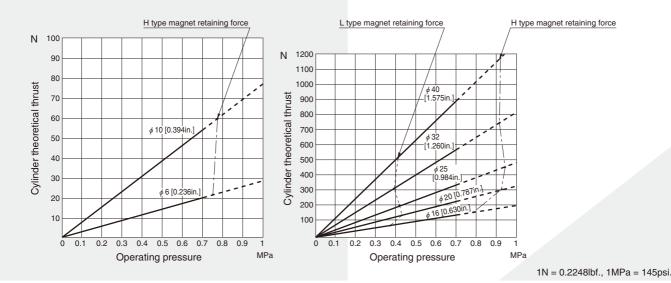
# Magnet Type Rodless Cylinders

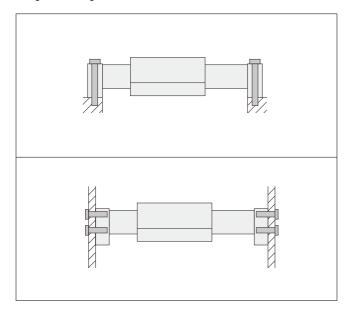
We promise strong retaining force and stable operation because of the neodymium rare earth magnet being used.



## MRC (Basic type)

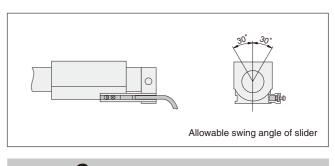
#### **1.** The installation is easy.

The end cover can be installed directly as the block type, without using a mounting bracket.



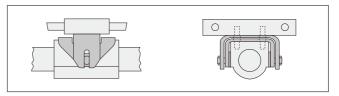
#### **2.** The sensor switch can be used.

The end of the stroke position can be easily detected in the H types by just installing a sensor switch, except for bore size 6mm [0.236in.].



#### **3.** Installation of M mount

M mount which eliminates excessive load by moment is optional. When M mount is used, compensating misalignment and smooth operation becomes possible.



#### Wide product range saves space and simplifies operations Bore size : $\phi 6$ [0.236in.], $\phi 10$ [0.394in.], $\phi 16$ [0.630in.], $\phi 20$ [0.787in.], $\phi 25$ [0.984in.], $\phi 32$ [1.260in.], and $\phi 40$ [1.575in.]



### $MRG_{\langle With guide \rangle}$

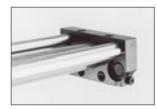
### **1.** Durability is increased, and guides have been used to enable heavy load capacity.

The load, which applied to the cylinder tube, is distributed to 2 guide shafts. A heavy load capacity (490.3N [110.2lbf.] or less for  $\phi$  40 [1.575in.]) and a large allowable moment are obtained.



#### **2.** The stroke can be finely adjusted.

The stroke can be finely adjusted with the stroke adjusting bolt within the range of  $+1 \sim -6$ mm [ $+0.039 \sim -0.236$ in.] for one side.



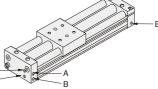
### **3.** It is possible to install a double rod type shock absorber.

A double rod type shock absorber which can be installed in the slider is optional. With multi orifice type operation, which needs no adjustment, the shock is smoothly absorbed.



#### **4.** Concentrated piping on one side

Concentrated piping on one side is possible on the end surface or the side as shown in the diagram to the right. Moreover, the piping location can be selected according to installation requirements because there are many connection ports.



#### **5.** Sensor switches can be used.

The magnet for the sensor switch and the mounting rail are standard equipment. Many kinds of small sized sensor switches can be attached.



# MRG With Guide Symbol • MRCH6 cannot be used in vertical applications.

#### **Specifications**

E	Bore size mm [in.]	6 [0.236]	10 [0.394]	16 [0.630]	20[0.787]	25[0.984]	32 [1.260]	40 [1.575]				
Item		0 [0.200]	10 [0:004]	10 [0.000]	20[0:101]	02 [1.200]	40[1.070]					
Operation type		Double acting type										
Media					Air							
Operating pressure	H type	0.25~ [36~				0.2~0.7 [29~102]						
range MPa [psi.]	L type	_	_			0.18~0.34 [26~49]						
Proof pressure	MPa [psi.]											
Operating temperature	range °C [°F]				0~60 [32~140]							
Operating speed range Not	e mm/s [in./sec.]			1(	00~500 [3.9~19	.7]						
Cushion			Rubber bumper									
Lubrication			Not required									
Stroke adjusting range	mm [in.]			+1~-6 [+0.039~-0.236] (One side) (Fine adjustment at the end of the stroke only)								
Stroke tolerance	1000 or less	$+1.5 \begin{bmatrix} +0.059\\ 0 \end{bmatrix}$										
mm [in.]	1001~1500				$+2.0 \begin{bmatrix} +0.079 \\ 0 \end{bmatrix}$							
Port size			M5×0.8			Rc1/8		Rc1/4				

Note: Adjust the maximum operating speed at 300mm/s [11.8in./sec.] or less when you use the sensor switch for the intermediate positioning because of the response speed of the load relay, etc. Remark: For details of the sensor switches, see p.1544.

