically. If liquid or dust gets into the cylinder, it may cause defective operation.

Lubrication

The cylinder can be used without lubrication, however, if lubrication, such as a lubricator, is used, use turbine oil type 1 (ISO VG32) or an equivalent. Avoid using spindle oil or machine oil.

Environment

- 1. Cover the unit when using it in locations where it might be subject to excessive dust, dripping water, dripping oil, etc.
- 2. Do not use the cylinder in environments which may be corrosive. Using the cylinder in these types of environments may result in damage or defective operation
- 3. Do not use it in excessively dry conditions.
- 4. Do not use the cylinder if the ambient temperature is over 60°C [140°F], doing so may result in damage or defective operation. Also, consider anti-freezing measures if the temperature is less than 5°C [41°F], because moisture may freeze and result in damage or defective operation.

Handling

- 1. Do not place your hands in the way of the cylinder when it is operating.
- 2. Be careful that no part of your body is pinched between the end plate and the cylinder body when the cylinder is retracting.
- **3.** Confirm that there is no pressurized air in the cylinder before starting maintenance work.
- 4. Use the cylinder within its operating speed range. Even if the speed is within the allowable range, install an external stopper to prevent directly impacting the cylinder, if the load is large or the allowable kinetic energy is exceeded.
- 5. Use a separate cushioning device, such as a shock absorber, if noise or vibration is an issue.

Warranty and General Disclaimer

1. Warranty Period

The warranty period for Koganei products is 180 days from the date of delivery.

- 2. Scope of Warranty and General Disclaimer
- (1) The Koganei product warranty covers individual products. When a product purchased from Koganei or from an authorized Koganei distributor malfunctions during the warranty period in a way that is attributable to Koganei responsibility, Koganei will repair or replace the product free of charge. Even if a product is still within the warranty period, its durability is determined by its operation cycles and other factors. Contact your nearest Koganei sales office or the Koganei overseas department for details.
- (2) Koganei shall not be held responsible for any losses or for any damage to other machinery caused by breakdown, loss of function, or loss of performance of Koganei products
- (3) Koganei shall not be held responsible for any losses due to use or storage of the product in a way that is outside of the product specifications prescribed in Koganei catalogs and instruction manuals, and/or due to actions that violate the mounting, installation, adjustment, maintenance or other safety precautions.
- (4) Koganei shall not be held responsible for any losses caused by breakdown of the product due to factors outside the responsibility of Koganei, including but not limited to fire, natural disaster, the actions of third parties, and intentional actions or errors by you.



General precautions

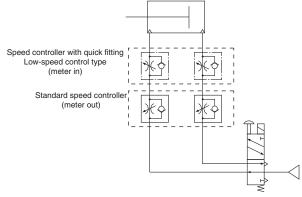
Other

The piston of the single acting type may not retract (return) even when the air is exhausted if air is continuously supplied to the piping port so that its spring is left compressed for a long period (more than 48 hours). Use a double acting cylinder if it will be left unused for long periods such as this.

About the circuit to prevent rod pop-out

Rod pop-out prevention circuit

Using the cylinder in combination with the speed controller shown in the following diagram is effective for controlling speed and preventing rod pop-out.



Note: Install the speed controller as close as possible to the cylinder.



Mounting

- 1. The cylinder can be mounted in any orientation, but the mounting surface must be flat. If the cylinder twists or bends when mounted, not only will it be inaccurate, but there may be air leaks and defective operation.
- 2. Note that a mounting surface that is scratched or dented can adversely affect flatness.
- **3.** If the cylinder is subject to large impacts, use a support structure, such as brackets, to hold the cylinder body in addition to the mounting bolts.
- Be sure that the cylinder body and the mounting bolts are of sufficient strength.
- In cases where loosening of screws due to impact and/or vibration may be a factor, consider looseness prevention measures.
- 6. Do not scratch or dent the sliding parts of the piston rod. Doing so could damage the packing and cause air leaks.
- 7. The piston rod and linear guides are coated with grease, do not wipe it off. Doing so may cause defective operation. If you cannot see the lubricant, apply some grease. The grease to be used depends on the specification. Contact Koganei for details.
- Note that you cannot use the tapped holes on the front-surface (rod side) of the cylinder if you mount it using the counterbored holes on the cylinder body.

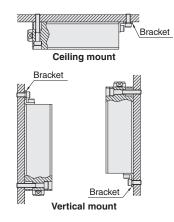
(Double acting type, single acting push type, single acting pull type, and double acting double rod end type from ϕ 10 [0.394 in] to ϕ 32 [1.260 in])

9. If you are using a combination of a cylinder and guide, use cylinder joints for flexible connections.

Mounting with brackets

We recommend using brackets for mounting if you are using the cylinder in the following conditions. (BCZ-BK \square or -BK)

- •Stroke : If using a cylinder with a longer than standard stroke.
- Mounting : If using a vertical or ceiling mount for a cylinder with a long stroke (guideline: Products with bore of φ20 [0.787 in] or greater and stroke of 50 mm [1.97 in] or longer).
- Process : If using a cylinder for large static loads, such as for pressing processes.
- Other : If using a cylinder in a location subject to extreme vibrations.



Tightening torque lists

Fittings

	N•m [in•lbf]
Thread size	Tightening torque
M3×0.5	0.7 [6.196]
M5×0.8	1.0 to 1.5 [8.851 to 13.277]
R1/8	7 to 9 [61.957 to 79.659]
R1/4	12 to 14 [106.212 to 123.914]
R3/8	22 to 24 [194.722 to 212.424]

Workpiece mounting	(Cylinder with guide)
• manpioto modining	N•m [in•lbf]

Thread size		Tightening torque
	M3×0.5	0.63 [5.576]
	M4×0.7	1.5 [13.277]
	M5×0.8	3.0 [26.553]
	M6×1	5.2 [46.025]

Plugs (Cylinder with guide)

	N•m [in•lbf]
Thread size	Tightening torque
M3×0.5	0.3 [2.655]
M5×0.8	0.4 [3.540]

Cylinder & bracket mounting

Thread size	Tightening torque		
Thread Size	Cylinder	Bracket	
M3×0.5	1.2	[10.621]	
M4×0.7	2.7	[23.898]	
M5×0.8	5.4 [47.795]		
M6×1	9.2 [81.429]		
M8×1.25	22 [194.722]		
M10×1.5	44 [389.444]		
M12×1.75	76 [672.676]		
M16×2	190 [1681.7]		
M20×2.5	370 [3274.9]		

*For both mounting to cylinder or to a mating surface.

Sensor switch mounting

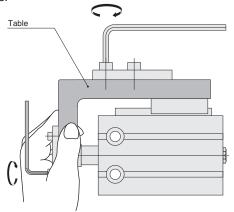
Screw tightening torque: 0.1 N•m to 0.2 N•m [0.885 in•lbf to 1.770 in•lbf]

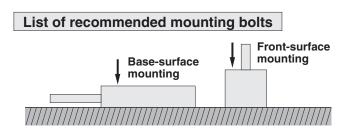
N•m [in•lbf]

Mounting workpiece to cylinder with guide

1. The table is supported by the linear guide, so be careful to avoid strong impact and excess moment when mounting workpieces.

2. Hold the table when securing the workpiece to the table with bolts. If you hold the body when tightening the bolts, it reduces the precision by applying too large moment on the guide.





Base-surface mounting

● Double acting type ● Single acting type (push, pull) ● Double rod ● With guide

	mm [in]
Cylinder bore mm [in]	Recommended mounting bolts
6 [0.236]	M3×12 [0.472]
8 [0.315]	M3×12 [0.472]
10 [0.394]	M3×16 [0.630]
12 [0.472]	M4×16 [0.630]
16 [0.630]	M4×20 [0.787]
20 [0.787]	M5×25 [0.984]
25 [0.984]	M5×30 [1.181]
32 [1.260]	M6×35 [1.378]
40 [1.575]	M8×45 [1.772]
50 [1.969]	M10×55 [2.165]
63 [2.480]	M12×65 [2.559]
80 [3.150]	M12×80 [3.150]
100 [3.937]	M16×110 [4.331]
125 [4.921]	M20×130 [5.118]

Use bolts longer than those in the table above when fastening the cylinder.

Front-surface mounting

Double acting type Single acting type	ting type (push, pull) Double rod
-------------------------------------------	-------------------------------------

Cylinder bore	Recommended mounting bolts			
mm [in]	Double acting type Single acting type		Double rod	
50 [1.969] M6×35 [1.378] + stroke		M6×55 [2.165] + stroke	M6×45 [1.772] + stroke	
63 [2.480]	M8×40 [1.575] + stroke	-	M8×50 [1.969] + stroke	
80 [3.150]	M10×45 [1.772] + stroke	-	M10×55 [2.165] + stroke	
100 [3.937]	M10×55 [2.165] + stroke	-	M10×55 [2.165] + stroke	
125 [4.921]	M12×55 [2.165] + stroke	_	M12×55 [2.165] + stroke	

Use bolts longer than those in the table above when fastening the cylinder.

Allowable kinetic energy (except cylinder with guide)

Use less kinetic energy on the cylinder than indicated in the table below.

Cylinder bore	Allowable kinetic energy J [ft-lbf]		
mm [in]	Double acting, double rod	Single acting (push & pull)	
6 [0.236]	0.008 [0.006]	0.004 [0.003]	
8 [0.315]	0.014 [0.010]	0.007 [0.005]	
10 [0.394]	0.022 [0.016]	0.012 [0.009]	
12 [0.472]	0.032 [0.024]	0.017 [0.013]	
16 [0.630]	0.057 [0.042]	0.03 [0.022]	
20 [0.787]	0.09 [0.066]	0.05 [0.037]	
25 [0.984]	0.14 [0.103]	0.08 [0.059]	
32 [1.260]	0.23 [0.170]	0.13 [0.096]	
40 [1.575]	0.36 [0.266]	0.21 [0.155]	
50 [1.969]	0.56 [0.413]	0.32 [0.236]	
63 [2.480]	0.89 [0.656]	_	
80 [3.150]	1.4 [1.033]		
100 [3.937]	2.2 [1.623]		
125 [4.921]	3.5 [2.582]	_	

Use the following equation to calculate the kinetic energy of loads.

$Ex = \frac{m}{2} v^2$	
Ex : Kinetic energy (J)	
m : Mass of load (kg) v : Piston speed (m/s)	

 $\mathsf{E}'\mathsf{x} = \frac{\mathsf{v}}{2\mathsf{g}'} v'^2$ E'x : Kinetic energy [ft-lbf] w': Load weight [lb]

w'

- v' : Piston speed [ft/sec]
- g' : Gravity acceleration 32.2 [ft/sec2]

Allowable lateral load (except cylinder with guide)

Apply less than the maximum lateral load to the cylinder than indicated in the table below.

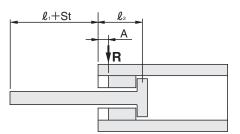
Equation

E

- φ6 [0.236] to φ12 [0.472], φ50 [1.969] to φ125 [4.9] Maximum allowable lateral load $W \leq \frac{\ell_2 - A}{\ell_1 + \ell_2 + St} \cdot R$
- φ16 [0.630] to φ40 [1.575]

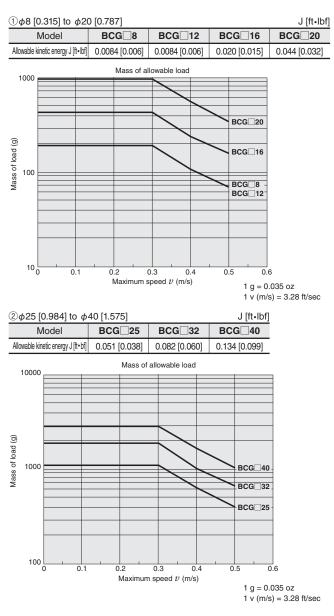
Maximum allowable lateral load
$$W \leq -$$

l 2 $\ell_{1+\ell_{2}+St}$ •R



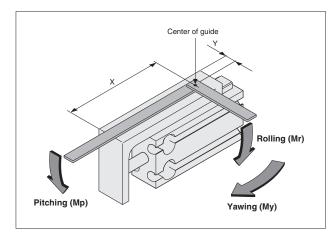
Cylinder	Allowable	l 1	l 2	А
bore	lateral load R	mm [in]	mm [in]	mm [in]
mm [in]	N [lbf]		[]	[]
6 [0.236]	1.0 [0.225]	4.0 [0.157]	13.8 [0.543]	3.8 [0.150]
8 [0.315]	1.8 [0.405]	4.0 [0.157]	14.3 [0.563]	4.3 [0.169]
10 [0.394]	2.7 [0.607]	4.0 [0.157]	14.4 [0.567]	4.3 [0.169]
12 [0.472]	4.0 [0.899]	5.0 [0.197]	14.0 [0.551]	3.5 [0.138]
16 [0.630]	7.0 [1.574]	5.0 [0.197]	15.0 [0.591]	-
20 [0.787]	11.0 [2.473]	6.0 [0.236]	17.5 [0.689]	-
25 [0.984]	17.2 [3.867]	6.0 [0.236]	18.0 [0.709]	-
32 [1.260]	28.1 [6.317]	7.0 [0.276]	18.5 [0.728]	-
40 [1.575]	44.0 [9.892]	7.0 [0.276]	23.0 [0.906]	-
50 [1.969]	68.7 [15.444]	8.0 [0.315]	27.3 [1.075]	8.0 [0.315]
63 [2.480]	109.1 [24.5]	8.0 [0.315]	33.0 [1.299]	8.0 [0.315]
80 [3.150]	175.9 [39.5]	10.0 [0.394]	32.5 [1.280]	8.0 [0.315]
100 [3.937]	274.9 [61.8]	12.0 [0.472]	44.5 [1.752]	9.0 [0.354]
125 [4.921]	429.5 [96.6]	16.0 [0.630]	50.0 [1.969]	9.0 [0.354]

Cylinder with guide, allowable kinetic energy



Allowable bending moment for cylinder with guide

Applying more than the allowable bending moment causes the guide to rattle, reduces precision, and has a bad effect on operating life.



 Use the center of the guide as shown in the diagram as the reference for the center of moment.

Dimension	ions of cer	nter of guide	mm [in]				mm [in]
Model	Stroke	Х	Y	Model	Stroke	Х	Y
	5	31.5			5	47.5	
	10	[1.240]			10	[1.870]	
	15	41.5			15	57.5	
	20	[1.634]			20	[2.264]	
	25	51.5			25	67.5	
	30	[2.028]	6		30	[2.657]	14.5
BCG 8	35	61.5	[0.236]	BCG 25	35	77.5	[0.571]
	40	[2.421]	[]		40	[3.051]	[]
	45	71.5			45	87.5	
	50	[2.815]			50	[3.445]	
	55	81.5			55	97.5	
	60	[3.209]			60	[3.839]	
	5	32.5	5		10	57	
	10	[1.280]			10	[2.244]	
	15	42.5			15	67	
	20	[1.673]			20	[2.638]	
	25	52.5			25	77	
D00 10	30	[2.067]	7.5	BCG_32	30	[3.031]	18
BCG[12	35	62.5	[0.295]	BCG_32	35	87	[0.709]
	40	[2.461]			40	[3.425]	
	45	72.5			45	97	
	50	[2.854]			50	[3.819]	
	55	82.5			55	107	
	60	[3.248]			60	[4.213]	
	5	37.5			10	70.5	
	10	[1.476]			15	[2.776]	
	15	47.5			20	[2.770]	
	20	[1.870]			25	80.5	
	25	57.5		ļ	30	[3.169]	23
BCG[16	30	[2.264]	9.5	BCG_40	35	90.5	[0.906]
bealin	35	67.5	[0.374]		40	[3.563]	[0.900]
	40	[2.657]			45	100.5	
	45	77.5			50	[3.957]	
	50	[3.051]			55	110.5	
	55	87.5			60	[4.350]	
	60	[3.445]					
	5	44					
	10	[1.732]					
	15	54					
	20	[2.126]					
	25	64					
BCG 20	30	[2.520]	11.5				
	35	74	[0.453]				
	40	[2.913]					
	45	84					
	50	[3.307]					
	55	94					
	60	[3.701]					

Allowable	bending mor	nent	N∙m [in•lbf]								
Model	Model Mp (pitching) Mr (rolling)										
BCG 8, BCG 12	0.21 [1.859]										
BCG_16 0.4 [3.540] 0.4 [3.540] 0.68 [6.01											
BCG 20	BCG 20 1.5 [13.277] 1.8 [15.932]										
BCG 25	2.18 [19.295]	2.18 [19.295]	4.18 [36.997]								
BCG 32	4.46 [39.475]	4.46 [39.475]	7.31 [64.701]								
BCG 40	6.7 [59.302]	8 [70.808]	13.7 [121.259]								
Heat resistant specification N·m [in-lbi											

Model	Mp (pitching)	Mr (rolling)	My (yawing)
BCGF8, BCGF12	0.11 [0.974]	0.11 [0.974]	0.18 [1.593]
BCGF16	0.35 [3.098]	0.35 [3.098]	0.60 [5.311]
BCGF20	0.88 [7.789]	0.88 [7.789]	1.25 [11.064]
BCGF25	1.37 [12.126]	1.21 [10.710]	2.30 [20.357]
BCGF32	3.56 [31.510]	2.99 [26.464]	6.00 [53.106]
BCGF40	6.32 [55.938]	5.30 [46.910]	11.04 [97.715]

Displacement of table due to bending moment for cylinder with guide (reference values) For heat resistant specification graphs, refer to page ().

