KOGANEI

Air Treatment

INSTRUCTION MANUAL Ver.1.0



Mounting and piping

- Install in locations where wiring, piping, and maintenance work is easy to perform.
- 2. Do not leave the primary pressure applied when the electrical power has been switched OFF. (At this time, the secondary pressure could rise as high as the primary pressure.)
- A bootstrap operation (of 1 to 2 seconds) occurs immediately after the power supply is switched ON, which could cause the secondary pressure to drop temporarily.
- **4.** After switching ON the power supply, do not leave the primary pressure lower than the setting value.
- Do not mount a valve on the ETR's primary side that will result in repeatedly switching the primary pressure ON and OFF.
- Electric noise could result in operations instability. Always take adequate noisereducing measures.
 - * For wiring, use shielded wires.
 - We use surge protection for nearby solenoid valves and inductive loads.

 **The content of the content of th
- 7. Mount in locations that are as distant from motors and powered lines as possible. When mounting near inductive loads and powered lines, always implement load surge suppression, and use magnetic shielding for insulation. In particular, consult us if planning to use in environments subject to much external electric noise.
- 8. The electro-pneumatic transducing regulator is adjusted to the specifications before being shipped out from Koganei. Avoid removing or disassembling any of its parts because such action could result in breakdowns.
- For other handling issues, see the User's Manual included with the product.

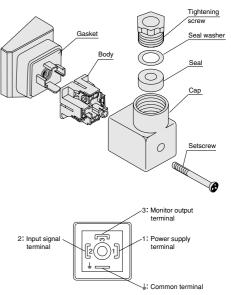


General precautions

- Always thoroughly blow off (use compressed air) the piping before plumbing. Entering chips, sealing tape, rust, etc., generated during piping work could result in air leaks or other defective operation.
- As the interior of the electro-pneumatic transducing regulator uses precision parts, the compressed air should be cleaned air devoid of solid substances, moisture, etc.
 - Intrusion of contaminated air into the device could have an adverse effect on operations characteristics and durability.
 - For the use of any other media than air, consult us.
- 3. While the system can be used without lubrication, if lubricating the actuators, etc. is required, use Turbine Oil Class 1 (ISO VG32) or equivalent. Avoid using spindle oil or machine oil.
- 4. The product cannot be used when the media or the ambient atmosphere contains any of the substances listed below. Organic solvents, phosphate ester type hydraulic oil, sulphur dioxide, chlorine gas, or acids, etc.
- 5. If using in locations subject to dripping water or oil, etc., or to large amounts of dust, use something to cover and protect the unit.

Wiring method

- 1. Removing the connector
- Loosen and remove the connector setscrew, and lift off the connector from the regulator.
- (2) Loosen the tightening screw, remove the seal washer and seal, and push the body out from the cap.



1 ······ Power supply+DC24V terminal

2·····Input signal terminal

Blank: DC $1\sim5$ (V)

-1: DC 0~5 (V)

-2: DC 0~10 (V)

-4: DC 4~20 (mA)

3·····Monitor output terminal (DC1∼5 (V))

↓ ·····Common terminal (GND)

2. Wiring

- (1) To avoid erratic operation in the electropneumatic transducing regulator due to electric noise, divide the power supply, input signal, and monitor output lines each, and use a shielded 2-wire cable for each.
- (2) The electro-pneumatic transducing regulator consumes a maximum of 5W of electrical power. For the power supply, therefore, use shielded wiring with a conductor area of 0.4mm²~0.5 mm² [0.0006~0.0008in²] (equivalent to AWG24~22).



Recommendation

Peripheral pneumatic devices are available for use with the ETR series. See the following list for reference.

ETR010

		TS6-01
Fitting	A Doort	TS8-01
	A, P port	TL6-01
		TL8-01
Muffler	R port	KM-1
Mullel	проп	KM-11
Tube		U6-B (0)
rube		U8-B (0)
Filter		F150-01

ETR200

		TS8-02
Fitting	A, P port	TS10-02
Titting	A, I port	TL8-02
		TL10-02
	PR port	150-30A
Muffler	R port	KM-2
	n poit	KM-23
Tube		U8-B (0)
Tube		U10-B (0)
Filter		F600-02

ETR600

		TS10-04
Fitting	A, P port	TS12-04
Titting	A, F port	TL10-04
		TL12-04
	PR port	150-30A
Muffler	R port	KM-4
	rt port	KM-41
Tube		U10-B (0)
Tube		U12-B (0)
Filter		F600-04