#### **Magnet Retaining Force**

							N [lbf.]
Bore size mm [in.] Type		10 [0.394]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]	40 [1.575]
H type	20.6 [4.63]	58.8 [13.21]	156.9 [35.27]	294.2 [66.14]	451.1 [101.41]	715.9 [160.93]	1147.4 [257.94]
L type	—	—	73.5 [16.52]	127.5 [28.66]	196.1 [44.08]	313.8 [70.54]	500.1 [112.42]

Remark: Bore size 6mm [0.236in.] and 10mm [0.394in.] are only available in H type.

#### **Bore Size and Stroke**

		mm
Bore size	Standard strokes	Available stroke range
6	50, 100, 150, 200	0~300
10	50, 100, 150, 200, 250, 300	0~500
16	100, 150, 200, 250, 300, 350, 400, 450, 500	0~750
20	150, 200, 250, 300, 350, 400, 450, 500, 600	0~1000
25	200, 250, 300, 350, 400, 450, 500, 600, 700, 800	0~1500
32	200, 250, 300, 350, 400, 450, 500, 600, 700, 800	0~1500
40	200, 250, 300, 350, 400, 450, 500, 600, 700, 800, 900, 1000	0~1500

#### Specifications of Shock Absorber (Optional)

	Model	KSHDM	KSHDM	KSHDM	KSHDM	KSHDM	KSHDM	KSHDM	
Item		5×6	5×8	5×10	6×10	8×12	10×15	12×18	
Applicable cylinder		MRGH6	MRGH10	MRG 16	MRG 20	MRG 25	MRG 32	MRG 40	
Maximum absorption	J [ft⋅lbf]	0.5 [0.37]	1.0 [0.74]	2.5 [1.84]	3.9 [2.88]	5.9 [4.35]	13.3 [9.81]	26.5 [19.55]	
Absorbing stroke	mm [in.]	6 [0.236]	8 [0.315]	10 [0.394]	10 [0.394]	12 [0.472]	15 [0.591]	18 [0.709]	
Maximum impact speed mr	n/s [in./sec.]			·	800 [31.5]		•	•	
Maximum operating frequency	y cycle/min				60				
Spring return forceNote	N [lbf.]	4.9 [1.10]	7.8 [1.75]	6.9 [1.55]	6.9 [1.55]	19.6 [4.41]	14.7 [3.30]	16.7 [3.75]	
Angle variation		2° or less							
Operating temperature ran	ge °C [°F]	F] 0~60 [32~140]							

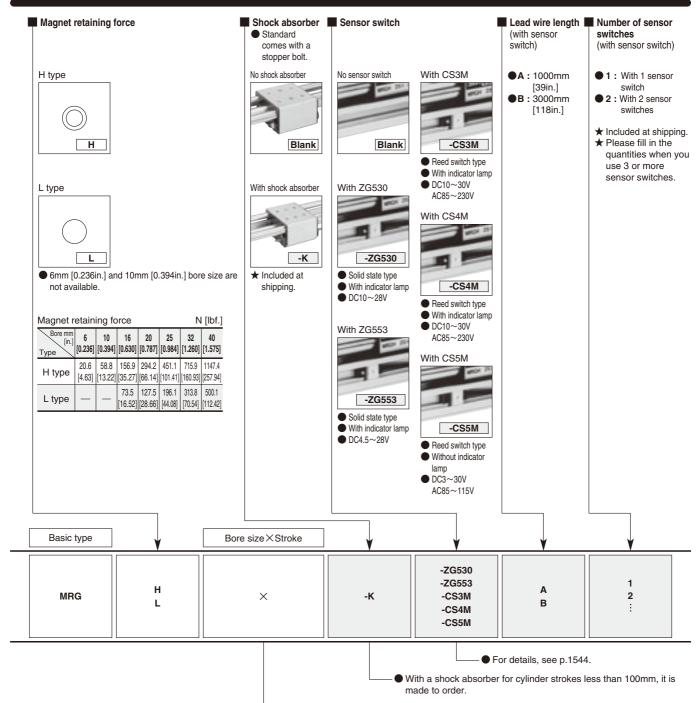
Note : The value at retracted position.

Caution: The life of the shock absorber may vary from the magnet type rodless cylinder, depending on its operating conditions.