Pitching (Mp)

Displacement of edge of table (arrow) when load W is applied at arrow

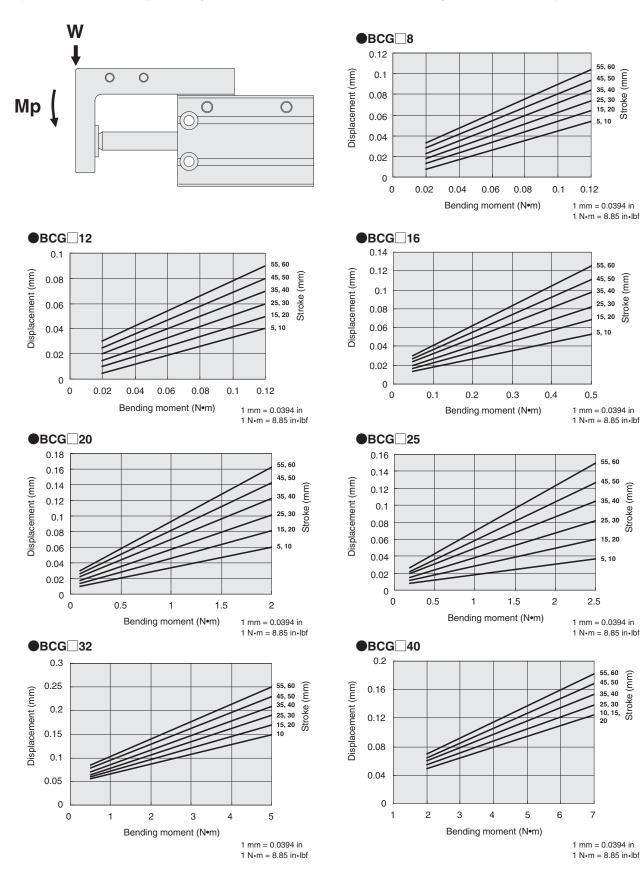
(Precaution: There may be a large increase in the displacement after a large impact load is applied to the table)

(mm)

(mm)

Stroke

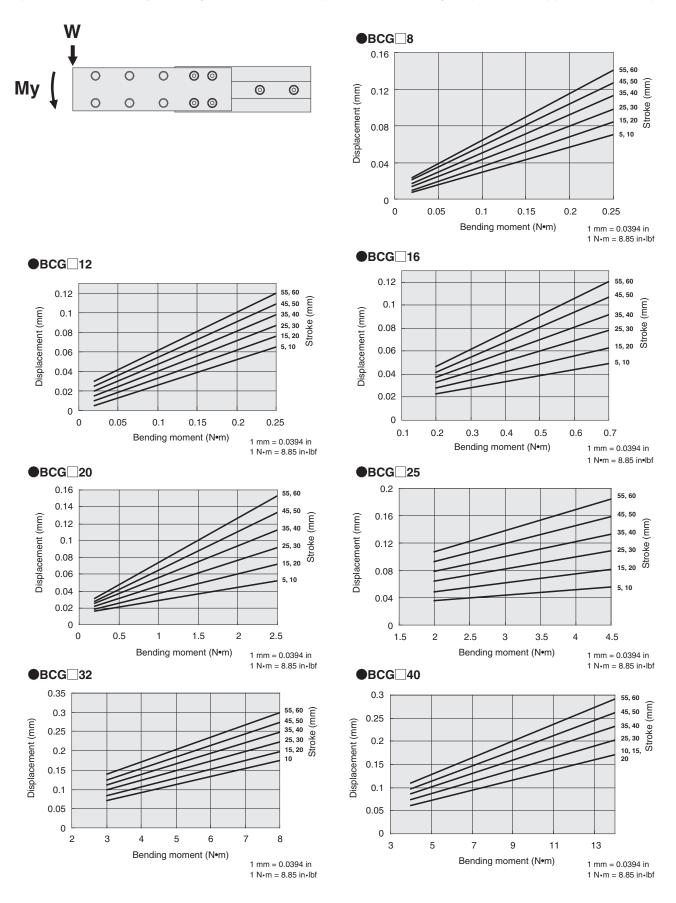
Stroke (mm)



Displacement of table due to bending moment for cylinder with guide (reference values) For heat resistant specification graphs, refer to page (9).

• Yawing (My)

Displacement of edge of table (arrow) when load W is applied at arrow

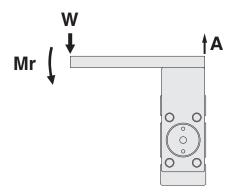


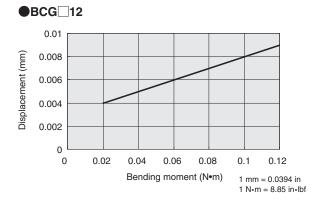
Displacement of table due to bending moment for cylinder with guide (reference values) For heat resistant specification graphs, refer to page @.

Rolling (Mr)

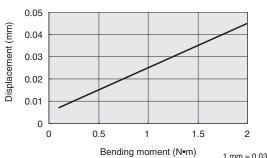
Displacement of edge of table (arrow A) when load W is applied at arrow

(Precaution: There may be a large increase in the displacement after a large impact load is applied to the table)



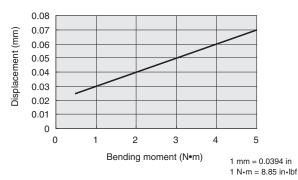


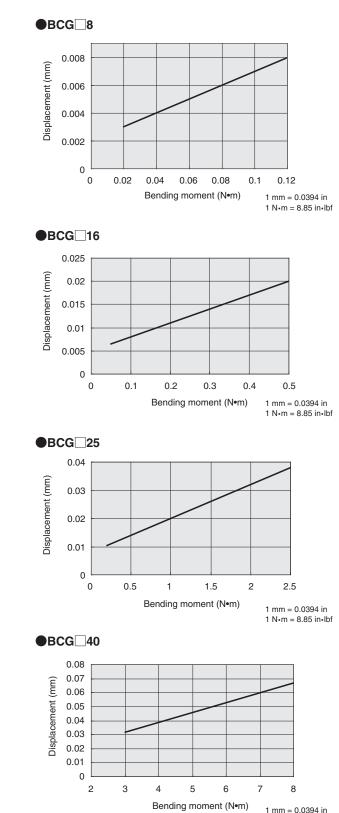
●BCG□20



1 mm = 0.0394 in 1 N•m = 8.85 in•lbf





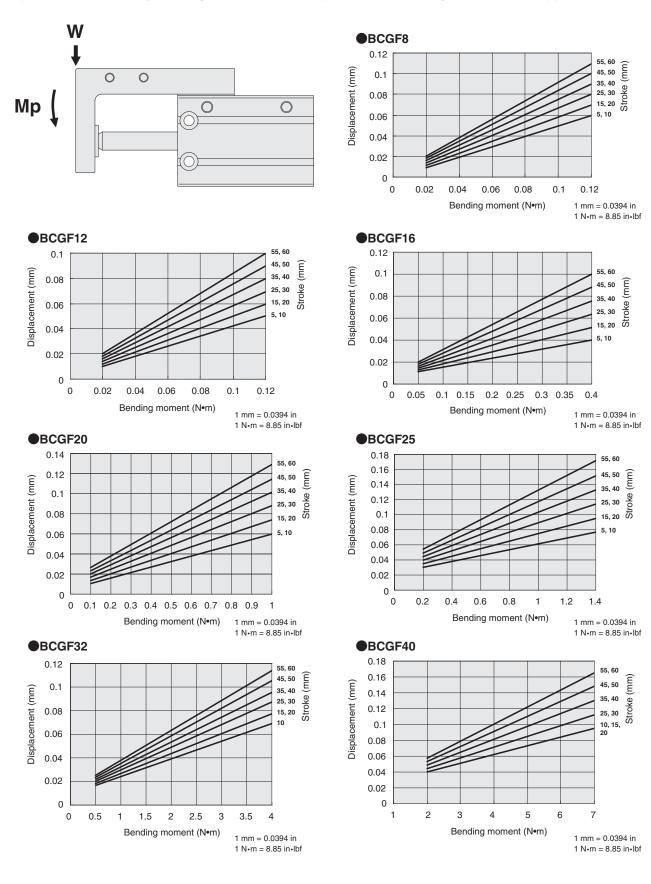


1 N•m = 8.85 in•lbf

Displacement of table due to bending moment for heat resistant specification cylinder with guide (reference values)

Pitching (Mp)

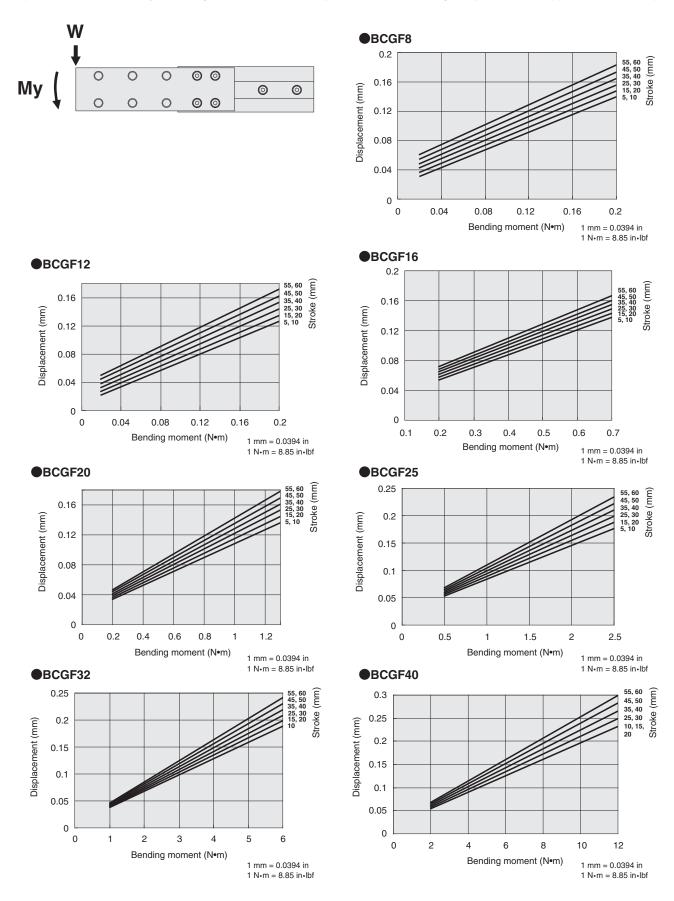
Displacement of edge of table (arrow) when load W is applied at arrow



Displacement of table due to bending moment for heat resistant specification cylinder with guide (reference values)

• Yawing (My)

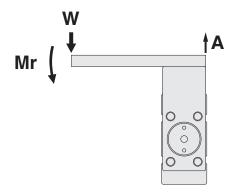
Displacement of edge of table (arrow) when load W is applied at arrow

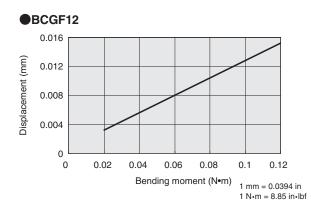


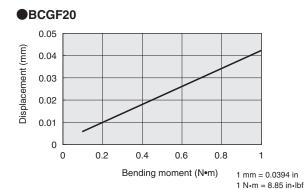
Displacement of table due to bending moment for heat resistant specification cylinder with guide (reference values)

Rolling (Mr)

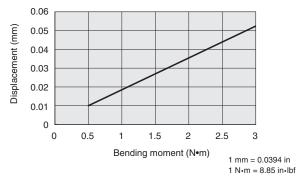
Displacement of edge of table (arrow A) when load W is applied at arrow

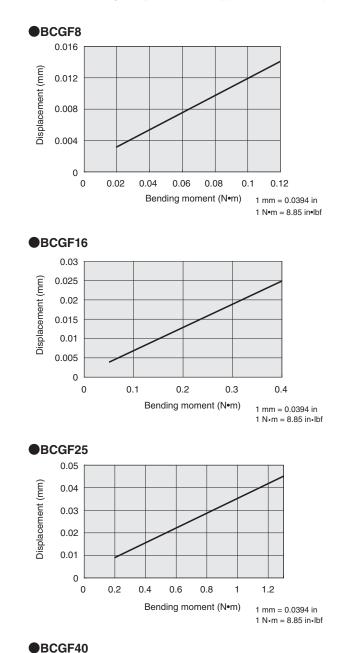


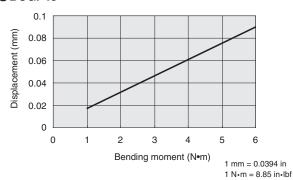












Thrust

Double acting type

Cylinder bore	Piston rod diameter	o	Pressure area			A	ir pressure MF	Pa		
mm	mm	Operation	mm ²	0.1	0.2	0.3	0.4	0.5	0.6	0.7
6		Push side	28.3	2.8	5.7	8.5	11.3	14.2	17.0	19.8
6	4	Pull side	15.7	1.6	3.1	4.7	6.3	7.9	9.4	11.0
•		Push side	50.3	5.0	10.1	15.1	20.1	25.2	30.2	35.2
8	5	Pull side	30.6	3.1	6.1	9.2	12.2	15.3	18.4	21.4
10	-	Push side	78.5	7.9	15.7	23.6	31.4	39.3	47.1	55.0
10	5	Pull side	58.9	5.9	11.8	17.7	23.6	29.5	35.3	41.2
12	c	Push side	113.0	11.3	22.6	33.9	45.2	56.5	67.8	79.1
12	6	Pull side	84.8	8.5	17.0	25.4	33.9	42.4	50.9	59.4
10		Push side	201.0	20.1	40.2	60.3	80.4	100.5	120.6	140.7
16	8	Pull side	150.0	15.0	30.0	45.0	60.0	75.0	90.0	105.0
20	10	Push side	314.0	31.4	62.8	94.2	125.6	157.0	188.4	219.8
20	10	Pull side	235.5	23.6	47.1	70.7	94.2	117.8	141.3	164.9
25	10	Push side	490.6	49.1	98.1	147.2	196.2	245.3	294.4	343.4
25	12	Pull side	377.6	37.8	75.5	113.3	151.0	188.8	226.6	264.3
32	16	Push side	803.8	80.4	160.8	241.1	321.5	401.9	482.3	562.7
32	10	Pull side	602.9	60.3	120.6	180.9	241.2	301.5	361.7	422.0
40	16	Push side	1256.0	125.6	251.2	376.8	502.4	628.0	753.6	879.2
40	10	Pull side	1055.0	105.5	211.0	316.5	422.0	527.5	633.0	738.5
50	20	Push side	1962.5	196.3	392.5	588.8	785.0	981.3	1177.5	1373.8
50	20	Pull side	1648.5	164.9	329.7	494.6	659.4	824.3	989.1	1154.0
63	20	Push side	3115.7	311.6	623.1	934.7	1246.3	1557.9	1869.4	2181.0
03	20	Pull side	2801.7	280.2	560.3	840.5	1120.7	1400.9	1681.0	1961.2
80	25	Push side	5024.0	502.4	1004.8	1507.2	2009.6	2512.0	3014.4	3516.8
00	20	Pull side	4533.4	453.3	906.7	1360.0	1813.4	2266.7	2720.0	3173.4
100	20	Push side	7850.0	785.0	1570.0	2355.0	3140.0	3925.0	4710.0	5495.0
100	30	Pull side	7143.5	714.4	1428.7	2143.1	2857.4	3571.8	4286.1	5000.5
125	25	Push side	12265.6	1226.6	2453.1	3679.7	4906.3	6132.8	7359.4	8585.9
120	35	Pull side	11304.0	1130.4	2260.8	3391.2	4521.6	5652.0	6782.4	7912.8

unit: N

• Single acting type

Operating	Cylinder bore	Piston rod diameter	Pressure area			Air press	sure MPa			Spring return force
type	mm	mm	mm ²	0.2	0.3	0.4	0.5	0.6	0.7	(at end of stroke)
	6	4	28.3	2.5	5.3	8.1	11.0	13.8	16.6	3.16
Γ	8	5	50.3	3.6	8.6	13.6	18.7	23.7	28.7	6.5
	10	5	78.5	8.5	16.4	24.2	32.1	39.9	47.8	7.17
0	12	6	113.0	12.7	24.0	35.3	46.6	57.9	69.2	9.9
Single acting	16	8	201.0	23.8	43.9	64.0	84.1	104.2	124.3	16.4
ush type -	20	10	314.0	46.4	77.8	109.2	140.6	172.0	203.4	16.4
push type	25	12	490.6	77.8	126.9	175.9	225.0	274.1	323.1	20.3
	32	16	803.8	127.8	208.1	288.5	368.9	449.3	529.7	33
	40	16	1256.0	211.7	337.3	462.9	588.5	714.1	839.7	39.5
	50	20	1962.5	338.8	535.1	731.3	927.6	1123.8	1320.1	53.7
	6	4	15.7	-	1.3	2.8	4.4	6.0	7.5	3.45
	8	5	30.6	—	2.0	5.1	8.1	11.2	14.3	7.17
	10	5	58.9	4.6	10.5	16.4	22.3	35.3	34.2	7.17
	12	6	84.8	7.1	15.5	24.0	32.5	41.0	49.5	9.9
Single acting	16	8	150.0	13.6	28.6	43.6	58.6	73.6	88.6	16.4
-	20	10	235.5	30.7	54.3	77.8	101.4	124.9	148.5	16.4
pull type	25	12	377.6	55.2	93.0	130.7	168.5	206.3	244.0	20.3
	32	16	602.9	87.6	147.9	208.2	268.5	328.7	389.0	33
	40	16	1055.0	171.5	277.0	382.5	488.0	593.5	699.0	39.5
	50	20	1648.5	276.0	440.9	605.7	770.6	935.4	1100.3	53.7

Double acting type

Cylinder bore	Piston rod diameter	0	Pressure area				Air pressure p	si		
in	in	Operation	in ²	15	29	44	58	73	87	102
0.236	0.157	Push side	0.044	0.629	1.281	1.911	2.540	3.192	3.822	4.451
0.230	0.157	Pull side	0.024	0.360	0.697	1.057	1.416	1.776	2.113	2.473
0.315	0.197	Push side	0.078	1.124	2.271	3.395	4.519	5.665	6.789	7.913
0.315	0.197	Pull side	0.047	0.697	1.371	2.068	2.743	3.440	4.136	4.811
0.394	0.197	Push side	0.122	1.776	3.530	5.305	7.059	8.835	10.589	12.364
0.394	0.197	Pull side	0.091	1.326	2.653	3.979	5.305	6.632	7.936	9.262
0.472	0.236	Push side	0.2	2.540	5.081	7.621	10.161	12.702	15.242	17.782
0.472	0.230	Pull side	0.131	1.911	3.822	5.710	7.621	9.532	11.443	13.354
0.630	0.315	Push side	0.3	4.519	9.037	13.556	18.075	22.6	27.1	31.6
0.030	0.315	Pull side	0.2	3.372	6.744	10.116	13.489	16.861	20.233	23.6
0.787	0.394	Push side	0.5	7.059	14.118	21.177	28.2	35.3	42.4	49.4
0.707	0.394	Pull side	0.4	5.305	10.589	15.894	21.177	26.5	31.8	37.1
0.984	0.472	Push side	0.8	11.038	22.054	33.1	44.1	55.1	66.2	77.2
0.904	0.472	Pull side	0.6	8.498	16.973	25.5	33.9	42.4	50.9	59.4
1.260	0.630	Push side	1.2	18.075	36.1	54.2	72.3	90.4	108.4	126.5
1.200	0.030	Pull side	0.9	13.556	27.1	40.7	54.2	67.8	81.3	94.9
1.575	0.630	Push side	2	28.2	56.5	84.7	112.9	141.2	169.4	197.7
1.575	0.630	Pull side	2	23.7	47.4	71.2	94.9	118.6	142.3	166.0
1.969	0.787	Push side	3	44.1	88.2	132.4	176.5	220.6	265	309
1.909	0.787	Pull side	3	37.1	74.1	111.2	148.2	185.3	222.4	259
2.480	0.787	Push side	5	70.1	140.1	210.1	280	350	420	490
2.400	0.787	Pull side	4	63.0	126.0	189.0	252	315	378	441
3.150	0.984	Push side	8	112.9	226	339	452	565	678	791
3.150	0.904	Pull side	7	101.9	203.8	306	408	510	611	713
3.9	1.181	Push side	12	176.5	353	529	706	882	1059	1235
3.3	1.101	Pull side	11	160.6	321	482	642	803	964	1124
4.9	1.378	Push side	19	276	551	827	1103	1379	1654	1930
4.5	1.570	Pull side	18	254	508	762	1016	1271	1525	1779