ETR601

		TS10-04
Fitting	A, P port	TS12-04
	A, I poit	TL10-04
		TL12-04
	PR port	150-30A
Muffler	R port	KM-4
	n poit	KM-41
Tube		U10-B (0)
Tube		U12-B (0)
Filter		F600-04

ELECTRO-PNEUMATIC TRANSDUCING REGULATORS



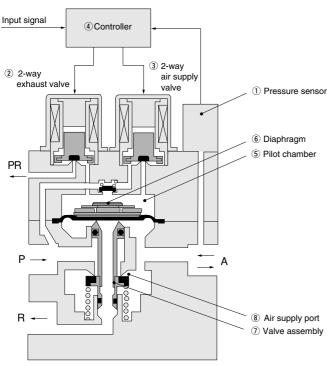
A fusion of air and electronics

- Flexibly control pressure.
- A sequencer (PC) allows remote control operation.
- Feedback control ensures superior flow rate characteristics.

Body construction uses P.W.M. control poppet

- Simple construction. Not requiring special air quality.
- Non-bleed type means no air leak problems.
- Any mounting direction is acceptable. It can withstand strong shocks and vibrations.

Operation Principle of Electro-Pneumatic Transducing Regulators

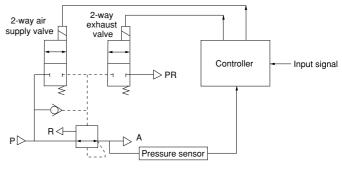


This diagram shows the ETR200

Increasing output air pressure A

When the controller 4 input signal increases, the 2-way valve 3 is activated and pressure on the pilot chamber 5 rises. Then, forcing downward the diaphragm 6 causes the valve assembly 7 to move downward, opening the air supply port 8, and causing the supply pressure P to flow in and output air pressure A to rise. Pressure A is detected using the pressure sensor 1, and the feedback returns to the controller.

The 2-way valves ②, ③ respond to the difference between output air pressure A and set pressure by an input signal, and switch supply air on and off to perform pressure adjustment, to obtain an output air pressure A that is proportional to the input signal.



Block diagram

What is an electro-pneumatic transducing regulator?

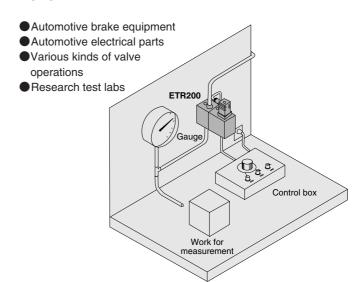
A multi-purpose pressure control device that operates in response to voltage or current input signals from the outside to continuously step and accurately control high relief regulator's (pilot type) pilot section in electro-pneumatic transducers, for high-precision air pressure control.

Application Examples of Electro-Pneumatic Transducing Regulators

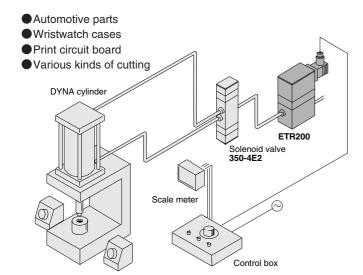
The Koganei Electro-Pneumatic Transducing Regulator is suitable for such applications as:

Setting up test benches simply. Level 2 Multiple stepping of air cylinder thrust. Level 3 Controlling valves. Level 4 Controlling various types of flow dispensers. Level 5 Controlling tension force in winder equipment.

Level 1

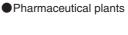


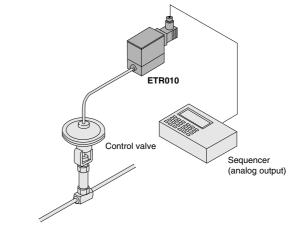
Level 2



Level 3

Bakeries and snack food processing plants



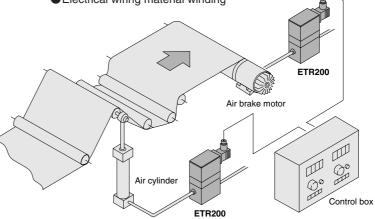


Level 4

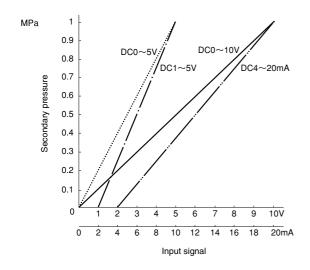
Compact disk manufacturing Applying solder paste Chemical filling machine Packaging material winding ETR010 Koganei suck back valve Tank Control box Index table