#### Mass

					kg [lb.]			
Bore size	Zero stro	oke mass	Additional mass for	Additional mass				
mm [in.]	2010 0410		each 1mm [0.0394in.]	Shock absorber	One sensor switch (with holder)			
	H type	L type	stroke	Shock absorber	One sensor switch (with holder)			
6 [0.236]	0.26 [0.57]	—	0.0007 [0.0015]	0.015 [0.033]				
10 [0.394]	0.47 [1.04]	—	0.0016 [0.0035]	0.027 [0.060]				
16 [0.630]	0.77 [1.70]	0.71 [1.57]	0.0023 [0.0051]	0.033 [0.073]				
20 [0.787]	1.27 [2.80]	1.22 [2.69]	0.0032 [0.0071]	0.055 [0.121]	A : 0.05 [0.11]			
25 [0.984]	1.67 [3.68]	1.61 [3.55]	0.0040 [0.0088]	0.086 [0.190]	B: 0.09 [0.20]			
32 [1.260]	3.11 [6.86]	3.00 [6.62]	0.0060 [0.0132]	0.166 [0.366]				
40 [1.575]	5.20 [11.47]	4.88 [10.76]	0.0090 [0.0198]	0.225 [0.496]				

#### **Order Codes**



See the "Bore Size and Stroke" table on the previous page.

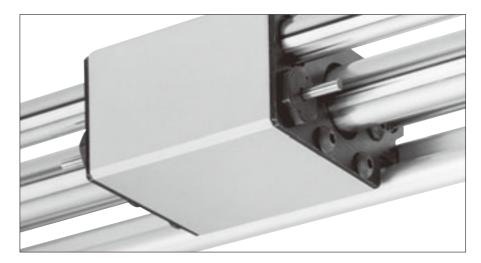
#### **Additional Parts** (To be Ordered Separately)

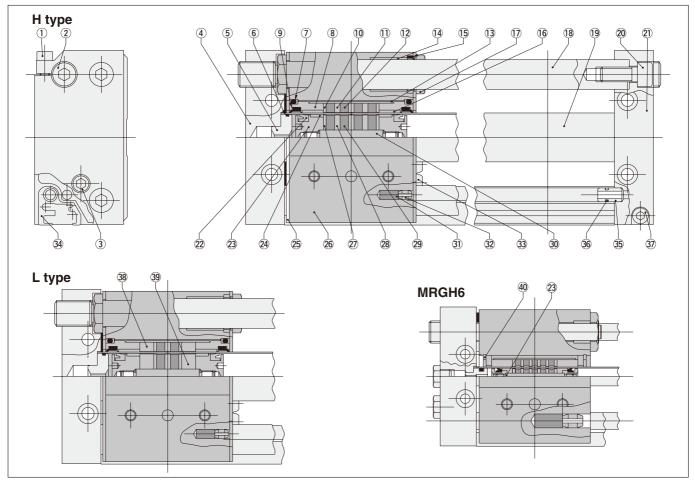
Shock absorber



For φ 6 [0.236in.] cylinder -KSHDM 5 $\times$ 6 For \$\phi\$ 10 [0.394in.] cylinder -KSHDM 5×8 For \$\overline{4}\$ 16 [0.630in.] cylinder -KSHDM 5×10 For \$\overline{4}\$ 20 [0.787in.] cylinder -KSHDM 6×10 For \$\u00e9 25 [0.984in.] cylinder -KSHDM 8×12 For \$\$\phi\$ 32 [1.260in.] cylinder -KSHDM 10×15 For  $\phi$  40 [1.575in.] cylinder — KSHDM 12×18 Note: Mounting nut is not included, please use the

mounting nut of the stopper bolt (common parts) to install.