• Single acting type

	e acting type		-			Air proc	sure psi			unit
Operating type	Cylinder bore in	Piston rod diameter in	Pressure area in ²	29	44	58	73	87	102	Spring return force (at end of stroke)
	0.236	0.157	0.044	0.562	1.191	1.821	2.473	3.102	3.732	0.710
Ī	0.315	0.197	0.078	0.809	1.933	3.057	4.204	5.328	6.452	1.461
	0.394	0.197	0.122	1.911	3.687	5.440	7.216	8.970	10.746	1.612
[0.472	0.236	0.2	2.855	5.395	7.936	10.476	13.016	15.557	2.226
Single	0.630	0.315	0.3	5.350	9.869	14.388	18.906	23.4	27.9	3.687
acting ush type	0.787	0.394	0.5	10.431	17.490	24.5	31.6	38.7	45.7	3.687
	0.984	0.472	0.8	17.490	28.5	39.5	50.6	61.6	72.6	4.564
	1.260	0.630	1.2	28.7	46.8	64.9	82.9	101.0	119.1	7.419
	1.575	0.630	2	47.6	75.8	104.1	132.3	160.5	188.8	8.880
Γ	1.969	0.787	3	76.2	120.3	164.4	208.5	253	297	12.072
	0.236	0.157	0.024	-	0.292	0.629	0.989	1.349	1.686	0.776
ſ	0.315	0.197	0.047	-	0.450	1.147	1.821	2.518	3.215	1.612
[0.394	0.197	0.091	1.034	2.360	3.687	5.013	7.936	7.688	1.612
[0.472	0.236	0.131	1.596	3.485	5.395	7.306	9.217	11.128	2.226
Single	0.630	0.315	0.2	3.057	6.430	9.802	13.174	16.546	19.918	3.687
acting	0.787	0.394	0.4	6.902	12.207	17.490	22.8	28.1	33.4	3.687
pull type	0.984	0.472	0.6	12.409	20.907	29.4	37.9	46.4	54.9	4.564
	1.260	0.630	0.9	19.693	33.2	46.8	60.4	73.9	87.5	7.419
	1.575	0.630	2	38.6	62.3	86.0	109.7	133.4	157.1	8.880
l l	1.969	0.787	3	62.0	99.1	136.2	173.2	210.3	247	12.072

Basic Cylinders

Cylinder with guide

Symbol





Specifications (standard, corrosion resistant, heat resistant specifications)

Item	Cylinder bore	8 [0.315]	12 [0.472]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]	40 [1.575]				
Operating type					Double acting type	9						
Medium					Air							
Operating	Standard, corrosion resistant specifications	0.2 to 0.7 [29 to 102]	0.1 to 0.7	[15 to 102]		0.08 to 0.7	[12 to 102]					
pressure range MPa [psi]	Heat resistant specification	[22 to 102]										
Proof pressure	MPa [psi]		1.05 [152]									
Operating temperatur	re range °C [°F]		0 to 60 [32 to 140] (0 to 150 [32 to 302] for heat resistant specification ^{Note})									
Operating speed rang	ge mm/s [in/sec]		50 to 500 [1.	969 to 19.7] (100 t	o 300 [3.9 to 11.8]] for heat resistant	specification)					
Cushion			Rubber bumper									
Lubrication		Not required										
Port size		M3×0.5	<0.5 M5×0.8 Rc1/8									
Running parallelisn	n mm [in]				0.1 [0.004] or less	3						
Allowable moment	Pitching	0.12 [1.062]	(0.11 [0.974])	0.40 [3.540]	1.50 [13.277]	2.18 [19.295]	4.46 [39.475]	6.70 [59.302]				
N•m [in•lbf]				(0.35 [3.098])	(0.88 [7.789])	(1.37 [12.126])	(3.56 [31.510])	(6.32 [55.938])				
Values in	Rolling	0.12 [1.062]	(0.11 [0.974])	0.40 [3.540]	1.80 [15.932]	2.18 [19.295]	4.46 [39.475]	8.00 [70.808]				
parentheses are				(0.35 [3.098])	(0.88 [7.789])	(1.21 [10.710])	(2.99 [26.464])	(5.30 [46.910])				
for heat resistant	Yawing	0.21 [1.859]	(0.18 [1.593])	0.68 [6.019]	2.20 [19.472]	4.18 [36.997]	7.31 [64.701]	13.70 [121.259]				
specification.				(0.60 [5.311])	(1.25 [11.064])	(2.30 [20.357])	(6.00 [53.106])	(11.04 [97.715])				

Note: Heat resistant specification is without sensor switch.

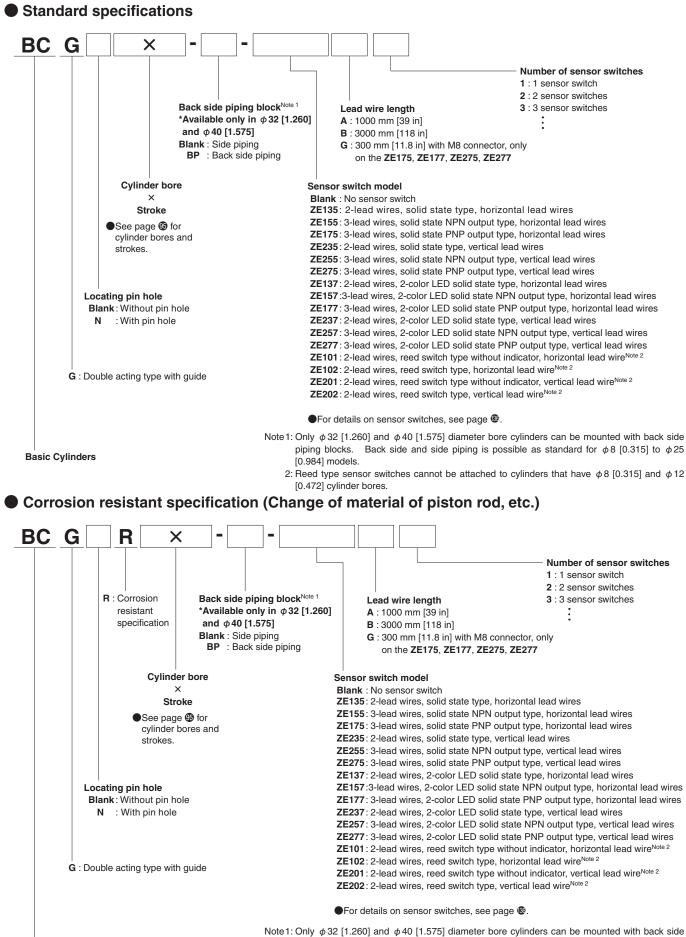
Linear guide being used

			mm [in]	
Culinder bere	Rail width	Manuf	acturer	
Cylinder bore	Hall Width	Standard, corrosion resistant specifications	Heat resistant specification	
φ 8 [0.315], φ 12 [0.472]	5 [0.197]			
φ 16 [0.630]	7 [0.276]		тнк	
φ 20 [0.787]	9 [0.354]	тнк	IUL	
φ 25 [0.984]	12 [0.472]			
φ 32 [1.260]	15 [0.591]		IKO	
φ 40 [1.575]	20 [0.787]		IKO	

Cylinder bore and stroke

	mm [in]
Cylinder bore	Standard stroke
8, 12, 16, 20, 25 [0.315, 0.472, 0.630, 0.787, 0.984]	5 ^{Note} , 10, 15 ^{Note} , 20, 25 ^{Note} , 30, 35 ^{Note} , 40, 45 ^{Note} , 50, 55 ^{Note} , 60
32 [1.260]	10, 15 ^{Note} , 20, 25 ^{Note} , 30, 35 ^{Note} , 40, 45 ^{Note} , 50, 55 ^{Note} , 60
40 [1.575]	10 ^{Note} , 15 ^{Note} , 20, 25 ^{Note} , 30, 35 ^{Note} , 40, 45 ^{Note} , 50, 55 ^{Note} , 60

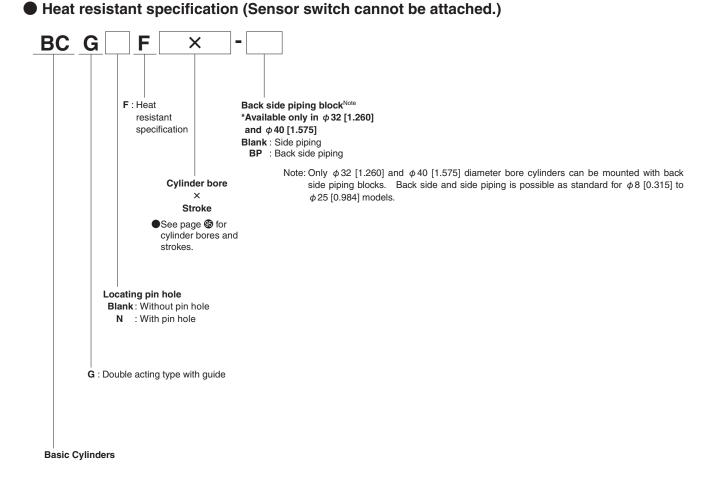
Note: Collar stopper is used in this stroke.





Note 1: Only ϕ 32 [1.260] and ϕ 40 [1.575] diameter bore cylinders can be mounted with back side piping blocks. Back side and side piping is possible as standard for ϕ 8 [0.315] to ϕ 25 [0.984] models.

2: Reed type sensor switches cannot be attached to cylinders that have $\phi 8$ [0.315] and $\phi 12$ [0.472] cylinder bores.



Mass

Cylind	Cylinder with guide											unit: g
Model		Stroke mm [in]										
Model	5 [0.197]	10 [0.394]	15 [0.591]	20 [0.787]	25 [0.984]	30 [1.181]	35 [1.378]	40 [1.575]	45 [1.772]	50 [1.969]	55 [2.165]	60 [2.362]
BCG 8	56	54	68	66	80	78	92	90	104	102	116	114
BCG 12	82	81	96	95	110	109	124	123	138	137	152	151
BCG 16	133	131	155	153	178	176	200	198	222	220	245	243
BCG 20	207 (209)	205 (207)	236 (238)	234 (236)	265 (267)	263 (265)	294 (296)	292 (294)	323 (325)	321 (323)	352 (354)	350 (352)
BCG 25	321 (330)	317 (326)	366 (375)	362 (371)	411 (420)	407 (416)	456 (465)	452 (461)	501 (510)	497 (506)	546 (555)	542 (551)
BCG 32	-	597 (627)	675 (705)	669 (699)	746 (776)	740 (770)	818 (848)	812 (842)	889 (919)	883 (913)	961 (991)	955 (985)
BCG 40	-	1031 (1075)	1025 (1069)	1019 (1063)	1122 (1166)	1116 (1160)	1219 (1263)	1213 (1257)	1316 (1360)	1310 (1354)	1413 (1457)	1407 (1451)

Values in parentheses are mass of heat resistant specification.

In the case of back side piping specifications, mass is 76 g for a ϕ 32 cylinder bore and 108 g for a ϕ 40 cylinder bore.

												unit: oz
Model		Stroke mm [in]										
Model	5 [0.197]	0.197] 10 [0.394] 15 [0.591] 20 [0.787] 25 [0.984] 30 [1.181] 35 [1.378] 40 [1.575] 45 [1.772] 50 [1.969] 55 [2.165] 60 [2.362]										
BCG 8	1.975	1.905	2.399	2.328	2.822	2.751	3.245	3.175	3.7	3.6	4.1	4.0
BCG 12	2.892	2.857	3.386	3.351	3.9	3.8	4.4	4.3	4.9	4.8	5.4	5.3
BCG 16	4.7	4.6	5.5	5.4	6.3	6.2	7.1	7.0	7.8	7.8	8.6	8.6
BCG 20	7.3 (7.4)	7.2 (7.3)	8.3 (8.4)	8.3 (8.3)	9.3 (9.4)	9.3 (9.3)	10.4 (10.4)	10.3 (10.4)	11.4 (11.5)	11.3 (11.4)	12.4 (12.5)	12.3 (12.4)
BCG 25	11.3 (11.6)	11.2 (11.5)	12.9 (13.2)	12.8 (13.1)	14.5 (14.8)	14.4 (14.7)	16.1 (16.4)	15.9 (16.3)	17.7 (18.0)	17.5 (17.8)	19.3 (19.6)	19.1 (19.4)
BCG 32	—	21.1 (22.1)	23.8 (24.9)	23.6 (24.7)	26.3 (27.4)	26.1 (27.2)	28.9 (29.9)	28.6 (29.7)	31.4 (32.4)	31.1 (32.2)	33.9 (35.0)	33.7 (34.7)
BCG 40	—	36 (38)	36 (38)	36 (37)	40 (41)	39 (41)	43 (45)	43 (44)	46 (48)	46 (48)	50 (51)	50 (51)

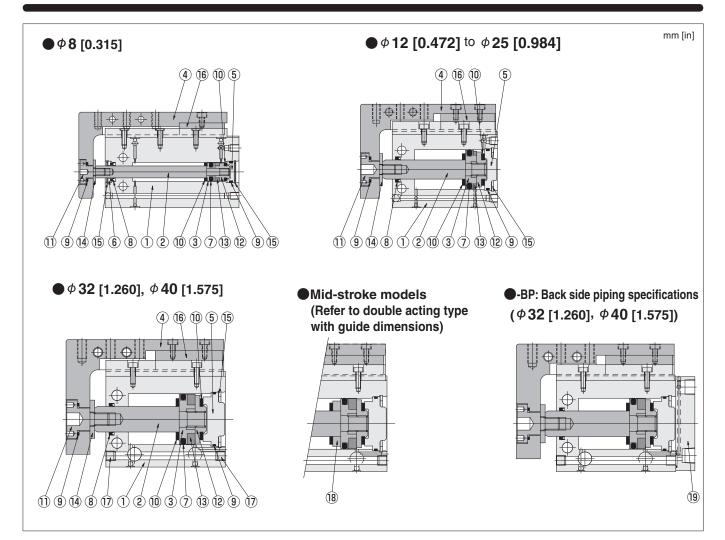
Values in parentheses are mass of heat resistant specification.

In the case of back side piping specifications, mass is 2.681 oz for a ϕ 1.260 cylinder bore and 3.8 oz for a ϕ 1.575 cylinder bore.

Additional mass of sensor switches

ZE A, **ZE G**: 15 g [0.529 oz] **ZE B**: 35 g [1.235 oz]

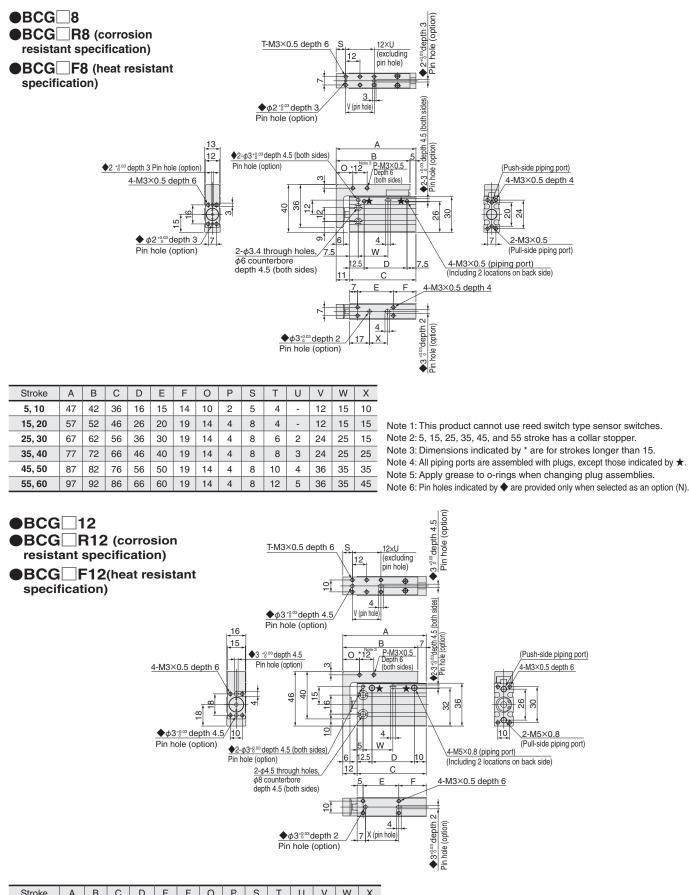
Inner construction



Major parts and materials (standard, corrosion resistant, heat resistant specifications)

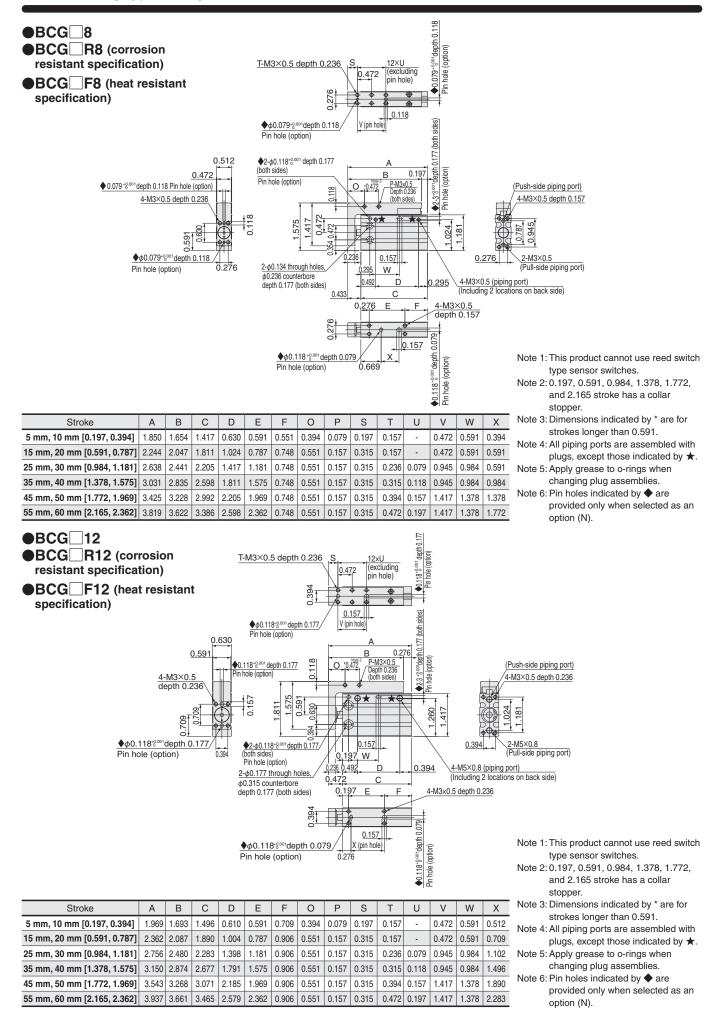
No.	Name	φ8 [0.315]	φ12 [0.472]	φ 16 [0.630]	φ 20 [0.787]	φ 25 [0.984]	φ 32 [1.260]	φ 40 [1.575]						
1	Cylinder body				oy (special anti-abr	asion treated)		, , , ,						
2	Piston rod			Stainless steel				osion and heat resis- are stainless steel.)						
3	Piston	Stainles	ss steel		Alu	ninum alloy (anodi	zed)							
4	Table			Alu	minum alloy (anodi:	zed)								
5	Head cover			Alu	minum alloy (anodi:	zed)								
6	Seal holder	Aluminum alloy (Anodized)	_	_	—	_	—	_						
7	★ Piston seal		Synthetic rubber (NBR) (heat resistant specification: FKM)											
8	★ Rod seal		Synthetic rubber (NBR) (heat resistant specification: FKM)											
9	★ O-ring		:	Synthetic rubber (N	BR) (heat resistant	specification: FKM)							
10	Bumper		:	Synthetic rubber (N	BR) (heat resistant	specification: FKM)							
(1)	End bolt				Stainless steel									
(12)	Support			Alu	minum alloy (anodi	zed)								
(13)	Magnet		Neodymium mag	gnet (no heat resist	ant specification)			no heat resistant cation)						
(14)	Bolt retainer				Stainless steel									
(15)	★ Retaining ring	Stainless steel	S	teel (Corrosion and	I heat resistant spe	cifications are elec	troless nickel plated	d.)						
(16)	Linear guide				Stainless steel									
(17)	Plug	—	_	-	—	—	Stainless steel	Stainless steel						
(18)	Stopper			Alu	minum alloy (anodiz	zed)								
(19)	★ Back side piping block	_	Aluminum alloy Aluminum alloy (Anodized) (Anodized)											