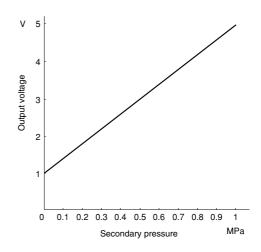
Level 5

- Video tapes and other magnetic tapes
- Coil wires
- Electrical wiring material winding

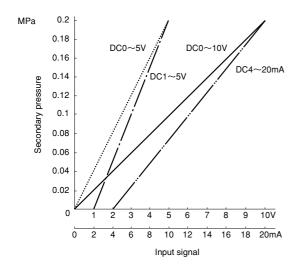


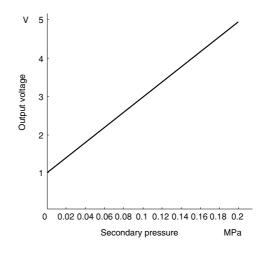
ETR010, 200, 600





ETR601





1MPa = 145psi.

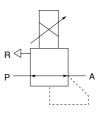




Specifications

			Basic	model	ETR010	ETR010-1	ETR010-2	ETR010-4
Item					LIMOTO	LIMO10-1	L111010-2	L111010-4
Media						А	ir	
Port size				Rc		1,	/8	
Pressure	setting ran	ge	MPa	[psi.]		0.005~0.7	[0.7~102]	
Primary p	ressure rai	nge	MPa	[psi.]	Set pre	ssure or more	, and 0.9 [131]	or less
Proof pres	ssure		MPa	[psi.]		1.32	[191]	
	Voltage	Voltage		DC[V]	1~5	0~5	0~10	
Input control method current		Input impe	edance	kΩ	20	20	42	_
	Current	Current DC [mA]						4~20
	method		mpedance Ω		 25			250
Output	Output vo	/oltage		OC [V]	1~5			
signal	Load imp	Load impedance $k\Omega$		kΩ	5 or more			
Power sup	pply			OC [V]	24 (7W)±10%			
Linearity*	•				±1.0% F.S.			
Hysteresis	s*				±0.5% F.S.			
Step resp	onse ^{Note}			s	1 or less			
Operating temperature range (atmosphere and media) °C [°F]		C [°F]	5~50 [41~122]					
Vibration resistance m/s² [ft./sec.²]			/sec. ²]	98 [322] or less				
Wiring				DIN connector (as standard)				
Mass			ŀ	(g [lb.]	0.44 [0.97]			

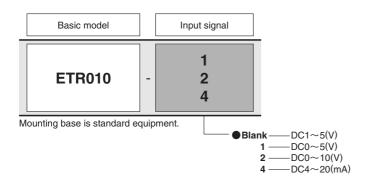
Symbol



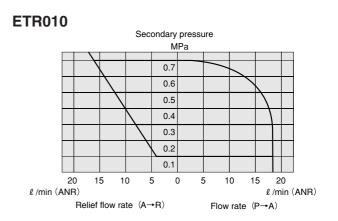
*Values are calculated assuming a pressure full span (F.S.) of 0.7MPa [102psi.].

Note: Secondary pressure values assume at no load conditions.

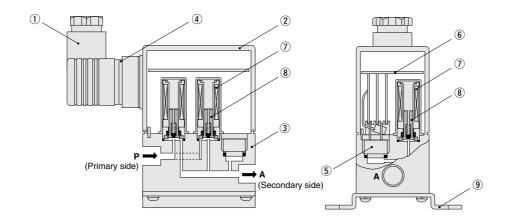
Order Codes



Flow Rate Characteristics and Relief Characteristics



Remark: Primary pressure is 0.7MPa [102psi]. 1MPa = 145psi. $1 \ell/min = 0.0353ft.^3/min$.