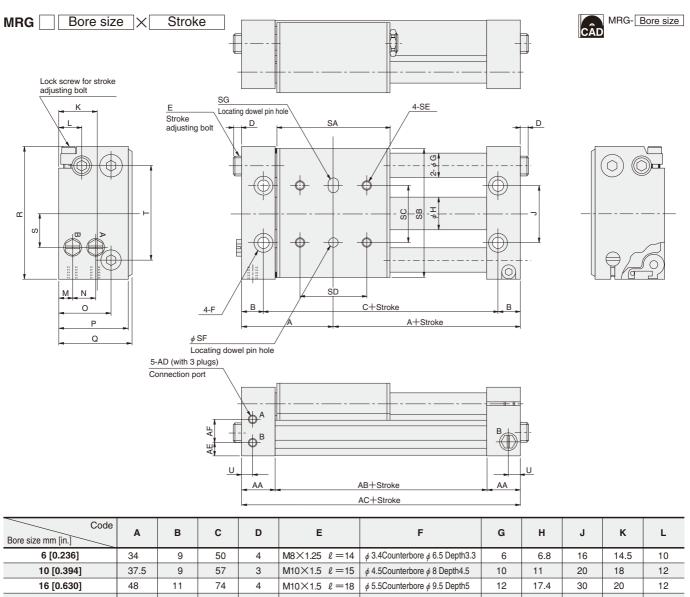


#### **Major Parts and Materials**

No.	Parts	Materials	Quantity	Remarks
	Lock screw for	All		Hexagon socket
1	stroke adjusting bolt	Alloy steel	2	head bolt
2	Stroke adjusting bolt	Alloy steel	2	
3	Plug	Steel	3	
	E I DIVISI	Aluminum alloy		
4	End cover R <sup>Note1</sup>	(anodized)	1	
5	End pipe	Aluminum alloy	2	
6	Cylinder gasket	Synthetic rubber (NBR)	2	
7	Slider gasket	Synthetic rubber (NBR)	2	Not available in $\phi$ 6 [0.236in.]
	Canan an halden	Aluminum alloy	_	Steel for $\phi$ 6
8	Scraper holder	(anodized)	2	[0.236in.]
9	Scraper	Synthetic rubber (NBR)	2	
10	Outer yoke B	Steel (nickel plated)	2	
1	Outer yoke A	Steel (nickel plated)	3	1 pc. for L type (4 for $\phi$ 6 and 2 for $\phi$ 10)
12	Outer magnet	Rare earth magnet	4	2 pcs. for L type (5 for $\phi$ 6 and 3 for $\phi$ 10)
13	Slider tube	Stainless steel	1	
(14)	Bushing	PTFE layer with	4	
	Dushing	filling material	-	
15	Scraper	Synthetic rubber (NBR)	4	Not available in $\phi$ 6 [0.236in.]
16	Bushing	Special plastic	2	
17	Stopper bolt	Carbon steel	1	Shock absorber (Optional)
(18)	Guide shaft	Carbon steel	2	
0	Guide shan	(hard chrome plated)	2	
(19)	Culinder tube	Aluminum alloy	4	Stainless steel for
(19)	Cylinder tube	(anodized)	1	$\phi$ 6, $\phi$ 10 and $\phi$ 16
20	Guide shaft mounting screw	Alloy steel	3	Hexagon socket head bolt
(21)	End cover LNote2	Aluminum alloy	4	
(ZI)	End cover Livez	(anodized)	1	

No.	Parts	Materials	Quantity	Remarks
22	Piston seal	Synthetic rubber (NBR)	1	
23	Piston	Aluminum alloy	2	Brass for $\phi$ 6 piston
24	Inner wear ring	Special plastic	2	
(25)	0	Steel	2	Not available in
(2)	Scraper plate	(phosphate coating)	2	φ 6 [0.236in.]
	Olivia	Aluminum alloy	_	
26	Slider	(anodized)	1	
27	Inner yoke B	Steel (nickel plated)	2	
28	Inner yoke A	Steel (nickel plated)	3	1 pc. for L type (4 for $\phi$ 6 and 2 for $\phi$ 10)
29	Inner magnet	Rare earth magnet	4	2 pcs. for L type (5 for $\phi$ 6 and 3 for $\phi$ 10)
30	Shaft	Stainless steel	1	
	Magnet for sensor		_	
31)	switch	Rare earth magnet	1	
32	Magnetic holder	Plastic	1	
	Scraper plate		_	Hexagon socket head bolt,
33	mounting screw	Alloy steel	6	brass for $\phi$ 6 [0.236in.]
	Sensor switch	Aluminum alloy		Also used as
34)	mounting rail	(anodized)	1	bypass pipe
35	Pipe	Aluminum alloy	2	
36	Pipe gasket	Synthetic rubber (NBR)	2	
37	Pipe mounting screw	Alloy steel	1	Hexagon socket head bolt
38	Outer spacer	Aluminum alloy	2	L type only
39	Inner spacer	Aluminum alloy	2	L type only
40	Snap ring	Steel	2	

Notes: 1. This is the side where concentrated piping can be done. 2. When looking the sensor rail front, this is the right sided one.



Code	м	N	ο	Р	Q	R	SNote	т	U	AA	AB	AC	A	D
40 [1.575]	76.5	19	115	4	M20×2.5	5 l=25	¢9Counte	rbore ø 14 [	Depth8.5	25	41.6	65	37.5	24
32 [1.260]	68.5	16	105	2	M18×2.5		1	rbore $\phi$ 14 [		20	33.6	50	31	20
25 [0.984]	57	14	86	4	M14×2	ℓ=20	φ 6.6Coun	terbore $\phi$ 11	Depth6.5	16	26.4	40	26	16
20 [0.787]	52.5	13	79	3	M12×1.7	75 ℓ =19	φ 5.5Coun	terbore $\phi$ 9.	5 Depth5.5	14	21.4	35	24	15
16 [0.630]	48	11	74	4	M10×1.5	5 l=18	φ 5.5Coun	terbore φ 9.	5 Depth5	12	17.4	30	20	12
10 [0.394]	37.5	9	57	3	M10×1.5	5 l=15	φ 4.5Coun	terbore φ 8	Depth4.5	10	11	20	18	12
6 [0.236]	34	9	50	4	11/18 × 1.25	$\ell = 14$	φ 3.400un	terbore $\phi$ 6.	5 Depth3.3	6	6.8	16	14.5	10