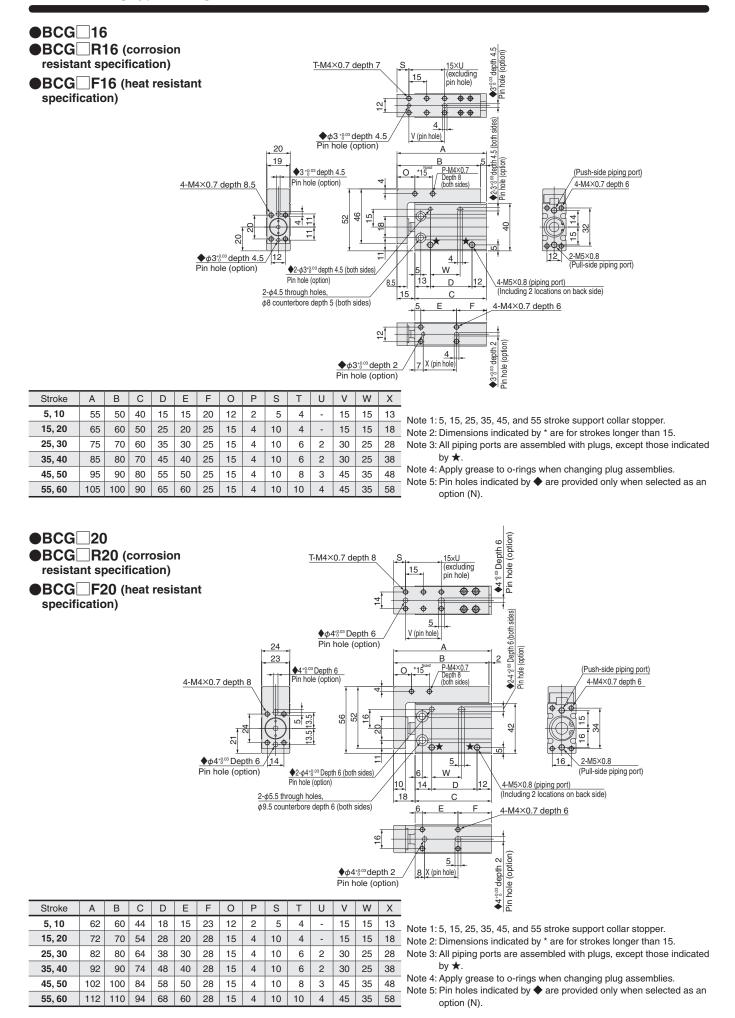
Items indicated by a 🖈 are available as additional parts or in packing sets. For order codes, see page 🕲 and 🕲.

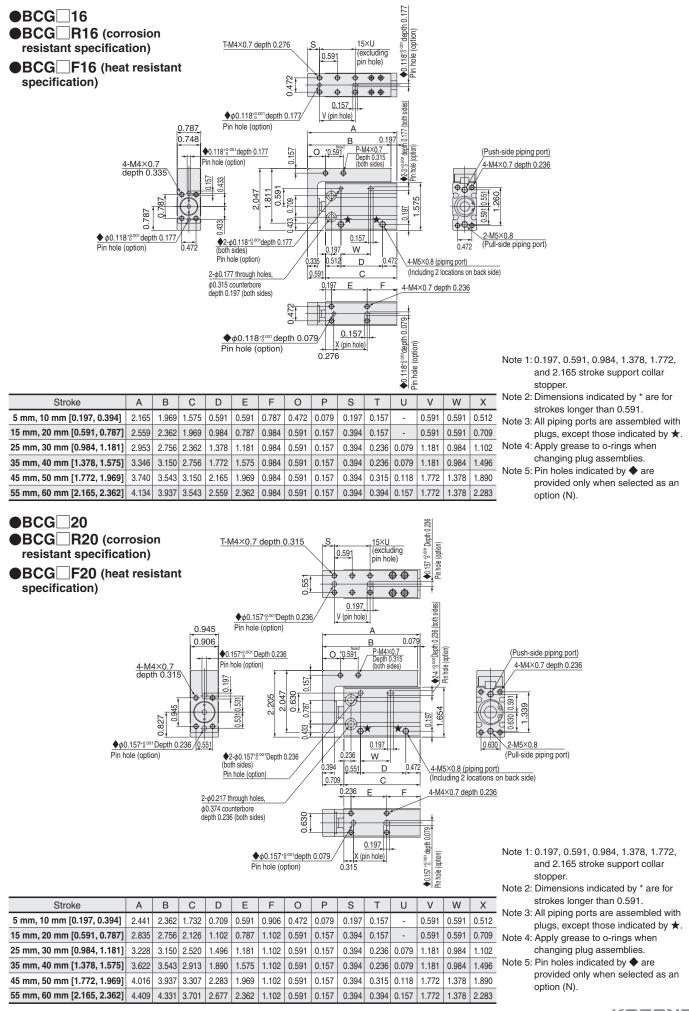


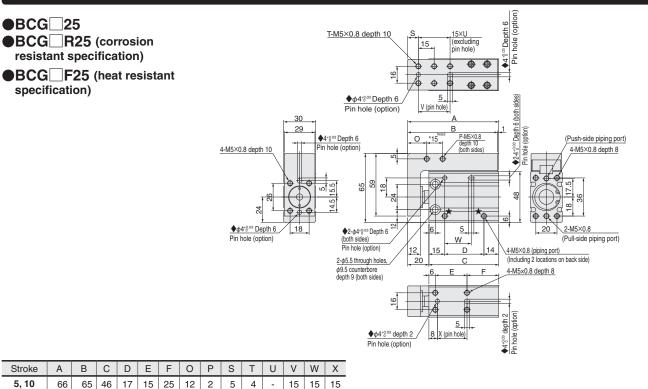
Stroke	А	В	С	D	Е	F	0	Р	S	Т	U	V	W	Х	
5, 10	50	43	38	15.5	15	18	10	2	5	4	-	12	15	13	
15, 20	60	53	48	25.5	20	23	14	4	8	4	-	12	15	18	
25, 30	70	63	58	35.5	30	23	14	4	8	6	2	24	25	28	
35, 40	80	73	68	45.5	40	23	14	4	8	8	3	24	25	38	
45, 50	90	83	78	55.5	50	23	14	4	8	10	4	36	35	48	
55, 60	100	93	88	65.5	60	23	14	4	8	12	5	36	35	58	

Note 1: This product cannot use reed switch type sensor switches. Note 2: 5, 15, 25, 35, 45, and 55 stroke has a collar stopper. Note 3: Dimensions indicated by * are for strokes longer than 15. Note 4: All piping ports are assembled with plugs, except those indicated by ★. Note 5: Apply grease to o-rings when changing plug assemblies. Note 6: Pin holes indicated by ♦ are provided only when selected as an option (N).









1	Stroke	A	D	U			Г	0	Р	5	1	0	V	vv	_ ^
	5, 10	66	65	46	17	15	25	12	2	5	4	-	15	15	15
	15, 20	76	75	56	27	20	30	18	4	10	4	-	15	15	18
	25, 30	86	85	66	37	30	30	18	4	10	6	2	30	25	28
	35, 40	96	95	76	47	40	30	18	4	10	6	2	30	25	38
	45, 50	106	105	86	57	50	30	18	4	10	8	3	45	35	48
	55, 60	116	115	96	67	60	30	18	4	10	10	4	45	35	58

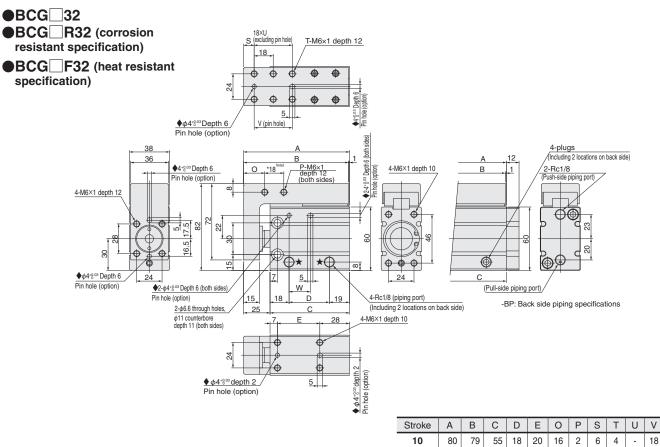
Note 1:5, 15, 25, 35, 45, and 55 stroke support collar stopper.

Note 2: Dimensions indicated by * are for strokes longer than 15.

Note 3: All piping ports are assembled with plugs, except those indicated by \bigstar .

Note 4: Apply grease to o-rings when changing plug assemblies.

Note 5: Pin holes indicated by \blacklozenge are provided only when selected as an option (N).



Note 1: 15, 25, 35, 45, and 55 stroke support collar stopper.

Note 2: Dimensions indicated by * are for strokes longer than 25.

Note 3: All piping ports are assembled with plugs, except those indicated by ★. However, in the case of the corrosion resistant specification, plugs are included for specifications other than back side piping specifications. Assemble using sealant, etc.

Note 4: Pin holes indicated by \blacklozenge are provided only when selected as an option (N).

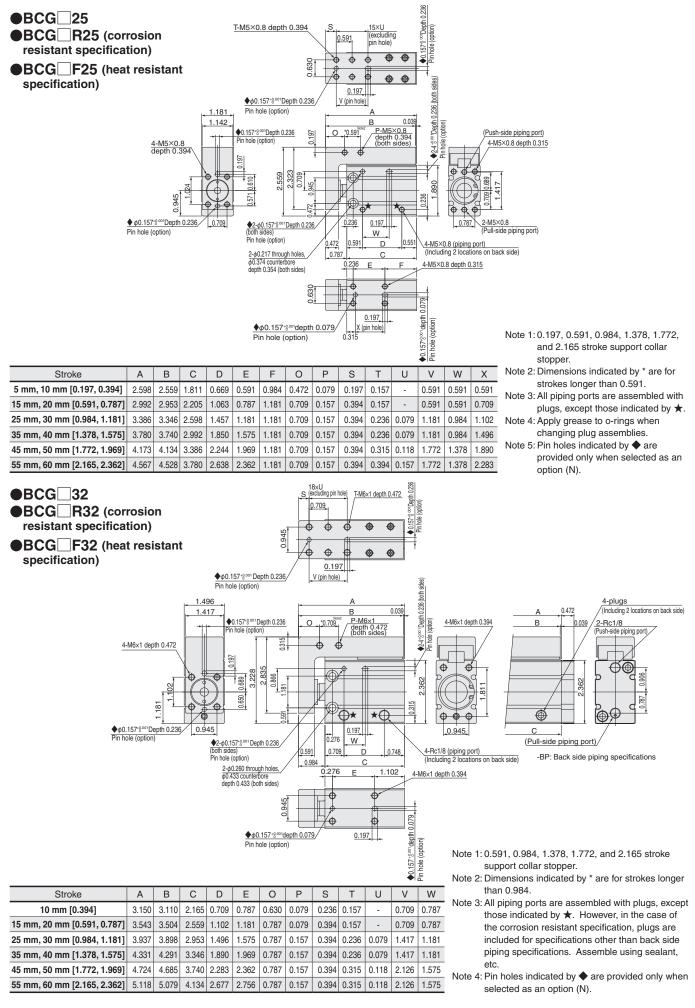
28 30 20

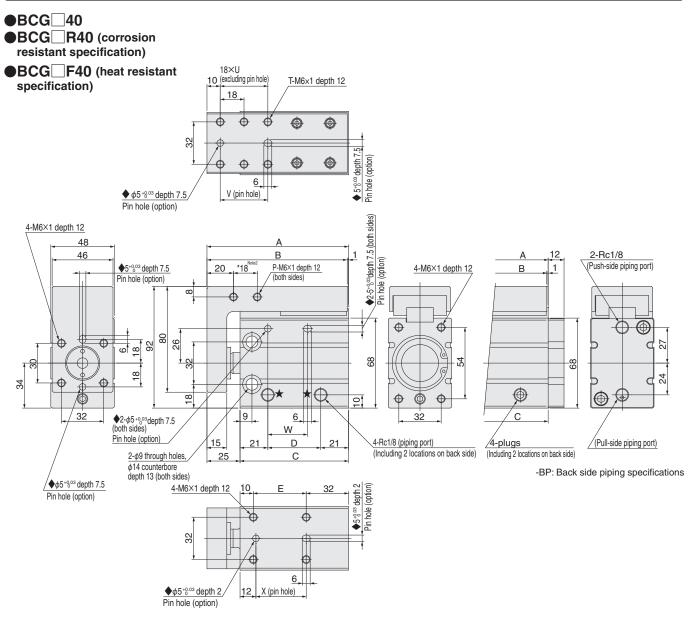
15, 20

W

-

10 4





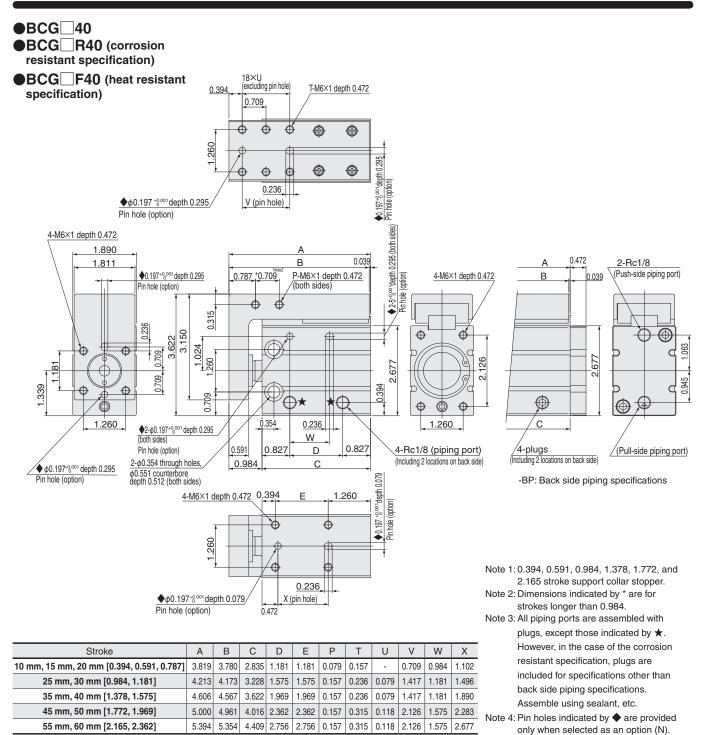
Stroke	А	В	С	D	E	Р	Т	U	V	W	Х
10, 15, 20	97	96	72	30	30	2	4	-	18	25	28
25, 30	107	106	82	40	40	4	6	2	36	30	38
35, 40	117	116	92	50	50	4	6	2	36	30	48
45, 50	127	126	102	60	60	4	8	3	54	40	58
55, 60	137	136	112	70	70	4	8	3	54	40	68

Note 1: 10, 15, 25, 35, 45, and 55 stroke support collar stopper.

Note 2: Dimensions indicated by * are for strokes longer than 25.

Note 3:All piping ports are assembled with plugs, except those indicated by ★. However, in the case of the corrosion resistant specification, plugs are included for specifications other than back side piping specifications. Assemble using sealant, etc.

Note 4: Pin holes indicated by \blacklozenge are provided only when selected as an option (N).



unit: in

Basic Cylinders

Clean system compatible cylinders Cylinder with guide

Symbol





Specifications (clean room specification)

Item	Cylinder bore	8 [0.315]	12 [0.472]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]	40 [1.575]					
Operating type					Double acting type)							
Medium					Air								
Operating pressure	range MPa [psi]	0.2 to 0.7 [29 to 102]	0.1 to 0.7	[15 to 102]		0.08 to 0.7	[12 to 102]						
Proof pressure	MPa [psi		1.05 [152]										
Operating temperature													
Operating speed range	e mm/s [in/sec]		50 to 300 [1.969 to 11.8]										
Cushion		Rubber bumper											
Lubrication		No											
Port size		M3×0.5		M53	< 0.8		Rc	1/8					
Running parallelism	mm [in]				0.1 [0.004] or less								
Allowable moment	Pitching	0.12 [1.062]	0.40 [3.540]	1.50 [13.277]	2.18 [19.295]	4.46 [39.475]	6.70 [59.302]					
	Rolling	0.12 [1.062]	0.40 [3.540]	1.80 [15.932]	2.18 [19.295]	4.46 [39.475]	8.00 [70.808]					
N•m [in•lbf]	Yawing	0.21 [1.859]	0.68 [6.019]	2.20 [19.472]	4.18 [36.997]	7.31 [64.701]	13.70 [121.259]					
Clean room rating ^{Not}	e 1	Clean room rating ^{Note 1} Class 6 equivalent (FED-STD Class 1000 equivalent) ^{Note 2}											

Note 1: Koganei standard. Dust collection port not available.

2: FED-STD was abolished as of November 2001, and it is designed here for reference purposed.

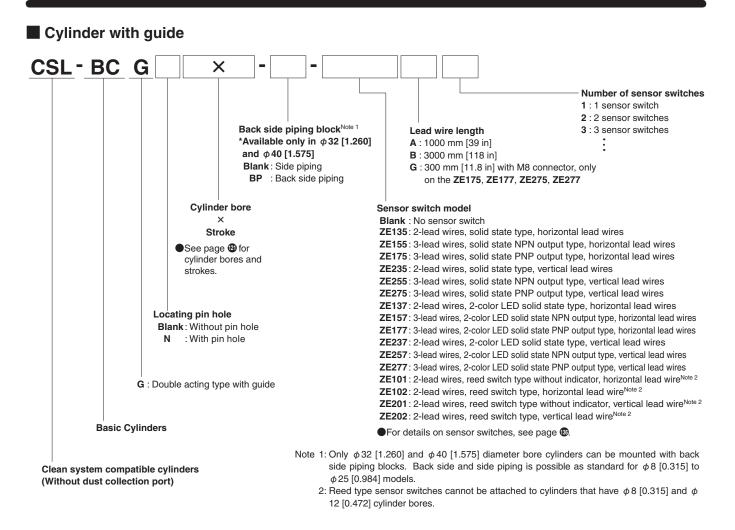
Linear guide being used

Cylinder bore	Rail width	Manufacturer
φ8 [0.315], φ12 [0.472]	5 [0.197]	
ϕ 16 [0.630]	7 [0.276]	
φ 20 [0.787]	9 [0.354]	тнк
φ 25 [0.984]	12 [0.472]	ITIK
φ 32 [1.260]	15 [0.591]	
ϕ 40 [1.575]	20 [0.787]	

Cylinder bore and stroke

Cylinder bore	Standard stroke
8, 12, 16, 20, 25 [0.315, 0.472, 0.630, 0.787, 0.984]	5 ^{Note} , 10, 15 ^{Note} , 20, 25 ^{Note} , 30, 35 ^{Note} , 40, 45 ^{Note} , 50, 55 ^{Note} , 60
32 [1.260]	10, 15 ^{Note} , 20, 25 ^{Note} , 30, 35 ^{Note} , 40, 45 ^{Note} , 50, 55 ^{Note} , 60
40 [1.575]	10 ^{Note} , 15 ^{Note} , 20, 25 ^{Note} , 30, 35 ^{Note} , 40, 45 ^{Note} , 50, 55 ^{Note} , 60

Note: Collar stopper is used in this stroke.