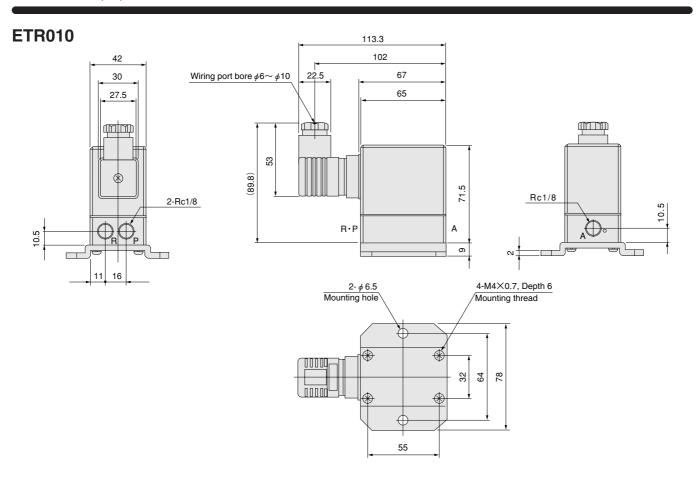


Major Parts and Materials

No.	Parts	Materials
1	DIN connector	Plastic
2	Cover	Plastic
3	Body	Aluminum alloy (anodized)
4	Gasket	Synthetic rubber (chloroprene)

No.	Parts	Materials
(5)	Pressure sensor	Plastic (diffusion-type semiconductor)
6	Circuit board assembly	Glass epoxy
7	Coil assembly	
8	Plunger	Magnetic stainless
9	Mounting base	Mild steel (zinc plated)

Dimensions (mm)



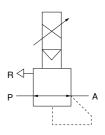




Specifications

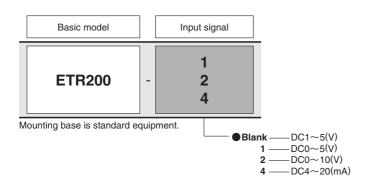
Item	Basic model Item					ETR200-1	ETR200-2	ETR200-4
Media						А	ir	
Port size				Rc		1.	/4	
Pressure	setting ran	ge	MPa	a [psi.]		0.01~0.7	[1.5~131]	
Primary p	ressure rar	nge	MPa	g [psi.]	Set pressure	+0.1 [15] or	more, and 0.9	[131] or less
Proof pres	ssure		MPa	a [psi.]		1.32	[191]	
	Voltage	Voltage		DC[V]	1~5	0~5	0~10	
Input	method	Input impe	edance	kΩ	20	20	42	
signal	Current	Current	DO	C [mA]				4~20
	method Input impo		edance	Ω		250		
Output	Output vo	Itage	I	OC [V]	1~5			
signal	Load impe	edance		kΩ	5 or more			
Power sup	pply		ı	OC [V]	24 (7W)±10%			
Linearity*						±1.0°	% F.S.	
Hysteresis	s*				±0.5% F.S.			
Step resp	onse ^{Note}			s	2 or less			
Operating temperature range (atmosphere and media) °C [°F]		C [°F]	5~50 [41~122]					
Vibration resistance m/s² [ft./sec.²]			98 [322] or less					
Wiring			DIN connector (as standard)					
Mass			ı	kg [lb.]		0.74	[1.63]	

Symbol



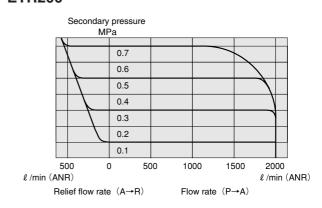
Walues are calculated assuming a pressure full span (F.S.) of 0.7MPa [102psi.].
 Note: Secondary pressure values assume at no load conditions.

Order Codes

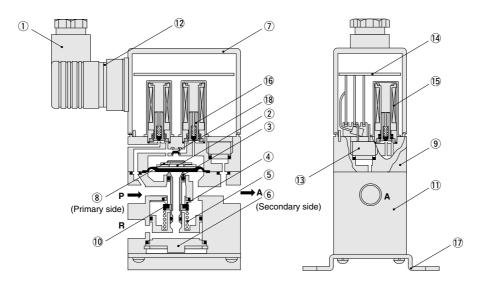


Flow Rate Characteristics and Relief Characteristics

ETR200



Remark: Primary pressure is 0.83MPa [120psi.]. 1MPa = 145psi. $1 \ell/min = 0.0353ft.3/min.$