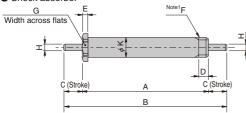
Bore size mm [in.]	М	N	0	Р	Q	R	SNote	Т	U	AA	AB	AC	AD
6 [0.236]	6	8.5	22	26	27	50	11	32	5	13	42	68	M5×0.8
10 [0.394]	6	11.5	26	33	34	60	16	44	5	14	47	75	M5×0.8
16 [0.630]	7	12	27	36	38	70	18	50	5.5	17	62	96	M5×0.8
20 [0.787]	8	14.5	33	44	46	84	23	60	7.5	19	67	105	Rc1/8
25 [0.984]	8.5	16.5	36	48	50	94	25	68	7.5	21	72	114	Rc1/8
32 [1.260]	10	20	44	58	60	116	32	85	8	25	87	137	Rc1/8
40 [1.575]	12	24	52	70	72	140	41	102	10	28	97	153	Rc1/4

Note : The distance to the connection port 'A' of MRGH6 is 0.

Code Bore size mm [in.]	AE	AF	SA	SB	SC	SD	SE	SF	SG
6 [0.236]	6	10.5	40	48	20	20	M4×0.7 Depth7		4 $^{+0.1}_{0}$ $\times$ 6 (Oval shape) Depth4
10 [0.394]	6	11.5	45	59	25	25	M4×0.7 Depth7		4 $^{+0.1}_{0}$ $\times$ 6 (Oval shape) Depth4
16 [0.630]	7	12	60	68	30	35	M5×0.8 Depth8	ø 5H8 Depth5	5 $^{+0.1}_{0}$ $\times$ 7 (Oval shape) Depth5
20 [0.787]	8	14.5	65	82	36	38	M5×0.8 Depth9	ø 5H8 Depth5	5 $^{+0.1}_{0}$ $ imes$ 7 (Oval shape) Depth5
25 [0.984]	8.5	16.5	70	92	42	40	M6×1 Depth10		$6^{+0.1}_{0} \times 8$ (Oval shape) Depth6
32 [1.260]	10	20	85	114	52	50	M8×1.25 Depth14		8 $^{+0.1}_{0}$ $\times$ 10 (Oval shape) Depth8
40 [1.575]	12	24	95	138	62	55	M8×1.25 Depth16		8 $^{+0.1}_{0}$ $\times$ 10 (Oval shape) Depth8

#### **Additional Parts**

#### Shock absorber



		-							mm [in.]
Code	Α	В	с	D	F	G	Н	к	E
<b>KSHDM5</b> × <b>6</b> (For <i>ϕ</i> 6 [0.236])	46	58	6	5	M8×1	12	2.5	8 <sup>-0.03</sup> -0.17	2.8
<b>KSHDM5</b> × <b>8</b> (For $\phi$ 10 [0.394])	51	67	8	5	M10×1	14	3	10 <sup>-0.03</sup> -0.18	2.8
<b>KSHDM5</b> ×10 (For $\phi$ 16 [0.630])	66	86	10	5	M10×1	14	3	10 <sup>-0.03</sup> -0.18	2.8
<b>KSHDM6</b> ×10 (For $\phi$ 20 [0.787])	73	93	10	7	M12×1	17	3	12 <sup>-0.04</sup> -0.19	3.8
<b>KSHDM8</b> ×12 (For $\phi$ 25 [0.984])	80	104	12	8	M14×1.5	19	5	14 <sup>-0.04</sup> -0.21	4.8
<b>KSHDM10</b> ×15 (For <i>ϕ</i> 32 [1.260])	99	129	15	10	M18×1.5	22	5	18 <sup>-0.05</sup>	6.8
<b>KSHDM12</b> × <b>18</b> (For <i>ϕ</i> 40 [1.575])	109	145	18	10	M20×1.5	24	5	20 <sup>-0.05</sup> -0.22	6.8

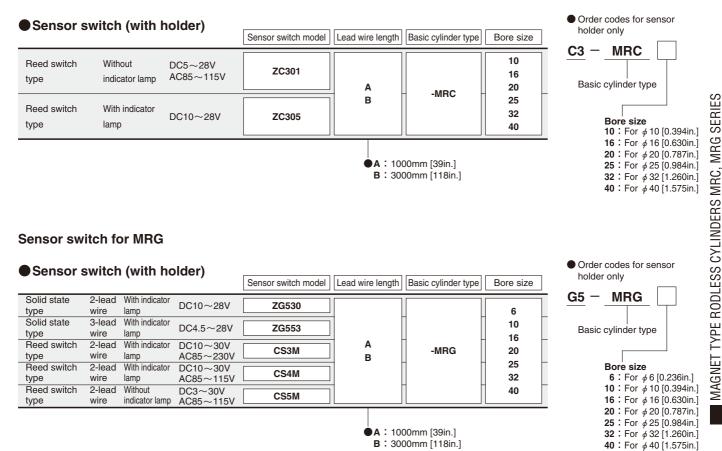
Notes: 1. Mounting nut is not included, use the mounting nut of the stopper bolt (common parts) to install. 2. Tightening torque of the nut when installing the shock absorber should not be exceeding the value of the table below.