Mass

• Cylinder with guide

												31-1
Model						Stroke	mm [in]					
woder	5 [0.197]	10 [0.394]	15 [0.591]	20 [0.787]	25 [0.984]	30 [1.181]	35 [1.378]	40 [1.575]	45 [1.772]	50 [1.969]	55 [2.165]	60 [2.362]
CSL-BCG8	56 [1.975]	54 [1.905]	68 [2.399]	66 [2.328]	80 [2.822]	78 [2.751]	92 [3.245]	90 [3.175]	104 [3.7]	102 [3.6]	116 [4.1]	114 [4.0]
CSL-BCG12	82 [2.892]	81 [2.857]	96 [3.386]	95 [3.351]	110 [3.9]	109 [3.8]	124 [4.4]	123 [4.3]	138 [4.9]	137 [4.8]	152 [5.4]	151 [5.3]
CSL-BCG16	133 [4.7]	131 [4.6]	155 [5.5]	153 [5.4]	178 [6.3]	176 [6.2]	200 [7.1]	198 [7.0]	222 [7.8]	220 [7.8]	245 [8.6]	243 [8.6]
CSL-BCG20	207 [7.3]	205 [7.2]	236 [8.3]	234 [8.3]	265 [9.3]	263 [9.3]	294 [10.4]	292 [10.3]	323 [11.4]	321 [11.3]	352 [12.4]	350 [12.3]
CSL-BCG25	321 [11.3]	317 [11.2]	366 [12.9]	362 [12.8]	411 [14.5]	407 [14.4]	456 [16.1]	452 [15.9]	501 [17.7]	497 [17.5]	546 [19.3]	542 [19.1]
CSL-BCG32	-	597 [21.1]	675 [23.8]	669 [23.6]	746 [26.3]	740 [26.1]	818 [28.9]	812 [28.6]	889 [31.4]	883 [31.1]	961 [33.9]	955 [33.7]
CSL-BCG40	-	1031 [36]	1025 [36]	1019 [36]	1122 [40]	1116 [39]	1219 [43]	1213 [43]	1316 [46]	1310 [46]	1413 [50]	1407 [50]

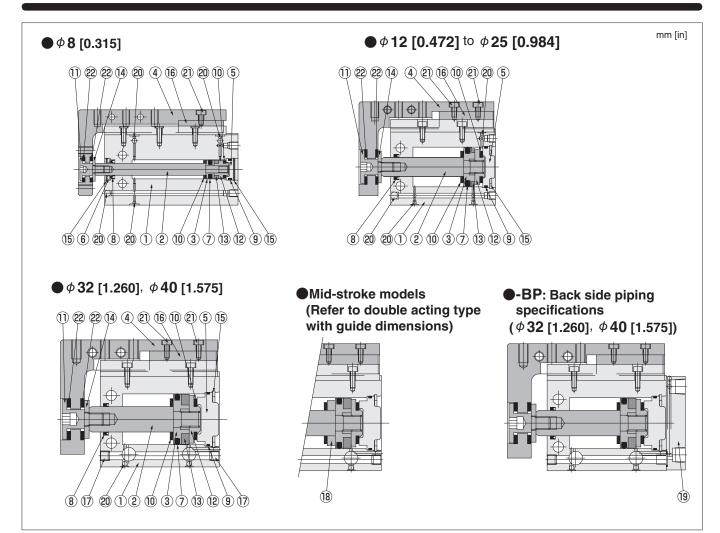
In the case of back side piping specifications, mass is 76 g [2.68 oz] for a ϕ 32 [1.260] cylinder bore and 108 g [3.8 oz] for a ϕ 40 [1.575] cylinder bore.

Additional mass of sensor switches

ZE A, **ZE G**: 15 g [0.53 oz] **ZE B**: 35 g [1.23 oz]

a [oz]

Inner construction

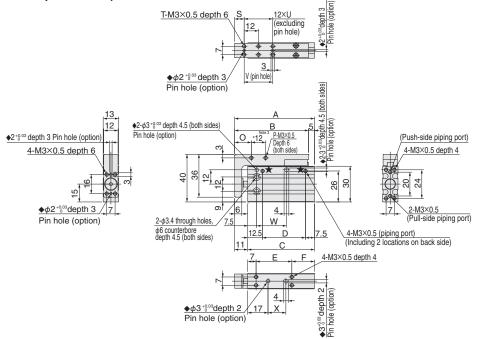


Major parts and materials (clean room specification)

No.	Name	φ 8 [0.315]	φ 12 [0.472]	φ 16 [0.630]	φ 20 [0.787]	φ 25 [0.984]	φ 32 [1.260]	φ 40 [1.575]							
1	Cylinder body			Aluminum all	oy (special anti-abra	asion treated)	·								
2	Piston rod				Stainless steel										
3	Piston	Stainles	ss steel		Alur	ninum alloy (anodi	zed)								
4	Table			Alu	minum alloy (anodiz	zed)									
5	Head cover			Alu	minum alloy (anodiz	zed)									
6	Seal holder	Aluminum alloy (Anodized)	_	_	_	_	_	_							
\overline{O}	★ Piston seal			S	nthetic rubber (NB	R)									
8	★ Rod seal		Synthetic rubber (NBR)												
9	★ O-ring		Synthetic rubber (NBR)												
10	Bumper		Synthetic rubber (NBR)												
11	End bolt				Stainless steel										
(12)	Support			Alu	minum alloy (anodiz	zed)									
(13)	Magnet		I	Neodymium magne	t		Plastic	magnet							
(14)	Bolt retainer				Stainless steel										
(15)	★ Retaining ring	Stainless steel			Steel (electroles	ss nickel plated)									
(16)	Linear guide				Stainless steel										
17	Plug	_	—	-	—	_	Stainle	ss steel							
(18)	Collar			Alu	minum alloy (anodiz	zed)									
(19)	★ Back side piping block	_	_	-	_	_	Aluminum all	oy (anodized)							
20	Steel ball				Stainless steel										
(21)	Bolt				Stainless steel										
(22)	Bumper				Urethane rubber										

Items indicated by a 🖈 are available as additional parts or in packing sets. For order codes, see page 🕲 and 🕲.

•CSL-BCG 8 (clean room specification)

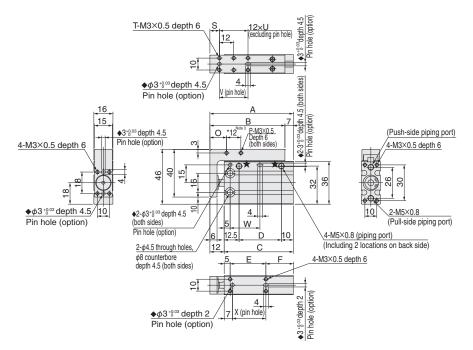


Stroke	А	В	С	D	E	F	0	Р	S	Т	U	V	W	Х
5, 10	47	42	36	16	15	14	10	2	5	4	-	12	15	10
15, 20	57	52	46	26	20	19	14	4	8	4	-	12	15	15
25, 30	67	62	56	36	30	19	14	4	8	6	2	24	25	15
35, 40	77	72	66	46	40	19	14	4	8	8	3	24	25	25
45, 50	87	82	76	56	50	19	14	4	8	10	4	36	35	35
55, 60	97	92	86	66	60	19	14	4	8	12	5	36	35	45

Note 1: This product cannot use reed switch type sensor switches.

- Note 2:5, 15, 25, 35, 45, and 55 stroke has a collar stopper.
- Note 3: Dimensions indicated by * are for strokes longer than 15.
- Note 4: All piping ports are assembled with plugs, except those indicated by ★.
- Note 5: Apply grease to o-rings when changing plug assemblies.
- Note 6: Pin holes indicated by ◆ are provided only when selected as an option (N).

CSL-BCG 12 (clean room specification)



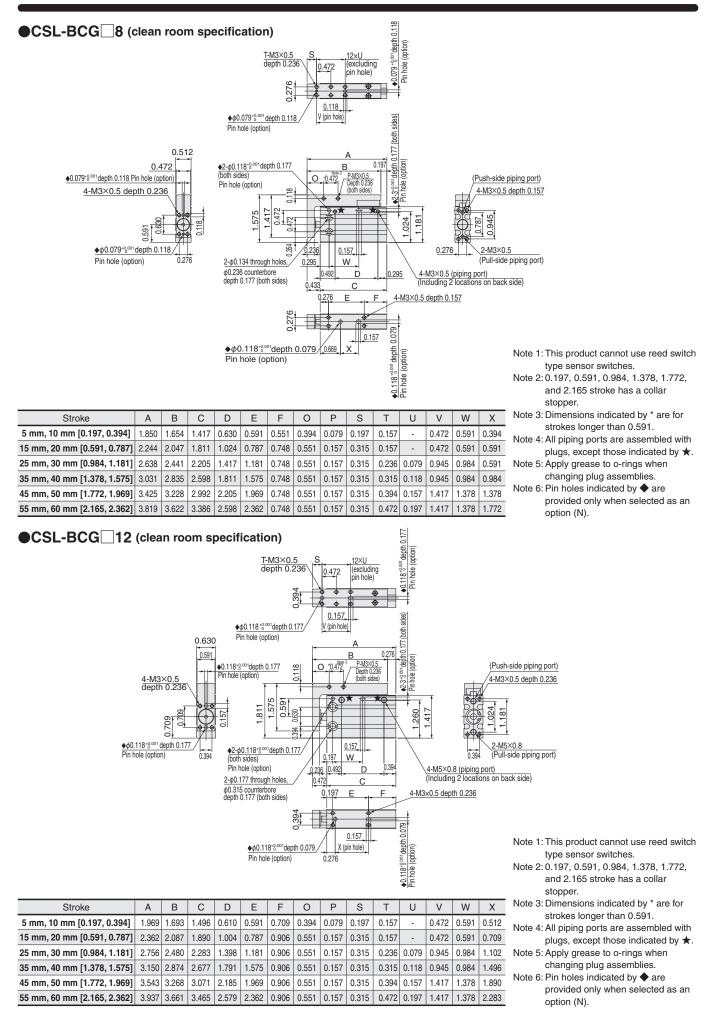
Stroke	А	В	С	D	Е	F	0	Р	S	Т	U	V	W	Х
5, 10	50	43	38	15.5	15	18	10	2	5	4	-	12	15	13
15, 20	60	53	48	25.5	20	23	14	4	8	4	-	12	15	18
25, 30	70	63	58	35.5	30	23	14	4	8	6	2	24	25	28
35, 40	80	73	68	45.5	40	23	14	4	8	8	3	24	25	38
45, 50	90	83	78	55.5	50	23	14	4	8	10	4	36	35	48
55, 60	100	93	88	65.5	60	23	14	4	8	12	5	36	35	58

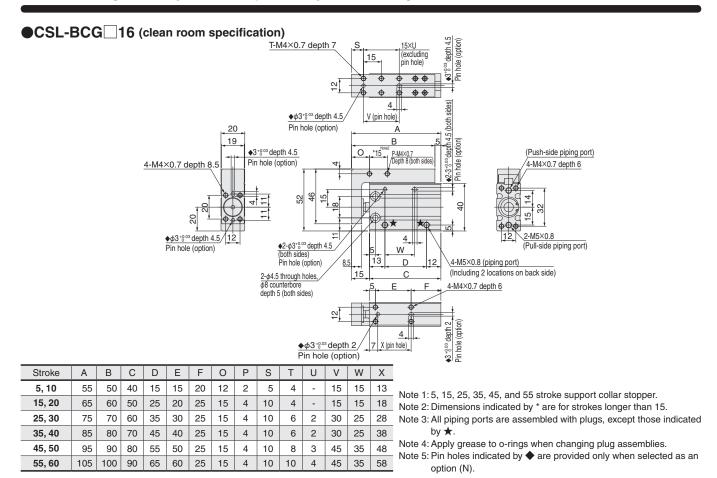
Note 1: This product cannot use reed switch type sensor switches. Note 2: 5, 15, 25, 35, 45, and 55 stroke has a collar stopper.

- Note 3: Dimensions indicated by * are for strokes longer than 15.
- Note 4: All piping ports are assembled with plugs, except those indicated by \bigstar .

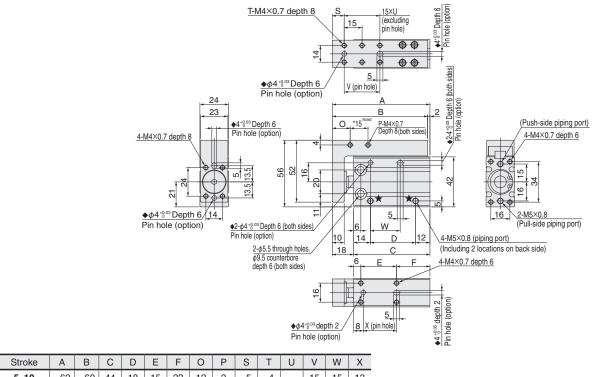
Note 5: Apply grease to o-rings when changing plug assemblies.

Note 6: Pin holes indicated by \blacklozenge are provided only when selected as an option (N).





CSL-BCG 20 (clean room specification)



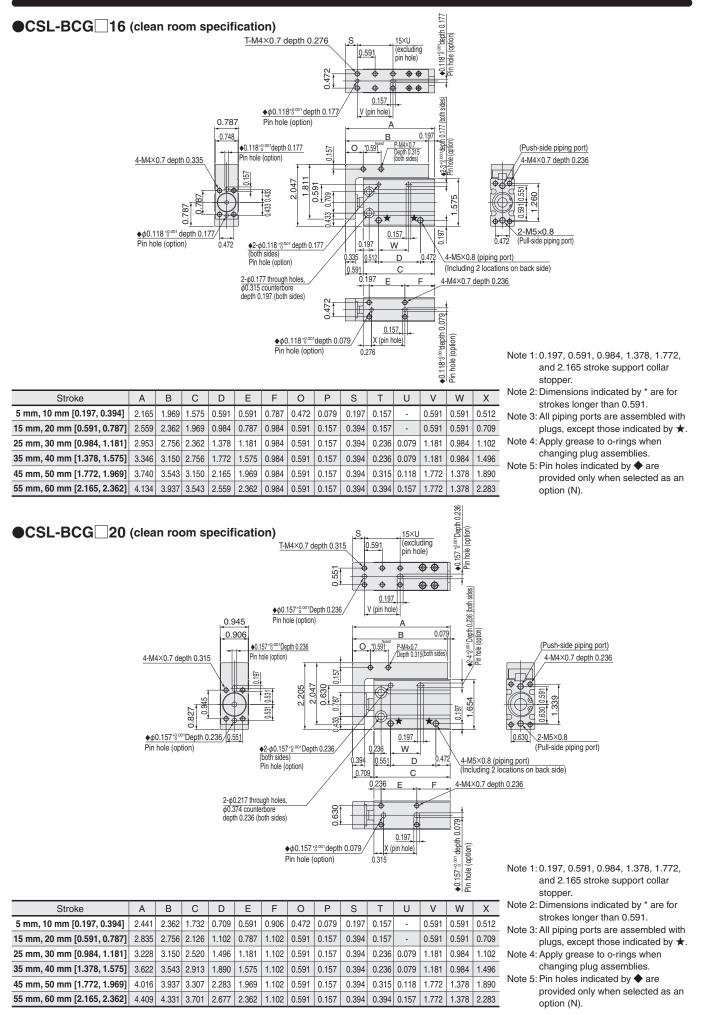
	Stroke	A	D	C			Г	0	Р	5	I	0	V	vv	_ ^
ĺ	5, 10	62	60	44	18	15	23	12	2	5	4	-	15	15	13
	15, 20	72	70	54	28	20	28	15	4	10	4	-	15	15	18
	25, 30	82	80	64	38	30	28	15	4	10	6	2	30	25	28
	35, 40	92	90	74	48	40	28	15	4	10	6	2	30	25	38
	45, 50	102	100	84	58	50	28	15	4	10	8	3	45	35	48
ĺ	55, 60	112	110	94	68	60	28	15	4	10	10	4	45	35	58

Note 1:5, 15, 25, 35, 45, and 55 stroke support collar stopper. Note 2: Dimensions indicated by * are for strokes longer than 15.

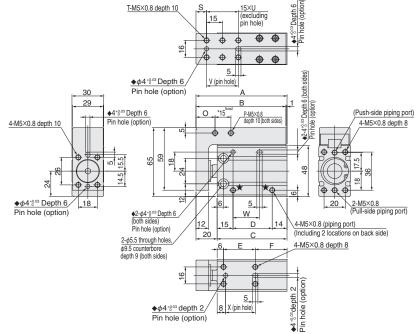
Note 3: All piping ports are assembled with plugs, except those indicated by $\bigstar.$

Note 4: Apply grease to o-rings when changing plug assemblies.

Note 5: Pin holes indicated by \blacklozenge are provided only when selected as an option (N).



•CSL-BCG 25 (clean room specification)



Stroke	Α	В	С	D	Е	F	0	Р	S	Т	U	V	W	Х
5, 10	66	65	46	17	15	25	12	2	5	4	-	15	15	15
15, 20	76	75	56	27	20	30	18	4	10	4	-	15	15	18
25, 30	86	85	66	37	30	30	18	4	10	6	2	30	25	28
35, 40	96	95	76	47	40	30	18	4	10	6	2	30	25	38
45, 50	106	105	86	57	50	30	18	4	10	8	3	45	35	48
55, 60	116	115	96	67	60	30	18	4	10	10	4	45	35	58

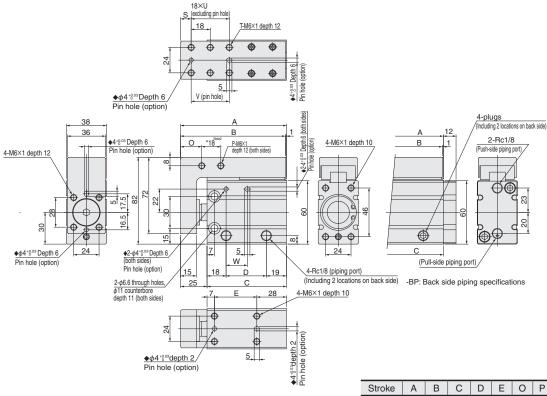
•CSL-BCG 32 (clean room specification)

Note 1:5, 15, 25, 35, 45, and 55 stroke support collar stopper.

- Note 2: Dimensions indicated by * are for strokes longer than 15.
- Note 3: All piping ports are assembled with plugs, except those indicated by \bigstar .