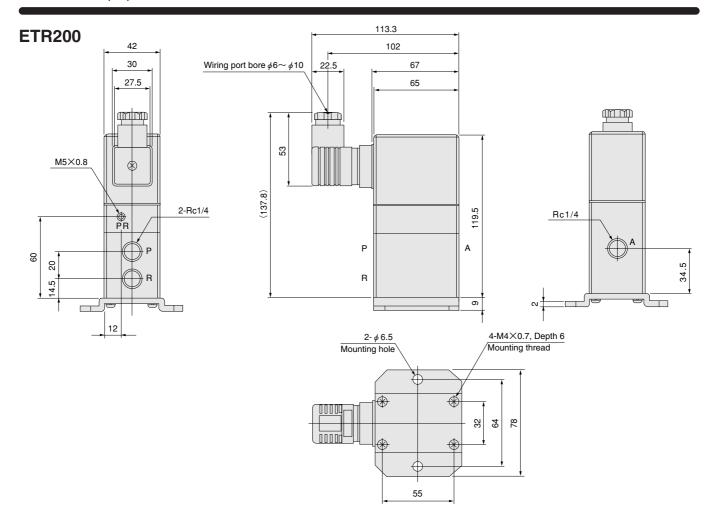


Major Parts and Materials

No.	Parts	Materials
1	DIN connector	Plastic
2	Diaphragm	Aluminum (NBR baked)
3	Valve pin	Brass
4	Valve seat	Brass
(5)	Spring	Piano wire
6	Exhaust cover	Aluminum alloy (anodized)
7	Cover	Plastic
8	Balancer	Brass
9	Adapter	Aluminum alloy (anodized)

No.	Parts	Materials
10	Valve	Brass (NBR baked)
11)	Body	Aluminum alloy (anodized)
12	Gasket	Synthetic rubber (chloroprene)
13	Pressure sensor	Plastic (diffusion-type semiconductor)
14)	Circuit board assembly	Glass epoxy
15	Coil assembly	
16	Plunger	Magnetic stainless
17	Mounting base	Mild steel (zinc plated)
18	Check valve	Synthetic rubber (NBR)

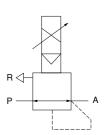
Dimensions (mm)





Specifications

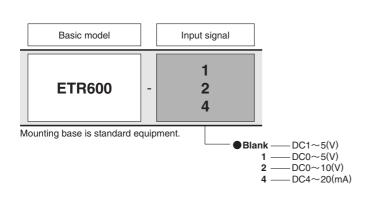
Item	Basic model Item					ETR600-1	ETR600-2	ETR600-4	
Media						Air			
Port size				Rc		1.	/2		
Pressure	setting ran	ge	MPa	[psi.]		0.01~0.7	[1.5~102]		
Primary p	ressure rar	nge	MPa	[psi.]	Set pressu	ure +0.1 [15] or	more, and 0.9 [1	31] or less	
Proof pres	ssure		MPa	[psi.]		1.32	[191]		
	Voltage	Voltage		C [V]	1~5	0~5	0~10		
Input	method	Input imp	edance	kΩ	20	20	42		
signal	Current	Current	DC	[mA]				4~20	
			edance	Ω				250	
Output	Output vo	oltage DC [V]		C [V]	1~5				
signal	Load imp	edance		kΩ	5 or more				
Power sup	pply			C [V]	24 (7W)±10%				
Linearity*	•					±1.0°	% F.S.		
Hysteresis	s*				±0.5% F.S.				
Step resp	onse ^{Note}			s	2 or less				
Operating temperature range (atmosphere and media)		°(C [°F]	5~50 [41~122]					
Vibration resistance m/s² [ft./sec.²]		/sec. ²]	98 [322] or less						
Wiring				DIN connector (as standard)					
Mass			k	g [lb.]		1.2 [2.65]		



*Values are calculated assuming a pressure full span (F.S.) of 0.7MPa [102psi.].

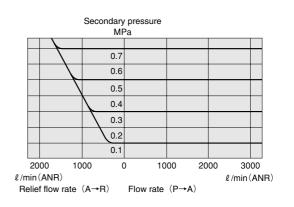
Note: Secondary pressure values assume at no load conditions.