	N⋅cm [in⋅lbf]
Model	Tightening torque
KSHDM5×6	196 [17.3]
KSHDM5×8	588 [52.0]
KSHDM5×10	588 [52.0]
KSHDM6×10	1177 [104.2]
KSHDM8×12	1569 [138.9]
KSHDM10×15	1961 [173.6]
KSHDM12×18	2942 [260.4]

Solid State Type, Reed Switch Type

#### **Order Codes for Sensor Switch**

Sensor switch for MRC (Not available in MRC6)

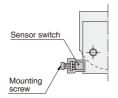


• For details of the sensor switches, see p.1544.

#### **Moving Sensor Switch**

#### For MRC

Loosening the mounting screw allows the sensor switch to be moved freely in the cylinder's axial direction. Tighten the mounting screw with a tightening torque of 0.2N·m [1.8in·lbf].



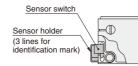
#### • For MRG

Loosening the sensor holder mounting screw (screw size M3) with an Allen wrench (nominal size 1.5) allows the sensor switch to be moved in the direction of the stroke.

(Tightening torque should be 0.2N·m [1.8in·lbf].)

#### ●MRG6~16

#### ●MRG20~40



Sensor switch Sensor holder (3 lines for identification mark)

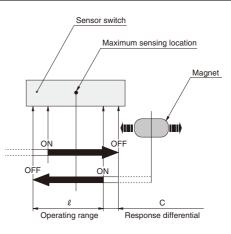
#### Sensor Switch Operating Range, Response Differential, and Maximum Sensing Location

#### • Operating range: *l*

The distance the piston travels in one direction, while the switch is in the ON position.

#### Response differential: C

The distance between the point where the piston turns the switch ON and the point where the switch is turned OFF as the piston travels in the opposite direction.



mm [in.]

#### MRC (Basic type)

Sensor switch model	ZC301 🗌, ZC305 🗌								
Bore size	10 [0.394]         16 [0.630]         20 [0.787]         25 [0.984]         32 [1.260]         40 [1.57]								
Operating range: <i>l</i>	4.3~6.8 [0.169~0.268]	4.2~7.0 [0.165~0.276]	6.0~9.3 [0.236~0.366]	5.5~8.5 [0.217~0.335]	7.0~9.6 [0.276~0.378]	8.3~11.2 [0.327~0.441]			
Response differentialNote1: C	1.3 [0.051] or less	1.5 [0.059] or less	1.2 [0.047] or less						
Maximum sensing locationNote2			ZC301:7[0.276]	ZC305: 10.5 [0.413]					

Remark: The values in the above table are reference values.

Notes: 1. These are values at the ambient temperature of 25°C [77°F].

2. They are values measured from the end of the sensor switch.

•MRG (with guide)					
Sensor switch model	ZG530 🗌, ZG553 🗌				
Operating range: <i>l</i>	3.0~5.0 [0.118~0.197]	5~9.8 [0.197~0.386]			
Response differentialNote1: C	0.7 [0.028] or less	1.5 [0.059] or less			
Maximum sensing locationNote2	11 [0.433]				

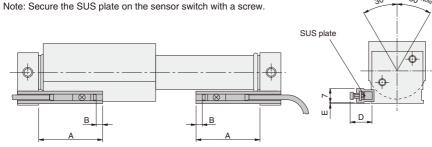
Remark : The values in the above table are reference values.

Notes: 1. These are values at the ambient temperature of 25°C [77°F].

This is the length measured from the switch's opposite end side to the lead wire.

#### For MRC

When the sensor switch is mounted in the locations shown below (the A and B dimensions in the table are reference values), the magnet comes to the maximum sensing location of the sensor switch at the end of the stroke.





Note: This is the allowable swing angle of the slider at the end of the stroke.

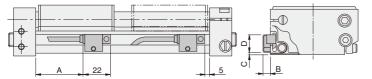
H type mm								
Cylinder model	Sensor switch	Code						
Cylinder model	model	Α	В	D	E			
MRCH10	ZC301	28	3.5 [0.138]	12 [0.472]	0.2 [0.008]			
MILCITIO	ZC305	[1.102]	0					
MRCH16	ZC301	33	3.5 [0.138]	11.5 [0.453]	0.5 [0.020]			
WHCHTO	ZC305	[1.299]	0					
MRCH20	ZC301	36	3.5 [0.138]	11.5 [0.453]	2.5 [0.098]			
WINCH 20	ZC305	[1.417]	0					
MRCH25	ZC301	39	3.5 [0.138]	11.5	1.5 [0.059]			
WINGI125	ZC305	[1.535]	0	[0.453]				
MRCH32	ZC301	43.5	3.5 [0.138]	10.5	4.5			
WINCH32	ZC305	[1.713]	0	[0.413]	[0.177]			
MRCH40	ZC301	49	3.5 [0.138]	11.5	5.5			
WINCH40	ZC305	[1.929]	0	[0.453]	[0.217]			

Notes: 1. Sensor switch cannot be used for L type and **MRCH6**. 2. The intermediate stroke position cannot be detected with a sensor switch.