Note 4: Apply grease to o-rings when changing plug assemblies.

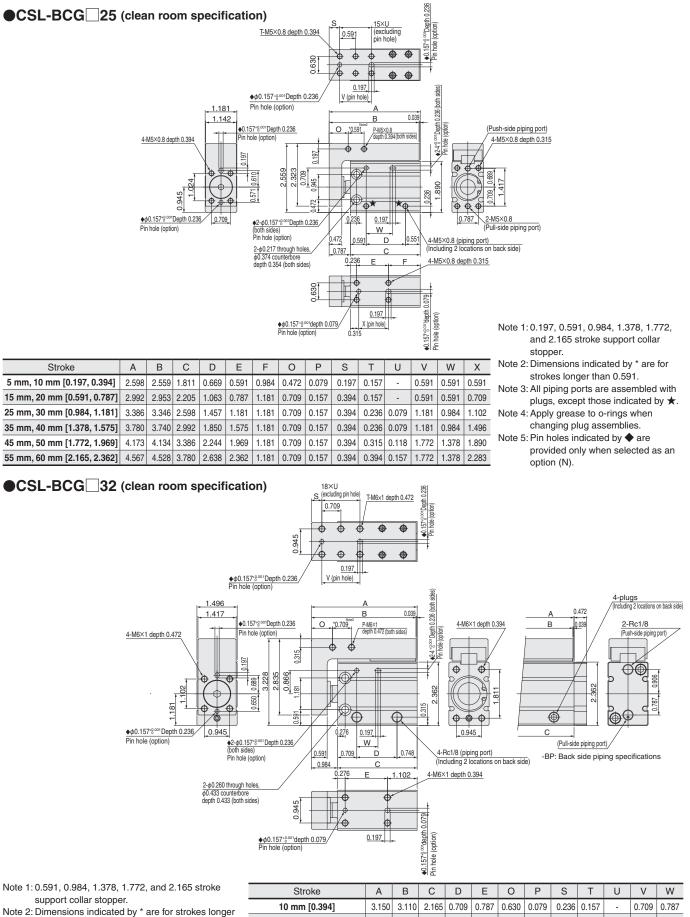
Note 5: Pin holes indicated by ♦ are provided only when selected as an option (N).



Note 1: 15, 25, 35, 45, and 55 stroke support collar stopper.

- Note 2: Dimensions indicated by * are for strokes longer than 25.
- Note 3: Plugs are included for specifications other than back side piping
- specifications. Assemble using sealant, etc.
 Note 4: Pin holes indicated by ◆ are provided only when selected as an option (N).

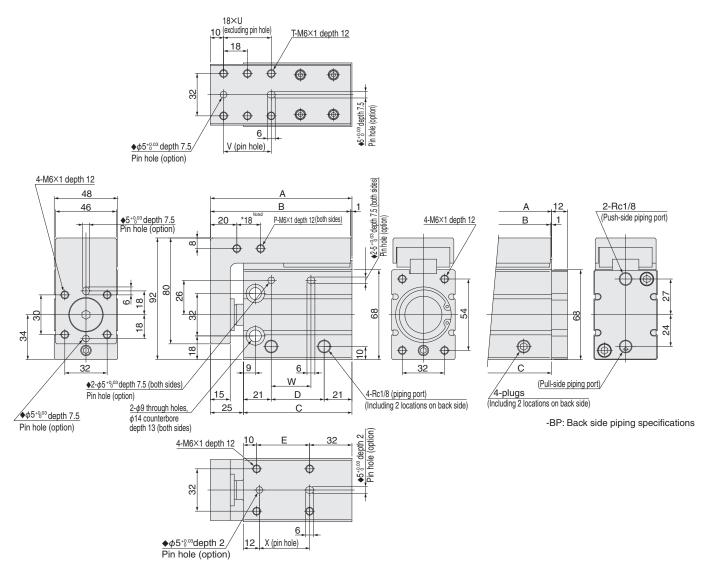
Stroke	A	В	С	D	Е	0	Ρ	S	Т	U	V	W
10	80	79	55	18	20	16	2	6	4	-	18	20
15, 20	90	89	65	28	30	20	2	10	4	-	18	20
25, 30	100	99	75	38	40	20	4	10	6	2	36	30
35, 40	110	109	85	48	50	20	4	10	6	2	36	30
45, 50	120	119	95	58	60	20	4	10	8	3	54	40
55, 60	130	129	105	68	70	20	4	10	8	3	54	40



- than 0.984. Note 3: Plugs are included for specifications other than
- back side piping specifications. Assemble using sealant, etc.
- Note 4: Pin holes indicated by ♦ are provided only when selected as an option (N).

Otroite	~	D	0			0		0		0	v	**
10 mm [0.394]	3.150	3.110	2.165	0.709	0.787	0.630	0.079	0.236	0.157	-	0.709	0.787
15 mm, 20 mm [0.591, 0.787]	3.543	3.504	2.559	1.102	1.181	0.787	0.079	0.394	0.157	-	0.709	0.787
25 mm, 30 mm [0.984, 1.181]	3.937	3.898	2.953	1.496	1.575	0.787	0.157	0.394	0.236	0.079	1.417	1.181
35 mm, 40 mm [1.378, 1.575]	4.331	4.291	3.346	1.890	1.969	0.787	0.157	0.394	0.236	0.079	1.417	1.181
45 mm, 50 mm [1.772, 1.969]	4.724	4.685	3.740	2.283	2.362	0.787	0.157	0.394	0.315	0.118	2.126	1.575
55 mm, 60 mm [2.165, 2.362]	5.118	5.079	4.134	2.677	2.756	0.787	0.157	0.394	0.315	0.118	2.126	1.575

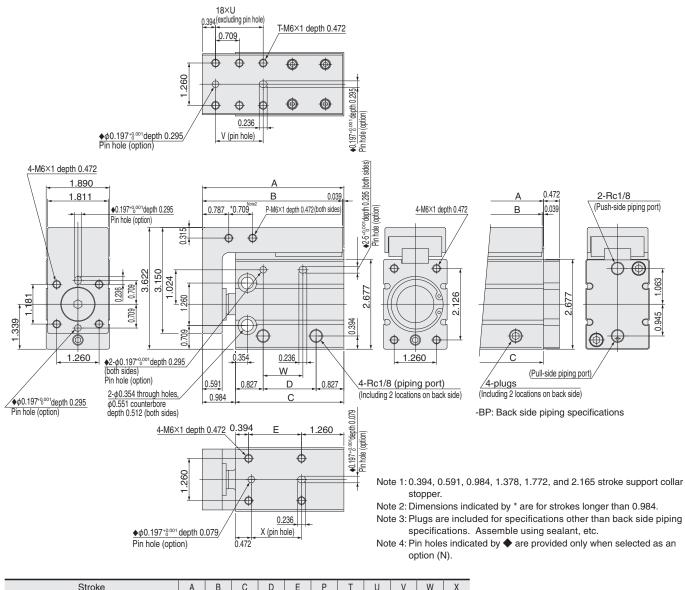
•CSL-BCG 40 (clean room specification)



Stroke	А	В	С	D	E	Р	Т	U	V	W	Х
10, 15, 20	97	96	72	30	30	2	4	-	18	25	28
25, 30	107	106	82	40	40	4	6	2	36	30	38
35, 40	117	116	92	50	50	4	6	2	36	30	48
45, 50	127	126	102	60	60	4	8	3	54	40	58
55, 60	137	136	112	70	70	4	8	3	54	40	68

- Note 1: 10, 15, 25, 35, 45, and 55 stroke support collar stopper.
- Note 2: Dimensions indicated by * are for strokes longer than 25.
- Note 3: Plugs are included for specifications other than back side piping specifications. Assemble using sealant, etc.
- Note 4: Pin holes indicated by \blacklozenge are provided only when selected as an option (N).

•CSL-BCG 40 (clean room specification)



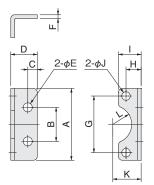
Stroke	А	В	С	D	E	Р	Т	U	V	W	Х
10 mm, 15 mm, 20 mm [0.394, 0.591, 0.787]	3.819	3.780	2.835	1.181	1.181	0.079	0.157	-	0.709	0.984	1.102
25 mm, 30 mm [0.984, 1.181]	4.213	4.173	3.228	1.575	1.575	0.157	0.236	0.079	1.417	1.181	1.496
35 mm, 40 mm [1.378, 1.575]	4.606	4.567	3.622	1.969	1.969	0.157	0.236	0.079	1.417	1.181	1.890
45 mm, 50 mm [1.772, 1.969]	5.000	4.961	4.016	2.362	2.362	0.157	0.315	0.118	2.126	1.575	2.283
55 mm, 60 mm [2.165, 2.362]	5.394	5.354	4.409	2.756	2.756	0.157	0.315	0.118	2.126	1.575	2.677

Order codes for brackets only mm [in]

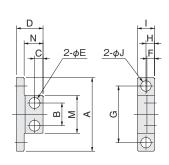
Note: Cannot be mounted on cylinders with guides (BCG \square).

Bracket dimensions mm [in]

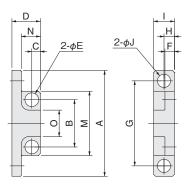
● φ **10 [0.394]** to φ **32 [1.260]**



• \$\phi\$ 40 [1.575] to \$\phi\$ 80 [3.150]



• \$\phi\$ 100 [3.9] to \$\phi\$ 125 [4.9]



Mounting bolt (2 pieces)



Material: Stainless steel (only M16 is steel)

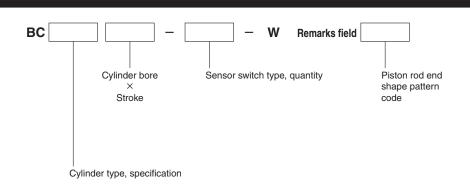
Bore	A	В	С	D	E	F	G	Н	I	J	К	L	М	N	0	Р	Q	S	т	Materials	Mass g[oz]
10 [0.394]	22 [0.866]	16 [0.630]	3 [0.118]	10 [0.394]	3.8 [0.150]	1 [0.039]	16 [0.630]	7 [0.276]	9.3 [0.366]	3.4 [0.134]	8 [0.315]	R5 [0.197]	-	-	-	5 [0.197]	3 [0.118]	4.5 [0.177]	M3 × 0.5	Stainless steel	4 [0.141]
12 [0.472]	26 [1.024]	14 [0.551]	4 [0.157]	13 [0.512]	4.8 [0.189]	1 [0.039]	19 [0.748]	8 [0.315]	11 [0.433]	4.5 [0.177]	8 [0.315]	R5 [0.197]	-	-	-	4 [0.157]	4 [0.157]	5.5 [0.217]	M4 × 0.7	Stainless steel	6 [0.212]
16 [0.630]											11 [0.433]	R7 [0.276]	-	-	-	5 [0.197]	3 [0.118]	5.5 [0.217]	M3 × 0.5	Stainless steel	7 [0.247]
20 [0.787]													-	-	-	8 [0.315]	4 [0.157]	7 [0.276]	M4 × 0.7	Stainless steel	12 [0.423]
25 [0.984]													-	-	-	8 [0.315]	4 [0.157]	7 [0.276]	M4 × 0.7	Stainless steel	14 [0.494]
32 [1.260]													-	-	-	8 [0.315]	5 [0.197]	8.5 [0.335]	M5 × 0.8	Stainless steel	24 [0.847]
40 [1.575]												-	28	14 [0.551]	-	12 [0.472]	6 [0.236]	10 [0.394]	M6 × 1	Aluminum alloy	25 [0.882]
50 [1.969]											-	-	37 [1.457]	18 [0.709]	-	12 [0.472]	8 [0.315]	13 [0.512]	M8 × 1.25	Aluminum alloy	45 [1.587]
63 [2.480]					11.5 [0.453]	8	60	9	18	11	-	-	40 [1.575]	20 [0.787]	-	16 [0.630]	10 [0.394]	16 [0.630]	M10 × 1.5	Aluminum alloy	80 [2.822]
80 [3.150]					14.5 [0.571]	8 [0.315]	70 [2.756]	10 [0.394]	20 [0.787]	14 [0.551]	_	_	48 [1.890]	28 [1.102]	-	20 [0.787]	12 [0.472]	18 [0.709]	M12 × 1.75	Aluminum alloy	128 [4.5]
100 [3.9]	112	50	9	30	14.5 [0.571]	10	90	11	22	14	_	_	68 [2.677]	20 [0.787]	28 [1.102]	20 [0.787]	12 [0.472]	18 [0.709]	M12 × 1.75	Aluminum alloy	167 [5.9]
125 [4.9]	140 [5.5]	58 [2.283]	14 [0.551]	42 [1.654]	18.5 [0.728]	14 [0.551]	110 [4.331]	15 [0.591]	30 [1.181]	18 [0.709]	_	_	82 [3.228]	30 [1.181]	30 [1.181]	35 [1.378]	16 [0.630]	24 [0.945]	M16 × 2	Aluminum alloy	410 [14.5]

Note: Mass includes mass of 2 supplied bolts

Piston rod end shape pattern diagrams

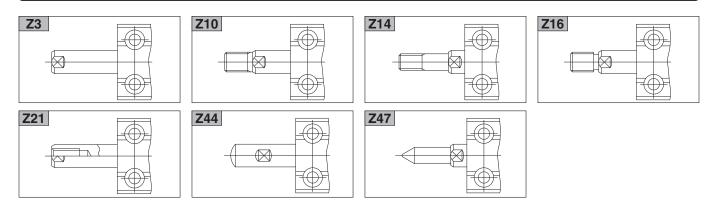
There are seven patternized piston rod end shapes. A non-standard end shaped cylinder can be order made by simply filling in the items on the order that has the required shape drawn on it. This applies to all types of basic cylinders. Contact Koganei for order forms with pattern shaped drawn on them.

Order code example



Note: For clean room specifications, CS- or CSL- is appended before BC. For details, see the pages for the corresponding order codes.

Piston rod end shape pattern diagrams (7 types)

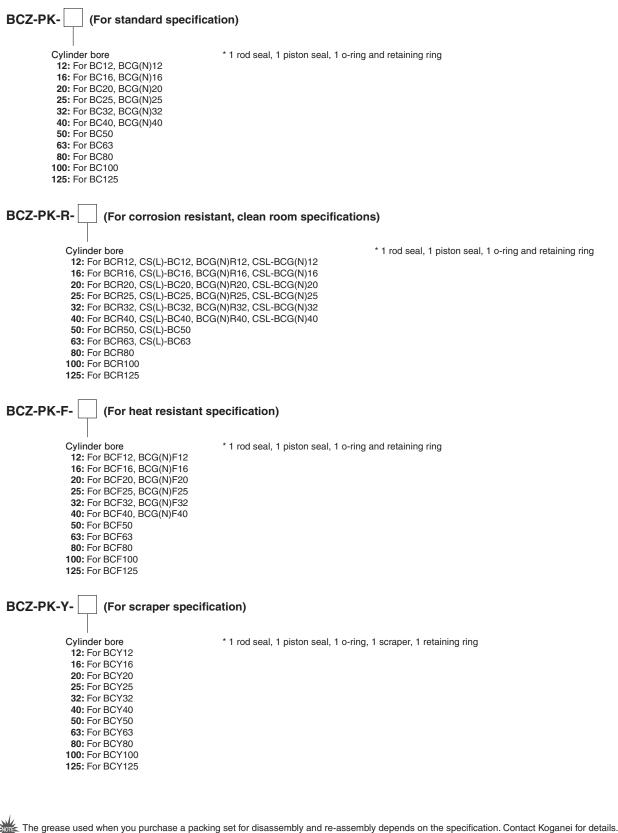


Additional Parts

Note 1: ϕ 6 [0.236], ϕ 8 [0.315] and ϕ 10 [0.394] cannot be disassembled.

2: Be careful that the steel balls do not fall out from the linear guide when doing maintenance on cylinders with guides.

Packing set for double acting type (including models with guides)



The greate used when you purchase a packing set for disasterinity and to assertiony depends on the specification. Contact regards in

Additional Parts

Note: $\phi \in [0.236]$, $\phi \in [0.315]$ and $\phi = 10 [0.394]$ cannot be disassembled.

Packing set for double acting double rod end type BCZ-PK-D (For standard specification) BCZ-PK-R-D (For corrosion resistant specification) Cylinder bore Cylinder bore * 2 rod seals, 1 piston seal, 1 o-ring and retaining ring 12: For BCD12 12: For BCDR12 16: For BCD16 16: For BCDR16 20: For BCD20 20: For BCDR20 25: For BCD25 25: For BCDR25 32: For BCD32 32: For BCDR32 40: For BCD40 40: For BCDR40 50: For BCD50 50: For BCDR50 63: For BCD63 63: For BCDR63 80: For BCD80 80: For BCDR80 100: For BCDR100 100: For BCD100 125: For BCD125 125: For BCDR125 Packing set for single acting push and pull type **BCZ-PK-S** (For standard specification) BCZ-PK-R-S (For corrosion resistant specification) Cylinder bore Cylinder bore * 1 rod seal, 1 piston seal, 1 o-ring, retaining ring 12: For BCSA12, BCTA12 12: For BCSAR12, BCTAR12 and 1 spring 16: For BCSA16, BCTA16 16: For BCSAR16, BCTAR16 20: For BCSA20, BCTA20 20: For BCSAR20, BCTAR20 25: For BCSA25, BCTA25 25: For BCSAR25, BCTAR25 32: For BCSA32, BCTA32 32: For BCSAR32, BCTAR32 40: For BCSA40, BCTA40 40: For BCSAR40, BCTAR40 50: For BCSA50, BCTA50 50: For BCSAR50, BCTAR50 Piping port plugs for cylinders with guides BCZ-PM (For standard, corrosion resistant, clean room specifications) Thread size 3: For M3(For BCG(N)8, BCG(N)R8, CSL-BCG(N)8) 5: For M5(For BCG(N)12, BCG(N)R12, CSL-BCG(N)12, BCG(N)16, BCG(N)R16, CSL-BCG(N)16, BCG(N)20, BCG(N)R20, CSL-BCG(N)20, BCG(N)25, BCG(N)R25, CSL-BCG(N)25) *4 plugs assembled with o-rings in each bag BCZ-F-PM (For heat resistant specification) Thread size 3: For M3(For BCG(N)F8) 5: For M5(For BCG(N)F12, BCG(N)F16, BCG(N)F20, BCG(N)F25) Back side piping block for cylinders with guides (For standard specification) BCZ-R-BP BCZ-BP (For corrosion resistant, clean room specifications) Cylinder bore Cylinder bore 32: For BCG(N)R32, CSL-BCG(N)32 32: For BCG(N)32 40: For BCG(N)40 40: For BCG(N)R40, CSL-BCG(N)40 BCZ-F-BP (For heat resistant specification) 1 back side piping block with press fitted steel balls Cylinder bore 1 each of two types of o-rings, 2 32: For BCG(N)F32 mounting bolts 40: For BCG(N)F40 The grease used when you purchase a packing set for disassembly and re-assembly depends on the specification. Contact Koganei for details.

 ${}^{\sharp}$ Products that have been disassembled and reassembled are not covered by the warranty.