Order Codes

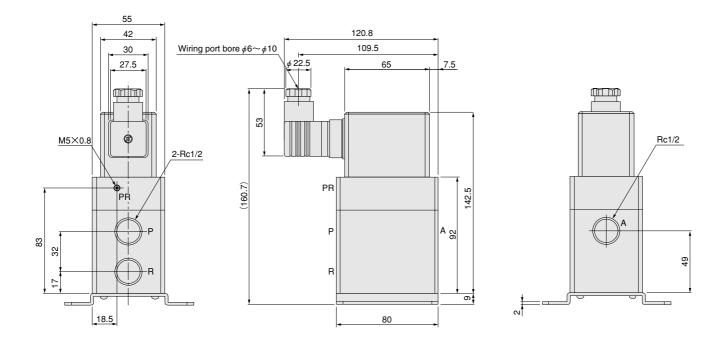


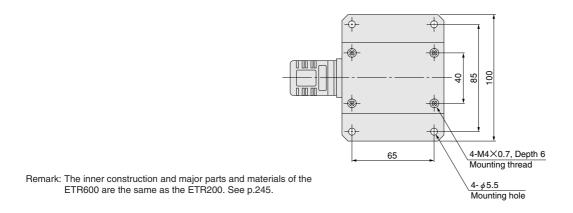
Flow Rate Characteristics and Relief Characteristics

ETR600



Remark:Primary pressure is 0.83MPa [120psi.]. 1MPa = 145psi. $1\ell/min = 0.0353ft3/min.$

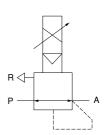






Specifications

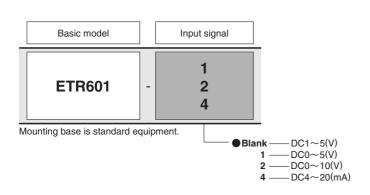
Item	Basic model Item					ETR601-1	ETR601-2	ETR601-4	
Media						Air			
Port size				Rc		1.	/2		
Pressure	setting ran	ge	MPa	[psi.]		0.01~0.2	[1.5~29]		
Primary p	ressure rar	nge	MPa	[psi.]	Set pressur	e +0.05 [7] or	more, and 0.4	[58] or less	
Proof pres	ssure		MPa	[psi.]		0.6	[87]		
	Voltage	Voltage	[OC [V]	1~5	0~5	0~10		
Input	method	Input imp	edance	kΩ	20	20	42		
signal	signal Current control	Current	DC	[mA]				4~20	
			edance	Ω					
Output	Output vo	voltage DC [V]		OC [V]	1~5				
signal	Load imp	edance		kΩ	5 or more				
Power sup	pply		[OC [V]	24 (7W)±10%				
Linearity*	•				±1.0% F.S.				
Hysteresis	s*				±0.5% F.S.				
Step resp	onse ^{Note}			s	2 or less				
Operating temperature range (atmosphere and media) °C		C [°F]	5~50 [41~122]						
Vibration resistance m/s² [ft./sec.²]			/sec ²]	98 [322] or less					
Wiring					DIN connector (as standard)				
Mass			ŀ	g [lb.]		1.2 [2.65]		



*Values are calculated assuming a pressure full span (F.S.)of 0.2MPa [29psi.].

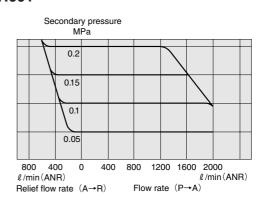
Note: Secondary pressure values assume at no load conditions.

Order Codes

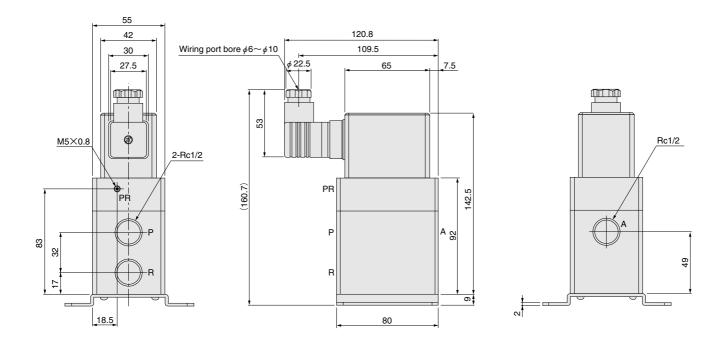


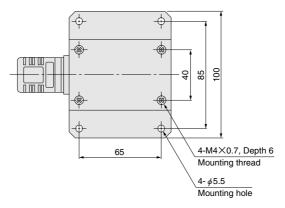
Flow Rate Characteristics and Relief Characteristics

ETR601



Remark:Primary pressure is 0.25MPa [36psi.]. 1MPa = 145psi. 1 ℓ /min = 0.0353ft3/min.





Remark: The inner construction and major parts and materials of the ETR601 are the same as the ETR200. See p.245.