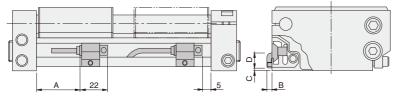
#### For MRG

When the sensor switch is mounted in the locations shown below, the magnet comes to the maximum sensing location of the sensor switch at the end of the stroke.

●MRG6~16



●MRG20~40



H type and L type mm [in.] Code в С Α D Cylinder mode MRGH6 6 [0.236] 2 [0.079] 13.5 [0.531] 16 [0.630] MRGH10 21 [0.827] 6 [0.236] 2 [0.079] 13.5 [0.531] MRG 16 35 [1.378] 6 [0.236] 2.5 [0.098] 13.5 [0.531] MRG 20 40 [1.575] 4.5 [0.177] 1 [0.039] 11 [0.433] MRG 25 45 [1.772] 4.5 [0.177] 2.5 [0.098] 11 [0.433] MRG 32 60 [2.362] 3.5 [0.138] 7.5 [0.295] 11 [0.433] MRG 40 70 [2.756] 3.5 [0.138] 11.5 [0.453] 11 [0.433]

If the stroke in the cylinder is less than the figures in the table below, the intermediate stroke position can be detected with a sensor switch.

Maximum	stroke	that	enables	detection	of	intermediate	stroke
positions							mm [in.]

Bore size	6 [0.236]	10 [0.394]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]	40 [1.575]
Stroke	300	500	750	750	800	800	800

MRG-SW

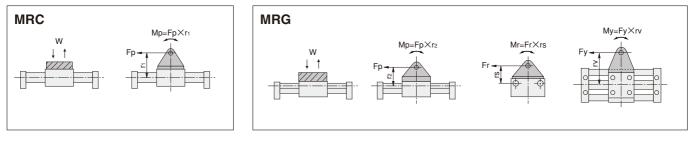
CÂD



#### Selection and Mounting

#### Allowable load and moment

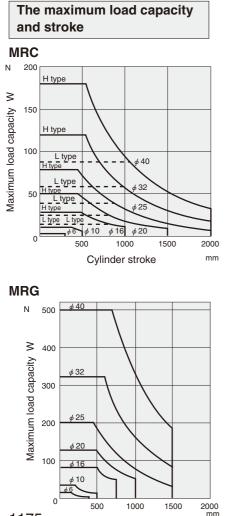
Although the magnet type rodless cylinders MRC, MRG series can be used with directly applying loads, make sure that the load and moment do not exceed the values in the table below.



	MRC			MRG			
Bore size mm [in.]	Maximum load capacity <b>W</b> <sup>Note1</sup> N [lbf.]		Pitching moment	Maximum load capacity	Pitching moment	Rolling moment Mr Note1	Yawing moment
	H type	L type	Mp N⋅m [ft⋅lbf]	W Note1 N [lbf.]		N⋅m [ft·lbf]	My N⋅m [ft⋅lbf]
6 [0.236]	3.9 [0.88]	_	0.10 [0.07]	14.7 [3.30]	0.29 [0.21]	0.06 [0.04]	0.29 [0.21]
10 [0.394]	11.8 [2.65]	-	0.29 [0.21]	39.2 [8.81]	0.98 [0.72]	0.20 [0.15]	0.98 [0.72]
16 [0.630]	29.4 [6.61]	14.7 [3.30]	1.18 [0.87]	78.5 [17.65]	2.45 [1.81]	0.49 [0.36]	2.45 [1.81]
20 [0.787]	49 [11.02]	24.5 [5.51]	2.45 [1.81]	127.5 [28.66]	5.39 [3.98]	1.08 [0.80]	5.39 [3.98]
25 [0.984]	78.5 [17.65]	39.2 [8.81]	3.92 [2.89]	196.1 [44.08]	9.81 [7.24]	1.96 [1.45]	9.81 [7.24]
32 [1.260]	117.7 [26.46]	58.8 [13.22]	8.83 [6.51]	313.8 [70.54]	15.7 [11.6]	3.14 [2.32]	15.7 [11.6]
40 [1.575]	176.5 [39.68]	88.3 [19.85]	13.7 [10.11]	490.3 [110.22]	24.5 [18.1]	4.90 [3.61]	24.5 [18.1]

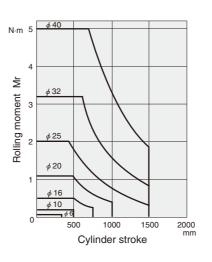
Notes: 1. W and Mr are the maximum values, and are different depending on the stroke. Refer to the graphs below.