Sensor switches

Solid state type, reed switch type

Robot cable is standard equipment

Lead wire flexibility is excellent because the conductor used is the same as for robot cables.

Specifications

Solid State Type

Item Model	ZE135	ZE155	ZE175	ZE235	ZE255	ZE275				
Wiring method	2-lead wire	3-lead wire with NPN output	3-lead wire with PNP output	2-lead wire	3-lead wire with NPN output	3-lead wire with PNP output				
Lead wire direction	Horiz	ontal		Ver	tical					
Power supply voltage	_	4.5 to 2	28 VDC	_	4.5 to 2	8 VDC				
Load voltage	10 to 28 VDC	4.5 to 2	28 VDC	10 to 28 VDC	4.5 to 2	8 VDC				
Load current	2.5 to 20 mA (at 25°C [77°F], and 10 mA at 60°C [140°F])	40 mA	A max.	2.5 to 20 mA (at 25°C [77 $^\circ\text{F}$], and 10 mA at 60°C [140 $^\circ\text{F}$])	40 mA	max.				
Consumption current	—	8 mA max. (24 VDC)	10 mA max.(24 VDC)	—	8 mA max. (24 VDC)	10 mA max.(24 VDC)				
Internal voltage drop ^{Note 1}	4 V max.	2 V max. (0.8 V max if l	oad is less than 10 mA)	4 V max.	2 V max. (0.8 V max if lo	oad is less than 10 mA)				
Leakage current	0.7 mA max. (24 VDC, 25°C [77 °F])	50 μ A max	к. (24 VDC)	0.7 mA max. (24 VDC, 25°C [77 °F])	50 µ A max	. (24 VDC)				
Response time			1 ms i	max.						
Insulation resistance	100	0 M Ω min. (at 50	0 VDC megger, b	etween case and lead wire termina	l)					
Dielectric strength		500 VAC (50/60 ⊦	Iz) 1 minute (betw	veen case and lead wire terminal)						
Shock resistanceNote 2			294.2 m/s² [30 G]	(non-repeated)						
Vibration resistanceNote 2		88.3 m/s ² [9 G] (total amplitude of	1.5 mm [0.059 in], 10 to 55 Hz)						
Protection from environment		IP67 (IE	C standard), JIS	C0920 (watertight type)						
Operation indicators			Red LED indica	tor lit when on						
Lead wires	PCCV0.2SQ x 2-lead (brown and blue) x l Note 3 PCCV0.1SSQ x 3-lead (brown, blue, and black) x l Note 3 PCCV0.2SQ x 2-lead (brown and blue) x l Note 3 PCCV0.1SSQ x 3-lead (brown, blue, and black) x									
Ambient temperature	0 to 60°C [32 to 140°F]									
Storage temperature range			-10 to 70°C [1	4 to 158°F]						
Mass	15 g [0.53 oz] (for lead wire length A: 1000 mm [39 in]), 35 g [1.23 oz] (for lead wire length B: 3000 mm [118 in]), 15 g [0.53 oz] (for lead wire length 300 mm [11.8 in] with M8 connector)									

Note 1: Internal voltage drop changes with the load current.

2: According to Koganei test standards.

3: Lead wire length l: A; 1000 mm [39 in], B; 3000 mm [118 in], G; 300 mm [11.8 in] with M8 connector only on the ZE175 and ZE275

Reed Switch Type

Item Model	ZE1	01	ZE1	02	ZE2	01	ZE2	02				
Wiring method				2-lead	d wire							
Lead wire direction		Horiz	ontal			Ver	tical					
Load voltage	5 to 28 VDC	85 to 115 VAC (rms)	10 to 28 VDC	85 to 115 VAC (rms)	5 to 28 VDC	85 to 115 VAC (rms)	10 to 28 VDC	85 to 115 VAC (rms)				
Load current	40 mA max.	20 mA max.	5 to 40 mA	5 to 20 mA	40 mA max.	20 mA max.	5 to 40 mA	5 to 20 mA				
Internal voltage drop ^{Note 1}	0.1 V max. (for load	current of 40 mA DC)	3.0 V	max.	0.1 V max. (for load of	current of 40 mA DC)	3.0 V	max.				
Leakage current	OmA											
Response time				1 ms	max.							
Insulation resistance		1(00 M Ω min. (at 5	00 VDC megger, b	between case and	l lead wire termina	al)					
Dielectric strength			1500 VAC (50/60	Hz) 1 minute (bet	tween case and le	ead wire terminal)						
Shock resistanceNote 2				294.2 m/s ² [30 G	i] (non-repeated)							
Vibration resistance ^{Note 2}		88.3 m/s ² [9 G] (1	total amplitude of	1.5 mm [0.059 in]	, 10 to 55 Hz), res	sonance frequenc	y 2570 ±250 Hz					
Protection from environment			IP67 (I	EC standard), JIS	C0920 (watertigh	nt type)						
Operation indicators	No	one	Red LED indic	ator lit when on	No	ne	Red LED indic	ator lit when on				
Lead wires			PCCV	0.2SQ x 2-lead (b	rown and blue) x	l Note 3						
Ambient temperature				0 to 60°C [3	32 to 140°F]							
Storage temperature range				-10 to 70°C [14 to 158°F]							
Contact protection measure	Required (see page											
Mass	15	g [0.53 oz] (for lea	ad wire length A:	1000 mm [39 in]),	35 g [1.23 oz] (for	r lead wire length	B: 3000 mm [118	in])				

Note 1: Internal voltage drop changes with the load current.

2: According to Koganei test standards. 3: Lead wire length ℓ : A; 1000 mm [39 in], B; 3000mm [118 in]

Sensor switches

Two-color LED solid state type

Robot cable is standard equipment

Lead wire flexibility is excellent because the conductor used is the same as for robot cables.

Specifications

Two-color LED solid state type

Item Model	ZE137	ZE157	ZE177	ZE237	ZE257	ZE277					
Wiring method	2-lead wire	3-lead wire with NPN output	3-lead wire with PNP output	2-lead wire	3-lead wire with NPN output	3-lead wire with PNP output					
Lead wire direction	Horiz	contal		Ver	tical						
Power supply voltage		4.5 to 2	28 VDC	_	4.5 to 2	8 VDC					
Load voltage	10 to 28 VDC	4.5 to 2	28 VDC	10 to 28 VDC	4.5 to 2	8 VDC					
Load current	2.5 to 20 mA (at 25°C [77°F], and 10 mA at 60°C [140°F])	40 m/	A max.	2.5 to 20 mA (at 25°C [77 $^\circ\text{F}$], and 10 mA at 60°C [140 $^\circ\text{F}$])	40 mA	max.					
Consumption current	_	8 mA max. (24 VDC)	10 mA max.(24 VDC)	_	8 mA max. (24 VDC)	10 mA max.(24 VDC)					
Internal voltage drop ^{Note 1}	4 V max.	2 V max. (0.8 V max if lo	oad is less than 10 mA)								
Leakage current	0.7 mA max. (24 VDC, 25°C [77 °F]) 50 μ A max. (24 VDC) 0.7 mA max. (24 VDC, 25°C [77 °F]) 50 μ A max										
Response time			1 ms i	max.							
Insulation resistance	100	0 M Ω min. (at 50	0 VDC megger, b	etween case and lead wire termina	l)						
Dielectric strength		500 VAC (50/60 H	Iz) 1 minute (betw	veen case and lead wire terminal)							
Shock resistanceNote 2			294.2 m/s² [30 G]	(non-repeated)							
Vibration resistanceNote 2		88.3 m/s ² [9 G]	(total amplitude of	1.5 mm [0.059 in], 10 to 55 Hz)							
Protection from environment		IP67 (IE	C standard), JIS (C0920 (water-proof type)							
Operation indicators	Appropriate operatio	n range: Green Ll	ED indicator lit wh	en on, operation range: Red LED i	ndicator lit when o	n					
Lead wires	PCCV0.2SQ x 2-lead (brown and blue) x l Note 3 PCCV0.1SSQ x 3-lead (brown, blue, and black) x l Note 3 PCCV0.2SQ x 2-lead (brown and blue) x l Note 3 PCCV0.1SSQ x 3-lead (brown, blue, and black) x l Note 3										
Ambient temperature	0 to 60°C [32 to 140°F]										
Storage temperature range	-10 to 70°C [14 to 158°F]										
Mass	15 g [0.53 oz] (for lead wire length A: 1000 mm [39 in]), 35 g [1.23 oz] (for lead wire length B: 3000 mm [118 in]), 15 g [0.53 oz] (for lead wire length 300 mm [11.8 in] with M8 connector)										

Note 1: Internal voltage drop changes with the load current.

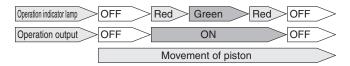
2: According to Koganei test standards.

3: Lead wire length l : A; 1000 mm [39 in], B; 3000 mm [118 in], G; 300 mm [11.8 in] with M8 connector only on the ZE177 and ZE277

Operation

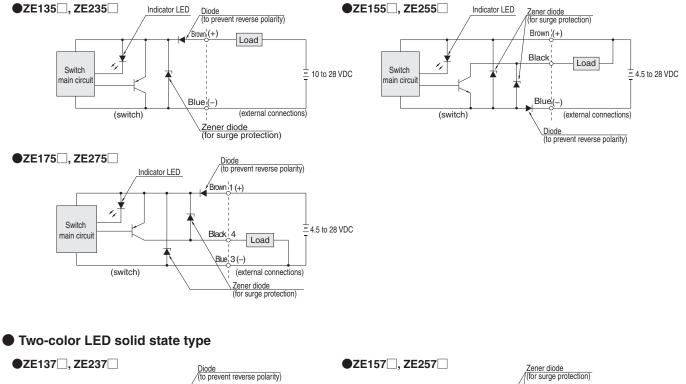
Explanation of operation of two-color LED solid state type

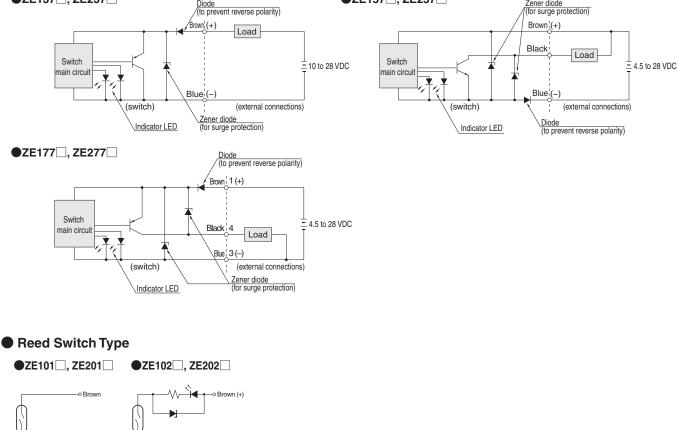
ZE137, ZE157, ZE177, ZE237, ZE257, ZE277



Note: The operating output may become unstable, due to the effects of the operating and installation environments, even if the appropriate operating range (green LED indicator lit) is fixed.

Solid State Type



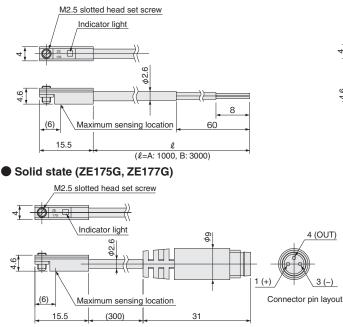


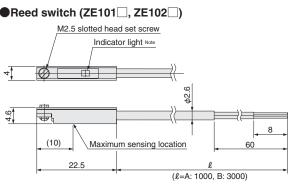
------ Blue (-)

Blue

Horizontal lead wire

●Solid state (ZE135□, ZE155□, ZE175□, ZE137□, ZE157□, ZE177□) ●Reed switch (ZE101□, ZE102□)

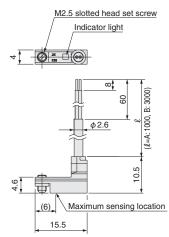




Note: Not available with the ZE101 \Box .

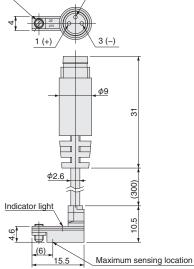
• Vertical lead wire

●Solid state (ZE235□, ZE255□, ZE275□, ZE237□, ZE257□, ZE277□)

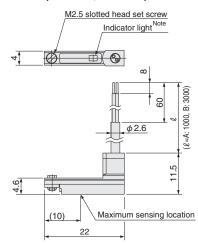


• Solid state (ZE275G, ZE277G)

Connector pin layout



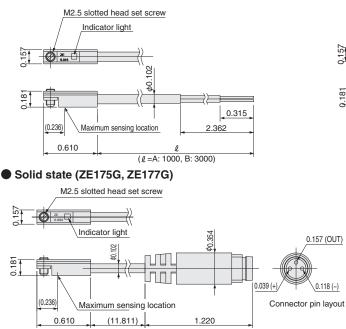
●Reed switch (ZE201□, ZE202□)

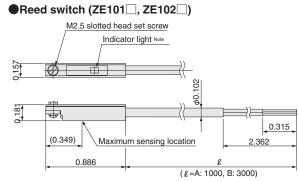


Note: Not available with the ZE201 \Box .

Horizontal lead wire

●Solid state (ZE135□, ZE155□, ZE175□, ZE137□, ZE157□, ZE177□)

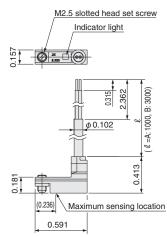




Note: Not available with the ZE101 \Box .

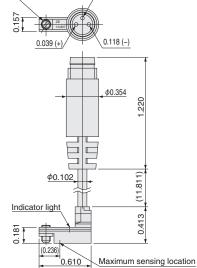
• Vertical lead wire

● Solid state (ZE235□, ZE255□, ZE275□, ZE237□, ZE257□, ZE277□)

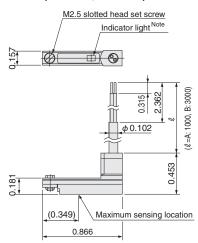


Solid state (ZE275G, ZE277G)

Connector pin layout M2.5 slotted head set screw 0.157 (OUT)



● Reed switch (ZE201 □, ZE202 □)

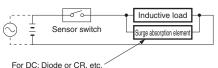


Note: Not available with the ZE201 \Box .

Contact Protection for Reed Switch Type Sensor Switch

In order to use the reed switch type sensor switch safely, take the contact protection measures listed below.

For connecting an inductive load (electromagnetic relay)



For AC: CR etc.

Diode: Forward current should be more than the circuit current, and for reverse direction, dielectric strength should be 10 times greater or more than the circuit voltage.

C: 0.01 to 0.1µF R: 1 to 4kΩ

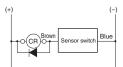
Wiring instructions for the solid state sensor switches

2-lead wire

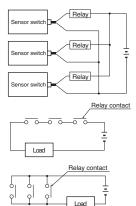
Basic connection



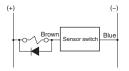
Connection to relays



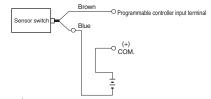
AND (series) connection and OR (parallel) connection

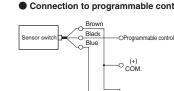


Connection to solenoid valve



Connection to programmable controller





- 1. Connect the lead wires according to their color. Incorrect wiring will cause damage to the sensor switch.
 - 2. The use of a surge protection diode is recommended with the inductive load such as an electromagnetic relay.
 - 3. Avoid the use of AND (series) connections because the circuit voltage will drop in proportion to the number of sensor switches.
 - 4. When using an OR (parallel) connection, it is possible to connect sensor switch outputs directly (ex: using corresponding black lead wires). Be aware of load return errors since current leakage increases with the number of switches.

3-lead wire with NPN output type

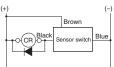
For capacitive surges

(When the lead wire length exceeds 10 m [32.808 ft])

Basic connection

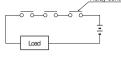


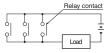
Connection to relays



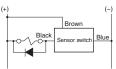
AND (series) connection and OR (parallel) connection

Relay Relay Relay insor switch Relay contact

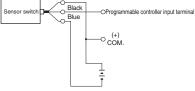




Connection to solenoid valve



Connection to programmable controller



O Programmable controller input terminal о (-) сом

Brov

Black

Connection to programmable controller

- 5. Because the sensor switches are magnetically sensitive, avoid using them in locations subject to strong external magnetic fields or bringing them in close proximity to power lines and areas where large electric currents are present. Also avoid using magnetic material for any parts used for mounting. It could result in erratic operation.
- 6. Do not excessively pull on or bend the lead wires.
- 7. Avoid using the switches in environments where chemicals or gas are present.
- 8. Consult the nearest Koganei sales office for use in environments subject to water or oil.

3-lead wire with PNP output type

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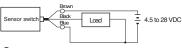
Load

Basic connection

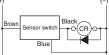
Choke coil: 1 to 5 mH

- As close as possible

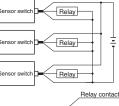
C surge suppressor

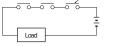


Connection to relays



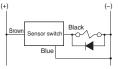
AND (series) connection and OR (parallel) connection







Connection to solenoid valve

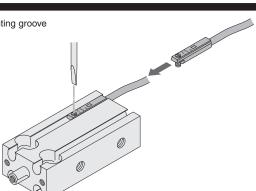


🚯 KOGANEI



Moving Sensor Switch

- Loosening the screw allows the sensor switch to be moved along the switch mounting groove of the cylinder tube.
- The tightening torque for the screws is 0.1 to 0.2 N•m [0.86 to 1.77 in•lbf].



Sensor Switch Operating Range, Response Differential, and Maximum Sensing Location

Operating range: *l*

The range from where the piston turns the switch on and the point where the switch is turned off as the piston travels in the same direction.

Response differential: C

The distance between the point where the piston turns the switch on and the point where the switch is turned off as the piston travels in the opposite direction.

Solid State	Туре												un	it: mm
Item Diameter	6	8	10	12	16	20	25	32	40	50	63	80	100	125
Operating range: ℓ	1.5 to 5 2 to 5 2 to 6 3 to 7 3 to 11													
Response differential: C		0.3 or less												
Maximum sensing location ^{Note}	sensing location ^{Nos} 6													

Note: The values in the table above are reference values. Note: The value from the opposite end of the lead wire. (shown by arrow)

				anon	,								ι	unit: in
Item	0.236	0.315	0.394	0.472	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9
Operating range: ℓ	0.059 t	0.236 0.315 0.394 0.472 0.630 0.787 0.984 1.260 1.575 1.969 2.480 3.150 3.9 4. 0.059 to 0.197 0.079 to 0.197 0.079 to 0.236 0.118 to 0.433 0.118 to 0.433												
Response ifferential: C		0.012 or less												
Maximum sensing location ^{Note}		0.236												

Note: The values in the table above are reference values. Note: The value from the opposite end of the lead wire. (shown by arrow)

 Note	
C (response differential)	OFF C (response differential) – Maximum sensing location

Reed Switch Type

Reed Switcl	п Туре									unit: mm			
Item Diameter	16	20	25	32	40	50	63	80	100	125			
Operating range: ℓ	3 to 9	to 9 4 to 12 6 to 14 7 to 18 8 to 19 8 to 24											
Response differential: C		0.3 or less											
Maximum sensing location ^{Note}	ing location ^{liste} 10												

Note: The values in the table above are reference values. Note: The value from the opposite end of the lead wire. (shown by arrow) unit: in

										unit. In		
Item	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9		
Operating range: <i>l</i>	0.118 to 0.354	0.1	57 to 0.4	172	0.236 to 0.551	0.2	76 to 0.7	709	0.315 to 0.748	0.315 to 0.945		
Response differential: C		0.012 or less										
Maximum sensing location ^{Note}		0.394										

Note: The values in the table above are reference values. Note: The value from the opposite end of the lead wire. (shown by arrow)

Two-color L	ED so	lid sta	te type	Э									un	iit: mm
Item Diameter	6	8 10 12 16 20 25 32 40 50 63 80 100 1 5 to 5												
Operating range: ℓ	1.5	1.5 to 5 2 to 6 3 to 8 4 to 12 5 to 1												5 to 12
Response differential: C		0.5 or less												
Maximum sensing location ^{Note}		6												

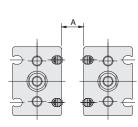
Note: The values in the table above are reference values. Note: The value from the opposite end of the lead wire. (shown by arrow) unit: in

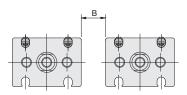
														arne. m
Item Diameter	0.236	0.315	0.394	0.472	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9
Operating range: ℓ	0.05 0.1	9 to 97	0	.079 t	o 0.23	6	0.118 to 0.315 0.157 to 0.4							0.197 to 0.472
Response differential: C		0.020 or less												
Maximum sensing location ^{Note}		0.236												

Note: The values in the table above are reference values. Note: The value from the opposite end of the lead wire. (shown by arrow)

When Mounting the Cylinders with Sensor Switches in Close Proximity

When using it connected to a cylinder, use under conditions using values greater than those shown in the table below.





Note: Install a shield plate (at least 1 mm [0.039 in] thick magnetic material) between two cylinders to use them in close proximity. However, magnetic materials cannot be used in magnetized environments.

Reed Swite	ch Type		Solid State	е Туре		Two-color	LED Solid	State Type
		unit: mm			unit: mm			unit: mm
Cylinder bore	Α	В	Cylinder bore	Α	В	Cylinder bore	Α	В
16			6			6		
20			8			8		
25			10			10		
32			12			12		
40	12	0	16			16		
50	12	0	20			20		
63			25	14	0	25	23	0
80			32	14	0	32	23	0
100			40			40		
125			50			50		
			63			63		
			80			80		
			100			100		
			125			125		
		unit: in			unit: in			unit: i
Cylinder bore	Α	В	Cylinder bore	Α	В	Cylinder bore	Α	В

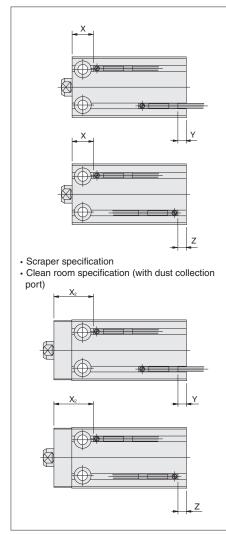
		unit: in			unit: in			unit: in
Cylinder bore	Α	В	Cylinder bore	Α	В	Cylinder bore	Α	В
0.630			0.236			0.236		
0.787			0.315			0.315		
0.984			0.394			0.394		
1.260			0.472			0.472		
1.575	0.472		0.630			0.630		
1.969	0.472	0	0.787			0.787	0.906	
2.480			0.984	0 551	0	0.984		0
3.150			1.260	0.551	0	1.260	0.906	0
3.9			1.575			1.575	1	
4.9			1.969			1.969		
			2.480			2.480		
			3.150	_		3.150		
			3.9			3.9		
			4.9			4.9		
			3.9			3.9		

• For cylinder with guide

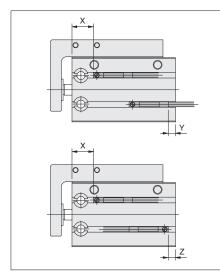
Reed Swi	itch Type	unit: mm	Solid Sta	te Type	unit: mm	Two-color	LED Solid	State Type unit: mm
Cylinder bore	Α	В	Cylinder bore	Α	В	Cylinder bore	Α	В
16			8			8		
20			12			12		
25	11	0	16			16		
32			20	23	0	20	15	0
40			25			25		
			32			32		
			40			40		

		unit: in			unit: in			unit: in
Cylinder bore	Α	В	Cylinder bore	Α	В	Cylinder bore	Α	В
0.630			0.315			0.315		
0.787			0.472			0.472		
0.984	0.433	0	0.630			0.630		
1.260			0.787	0.906	0	0.787	0.591	0
1.575			0.984			0.984		
			1.260			1.260		
			1.575			1.575		

Mounting the sensor switch in the locations shown (reference values in diagram), the sensor magnet comes to the maximum sensing location of the sensor switch at the end of the stroke.



* When the Y dimension is negative, the sensor switch protrudes from the cylinder body.



* When the Y dimension is negative, the sensor switch protrudes from the cylinder body.

Double acting type Single acting push type Single acting pull type.

Solid sta	te ty	/pe (2-	color L	ED in	cluded	I)								u	nit: mm
Item	ore	6	8	10	12	16	20	25	32	40	50	63	80	100	125
Double	х	10.5	11	11	11	12	15 (20)	16 (21)	17.5	22.5	27.5	33.5	34.5	46.5	53
	X 2	-	-	21	21	22	25 (30)	26 (31)	32.5	37.5	42.5	53.5	*54.5	*66.5	*73
acting	Υ	0	-0.5	0.5	1.5	2.5	3.5	4.5	7	9	10	12	14	18	19.5
type	z	3.5	3	4	5	6	7	8	10.5	12.5	13.5	15.5	17.5	21.5	23
Push	Х	25.5	26	26	26	27	30	31	32.5	37.5	47.5	-	-	—	-
Single	Υ	0	-0.5	0.5	1.5	2.5	3.5	4.5	7	9	10	-	-	-	—
acting type	z	3.5	3	4	5	6	7	8	10.5	12.5	13.5	-	-	-	-
Pull	х	25.5	26	26	26	27	30	31	32.5	37.5	47.5	-	-	-	-
Single	Υ	0	-0.5	0.5	1.5	2.5	3.5	4.5	7	9	10	-	-	-	-
acting type	Ζ	3.5	3	4	5	6	7	8	10.5	12.5	13.5	-	-	—	-

Note: Dimensions in () parentheses are for 5 mm dimensions for scraper specification only.

d Switch Type unit: mm															
125	100	80	63	50	40	32	25	20	16	12	10	8	6	ore	Item
49	42.5	30.5	29.5	23.5	18.5	13.5	12 (17)	11 (16)	8	-	-	-	-	Х	Double
*69	*62.5	*50.5	49.5	38.5	33.5	28.5	22 (27)	21 (26)	18	-	-	-	-	X 2	acting
16.5	15	11	9	7	6	4	1.5	0.5	-0.5	-	-	-	-	Υ	0
19	17.5	13.5	11.5	9.5	8.5	6.5	4	3	2	—	-	-	—	Ζ	type
-	—	-	-	43.5	33.5	28.5	27	26	23	—	-	—	—	Х	Push
-	—	-	-	7	6	4	1.5	0.5	-0.5	-	-	—	-	Υ	Single
-	-	-	-	9.5	8.5	6.5	4	3	2	-	-	-	-	Ζ	acting type
-	-	-	-	23.5	18.5	13.5	12	11	8	-	-	-	-	Х	Pull
-	-	-	-	27	16	14	11.5	10.5	14.5	-	-	-	-	Υ	Single
-	-	-	-	29.5	18.5	16.5	14	13	17	—	-	-	-	Ζ	acting type
	- - -	- - -	-	9.5 23.5 27	8.5 18.5 16	6.5 13.5 14	4 12 11.5	3 11 10.5	2 8 14.5	-	-	-	-	Z X Y	acting type Pull Single

Note: Dimensions in () parentheses are for 5 mm stroke models.* * Indicates dimensions for scraper specification only.

Double acting double rod end type

Solid state type (2-color LED included)

Solid sta	te ty	/pe (2-	color l	ED in	cluded)								u	nit: mm
Bore 6 8 10 12 16 20 25 32 40 50 63 80 100 125														125	
Double	Х	10.5	11	11	11	12	15	16	17.5	22.5	27.5	33.5	34.5	46.5	53
acting	Υ	4	4.5	5.5	6.5	7.5	8.5	9.5	12	14	20	22	24	18	19.5
type	Ζ	7.5	8	9	10	11	12	13	15.5	17.5	23.5	25.5	27.5	21.5	23

Reed Swi	tch ⁻	Туре												u	nit: mm
Item	ore	6	8	10	12	16	20	25	32	40	50	63	80	100	125
Double	Х	-	-	-	-	8	11	12	13.5	18.5	23.5	29.5	30.5	42.5	49
acting	Υ	-	-	-	—	4.5	5.5	6.5	9	11	17	19	21	15	16.5
type	Ζ	-	-	_	-	7	8	9	11.5	13.5	19.5	21.5	23.5	17.5	19

Double acting type with guide

Solid State Type

Solid Sta	colid State Type unit: mm									
Item	ore	8	12	16	20	25	32	40		
Double	Х	11 (16)	11 (16)	12 (17)	15 (20)	16 (21)	17.5 (22.5)	22.5 (27.5) (32.5 for stroke 10 only)		
acting	Υ	-0.5	1.5	2.5	3.5	4.5	12	14		
type	Ζ	3	5	6	7	8	15.5	17.5		

Note: Dimensions in () parentheses are for mid-stroke models (stroke 5, 15, 25, 35, 45, and 55).

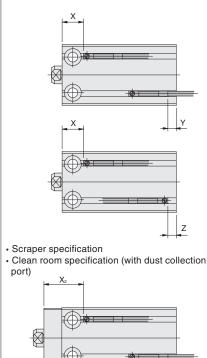
Beed Switch Type

Reed Swi	itch	Туре						unit: mm
Item	ore	8	12	16	20	25	32	40
Double	Х	_	—	8 (13)	11 (16)	12 (17)	13.5 (18.5)	18.5 (23.5) (28.5 for stroke 10 only)
acting	Υ	—	—	-0.5	0.5	1.5	9	11
type	Z	-	-	2	3	4	11.5	13.5

Note: Dimensions in () parentheses are for mid-stroke models (stroke 5, 15, 25, 35, 45, and 55).

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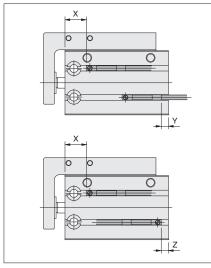
Mounting the sensor switch in the locations shown (reference values in diagram), the sensor magnet comes to the maximum sensing location of the sensor switch at the end of the stroke.



Υ

Ζ

* When the Y dimension is negative, the sensor switch protrudes from the cylinder body.



* When the Y dimension is negative, the sensor switch protrudes from the cylinder body.

Solid state type (2-color LED included)

Solid stat	Solid state type (2-color LED included) unit:										unit: in				
Item	ore	0.236	0.315	0.394	0.472	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9
Double	x	0.413	0.433	0.433	0.433	0.472	0.591 (0.787)	0.630 (0.827)	0.689	0.886	1.083	1.319	1.358	1.831	2.087
acting	X 2	-	-	0.827	0.827	0.866	0.984 (1.181)	1.024 (1.220)	1.280	1.476	1.673	2.106	*2.146	*2.618	*2.874
type	Υ	0	-0.020	0.020	0.059	0.098	0.138	0.177	0.276	0.354	0.394	0.472	0.551	0.709	0.768
	z	0.138	0.118	0.157	0.197	0.236	0.276	0.315	0.413	0.492	0.531	0.610	0.689	0.846	0.906
Push	X	1.004	1.024	1.024	1.024	1.063	1.181	1.220	1.280	1.476	1.870	-	-	-	-
Single	Y	0	-0.020	0.020	0.059	0.098	0.138	0.177	0.276	0.354	0.394	-	-	-	-
acting type	z	0.138	0.118	0.157	0.197	0.236	0.276	0.315	0.413	0.492	0.531	-	-	-	-
Pull	х	1.004	1.024	1.024	1.024	1.063	1.181	1.220	1.280	1.476	1.870	-	-	-	-
Single	Y	0	-0.020	0.020	0.059	0.098	0.138	0.177	0.276	0.354	0.394	-	-	-	-
acting type	Z	0.138	0.118	0.157	0.197	0.236	0.276	0.315	0.413	0.492	0.531	-	-	-	-

Note: Dimensions in () parentheses are for 0.197 in stroke models.* * Indicates dimensions for scraper specification only.

Reed Switch Type

unit: in

unit: in

lore	0.236	0.315	0.394	0.472	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9
x	-	-	-	-	0.315	0.433 (0.630)	0.472 (0.669)	0.531	0.728	0.925	1.161	1.201	1.673	1.929
X 2	-	-	-	-	0.709	0.827 (1.024)	0.866 (1.063)	1.122	1.319	1.516	1.949	*1.988	*2.461	*2.717
Υ	-	-	-	-	-0.020	0.020	0.059	0.157	0.236	0.276	0.354	0.433	0.591	0.650
z	-	-	-	-	0.079	0.118	0.157	0.256	0.335	0.374	0.453	0.531	0.689	0.748
X	-	-	-	-	0.906	1.024	1.063	1.122	1.319	1.713	-	-	-	-
Υ	-	-	-	-	-0.020	0.020	0.059	0.157	0.236	0.276	-	-	-	-
z	-	-	-	-	0.079	0.118	0.157	0.256	0.335	0.374	-	-	-	-
X	-	-	-	-	0.315	0.433	0.472	0.531	0.728	0.925	-	-	-	-
Υ	-	-	-	-	0.571	0.413	0.453	0.551	0.630	1.063	_	-	-	-
z	-	-	-	-	0.669	0.512	0.551	0.650	0.728	1.161	-	-	-	-
	X X2 Y Z X Y Z X Y	X – X2 – Y – Z – X – Y – Z – X – X – Y – Y –	X - - X2 - - Y - - Z - - X - - Y - - X - - X - - X - - X - - Y - - Y - -	X - - - X2 - - - Y - - - Z - - - X - - - Y - - - X - - - Y - - - X - - - X - - - Y - - -	X - - - - X2 - - - - Y - - - - Z - - - - Z - - - - Y - - - - X - - - - Y - - - - X - - - - X - - - - Y - - - -	X - - - - 0.315 X2 - - - 0.709 Y - - - 0.709 Y - - - 0.020 Z - - - 0.079 X - - - 0.079 X - - - 0.020 Z - - - 0.020 X - - - 0.0315 Y - - - 0.571	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	X - - - - 0.315 0.433 (0.639) 0.472 (0.639) 0.531 0.728 0.925 1.161 1.201 1.673 X2 - - - - 0.315 0.433 (0.639) 0.472 (0.639) 0.531 0.728 0.925 1.161 1.201 1.673 X2 - - - - 0.709 0.827 (1.024) 0.866 (1.024) 1.122 1.319 1.516 1.949 *1.988 *2.461 Y - - - - 0.070 0.128 0.157 0.236 0.276 0.354 0.433 0.591 Z - - - 0.079 0.118 0.157 0.236 0.276 0.354 0.433 0.591 X - - - 0.079 0.118 0.157 0.236 0.276 0.354 0.433 0.689 X - - - 0.020 0.020 0.059 0.157 </td						

Note: Dimensions in () parentheses are for 0.197 in stroke models.** Indicates dimensions for scraper specification only.

Double acting double rod end type

Solid state type (2-color LED included)

Item	ore	0.236	0.315	0.394	0.472	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9
Double	Х	0.413	0.433	0.433	0.433	0.472	0.591	0.630	0.689	0.886	1.083	1.319	1.358	1.831	2.087
acting	Υ	0.157	0.177	0.217	0.256	0.295	0.335	0.374	0.472	0.551	0.787	0.866	0.945	0.709	0.768
type	Ζ	0.295	0.315	0.354	0.394	0.433	0.472	0.512	0.610	0.689	0.925	1.004	1.083	0.846	0.906

Reed Switch Type

Reed Swi	itch	Туре													unit: in
Item	ore	0.236	0.315	0.394	0.472	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9
Double	X	-	—	-	-	0.315	0.433	0.472	0.531	0.728	0.925	1.161	1.201	1.673	1.929
acting	Y	-	-	-	-	0.177	0.217	0.256	0.354	0.433	0.669	0.748	0.827	0.591	0.650
type	Z	-	—	-	-	0.276	0.315	0.354	0.453	0.531	0.768	0.846	0.925	0.689	0.748

Double acting type with guide

Solid State Type

Solid Sta	colid State Type unit: in								
Item	ore	0.315	0.472	0.630	0.787	0.984	1.260	1.575	
Double	x	0.433	0.433	0.472	0.591	0.630	0.689	0.886(1.083) (1.280 for stroke 0.394 only)	
	^	(0.630)	(0.630)	(0.669)	(0.787)	(0.827)	(0.886)	0.880(1.083) (1.200 IOI SITOKE 0.394 OIIIy)	
acting	Υ	-0.020	0.059	0.098	0.138	0.177	0.472	0.551	
type	Z	0.118	0.197	0.236	0.276	0.315	0.610	0.689	

Note: Dimensions in () parentheses are for mid-stroke models (stroke 0.197, 0.591, 0.984, 1.378, 1.772, and 2.165).

Pood Switch Type

neeu Swi	lich	Type						unit: in
Item	ore	0.315	0.472	0.630	0.787	0.984	1.260	1.575
Double	x	_	_	0.315 (0.512)	0.433 (0.630)	0.472 (0.669)	0.531 (0.728)	0.728(0.925) (1.122 for stroke 0.394 only)
acting	Υ	-	-	-0.020	0.020	0.059	0.354	0.433
type	z	_	_	0.079	0.118	0.157	0.453	0.531

Note: Dimensions in () parentheses are for mid-stroke models (stroke 0.197, 0.591, 0.984, 1.378, 1.772, and 2.165).

MEMO

Limited Warranty

KOGANEI CORP. warrants its products to be free from defects in material and workmanship subject to the following provisions.

Warranty Period	The warranty period is 180 days from the date of delivery.
Koganei Responsibility	If a defect in material or workmanship is found during the warranty period, KOGANEI CORP. will replace any part proved defective under normal use free of charge and will provide the service necessary to replace such a part.
Limitations	• This warranty is in lieu of all other warranties, expressed or implied, and is limited to the original cost of the product and shall not include any transportation fee, the cost of installation or any liability for direct, indirect or consequential damage or delay resulting from the defects.

- KOGANEI CORP. shall in no way be liable or responsible for injuries or damage to persons or property arising out of the use or operation of the manufacturer's product.
- This warranty shall be void if the engineered safety devices are removed, made inoperative or not periodically checked for proper functioning.
- Any operation beyond the rated capacity, any improper use or application, or any improper installation of the product, or any substitution upon it with parts not furnished or approved by KOGANEI CORP., shall void this warranty.
- This warranty covers only such items supplied by KOGANEI CORP. The products of other manufacturers are covered only by such warranties made by those original manufacturers, even though such items may have been included as the components.

The specifications are subject to change without notice.

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