2. Cylinder thrust Fp and Fy should be 60% or less of the magnet retaining force.

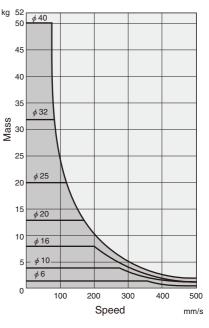


Cylinder stroke

Cylinder stroke and rolling moment MRG



The mass and speed that can be stopped with a stopper bolt MRG

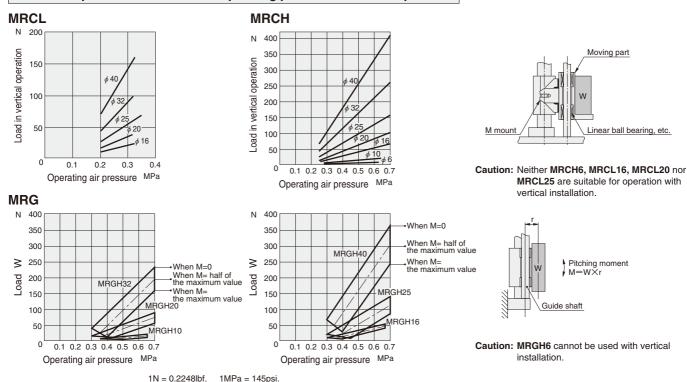


1kg = 2.205lb. 1mm/s = 0.0394in./sec.

Range of possible use

For the MRG series with stopper bolts, use within the allowable operating range of the mass and speed in the graph. If one of these is exceeded, use a type with a shock absorber.

1N = 0.2248lbf. 1mm = 0.0394in. 1N·m = 0.7376ft·lbf



#### Relationship between the load and operating pressure in vertical operation

Stopping at the intermediate stroke

The operating air pressure when the load is stopped during the stroke by an external stopper, etc., should be less than 0.55MPa [80psi.] with the H type, and less than 0.27MPa [39psi.] with the L type.

If used with more pressure than the above, the piston alignment may be off, please be careful.

#### Mounting

- 1. Because strong magnets are built into the **MRC** and the **MRG** series magnet type rodless cylinder's tube, they cannot be used where there is any magnetized cutting oil or metal chips, etc.
- 2. Care must be exercised not to damage or dent the cylinder tube or the guide shaft.
- 3. If misalignment between slider and piston occurs, or if they come out due to external force exceeding the magnet retaining force, apply an external force to the slider and put the slider back in its correct alignment when the piston comes to the end of the stroke.
- Clean periodically when using where the cylinder tube or the guide shaft easily becomes smeared. Apply lubricant on the surface of the cylinder tube and the guide shaft after cleaning.
- 5. With the MRC series, be sure to install a guide outside by using an M mount, as shown in the diagrams to the right, because the slider rotates freely.
- With the MRG series, do not use an external guide such as a linear ball bearing. Install
  and use an M mount for the MRC series when the external guide is installed and used.
- 7. The H type of the MRC series (except MRCH6) can detect the position at the end of the stroke just by installing a sensor switch, but the sensor switch does not always work properly, depending on how the cylinder is mounted.

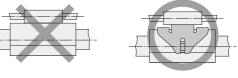
When the bottom of the slider is close to the magnetic material mounting surface of the equipment, use a spacer etc., as shown in the diagram to the right, and install it 5mm [0.20in.] or more apart.

8. Periodic greasing is necessary for the MRC and the MRG series.

For the **MRC** series, apply grease on outer surface of the cylinder tube, and for the **MRG**, grease on the outer surface of the cylinder tube and the guide shaft, about every 300km [186mi.] traveling distance.

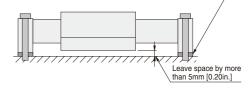
 $\langle \text{Recommended grease} \rangle$ 

 $\mbox{MRC6}$  and  $\mbox{MRC6}$  : Fluorine-contained lithium type grease Excluding the above: Synthetic hydrocarbon type grease



Using an M mount

A spacer thicker than t=3mm [0.12in.]





#### **General precautions**

#### Piping

Always thoroughly blow off (use compressed air) the tubing before connecting it to the cylinder. Entering chips, sealing tape, rust, etc., generated during piping work could result in air leaks or other defective operation.

#### Atmosphere

- 1. If using in locations subject to dripping water, dripping oil, etc., or to large amounts of dust, use a cover to protect the unit.
- 2. The product cannot be used when the media or ambient atmosphere contains any of the substances listed below.

Organic solvents, phosphate ester type hydraulic oil, sulphur dioxide, chlorine gas, or acids, etc.

#### Lubrication

The product can be used without lubrication, if lubrication is required, use Turbine Oil Class

1 (ISO VG32) or equivalent.

Avoid using spindle oil or machine oil.

#### Media

- 1. Use air for the media. For the use of any other media, consult us.
- 2. Air used for the rodless cylinder should be clean air that contains no deteriorated compressor oil, etc. Install an air filter (filtration of a minimum 40 µm) near the rodless cylinder or valve to remove collected liquid or dust. In addition, drain the air filter periodically.