

http://www.koganei.co.jp

With locating pin hole (option)



# Smallest Lightest Compact Basic Cylinders BC Cylinders

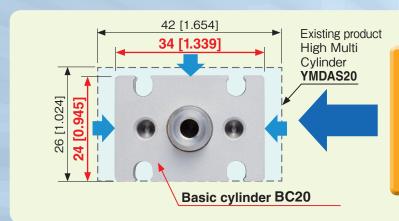
Possible to create all assembly processes with just BC cylinders Wide range of variations from  $\phi$ 6 [0.236 in] to  $\phi$ 125 [4.9 in] NEW Heat resistant specification, clean room specification, with locating pin hole, and more! **NEW** Variations! Corrosion resistant, heat resistant, scraper specifications Double rod cylinders: Selectable thread type Clean system compatible cylinders Piston rod end shape (order made)

# Basic Cylinders



**BASIC CYLINDERS** 

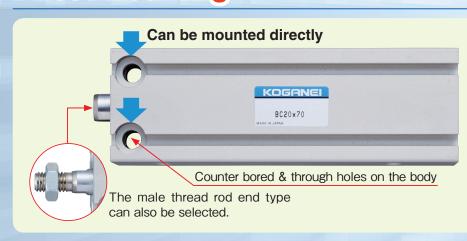
## **Lightweight & Compact**



Cross section is 25% smaller Total length is 30% shorter 40% less mass

Comparison of 10 mm [0.394 in] stroke

## **Direct mounting**





Bracket can be mounted on the head side of  $\phi 10 \ [0.394]$  to  $\phi 125 \ [4.9]$  models (except when guide is attached)

Bracket material  $\phi 10$  [0.394] to  $\phi 32$  [1.260]: Stainless steel  $\phi$ 40 [1.575] to  $\phi$ 125 [4.9]: Aluminum alloy

Excellent series ranging from  $\phi$  6 to  $\phi$  125 [0.236 to 4.9] (Double acting type and double rod cylinders)

H grease compatibility as standard NEW 150°C 1302°F 1 compatibility for heat resistant standard





CAUTION Read the safety precautions on page before using this product.

## **Cylinder with guide**

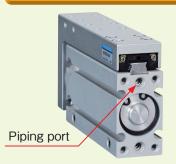
φ8 [0.315], φ12 [0.472], φ16 [0.630], φ20 [0.787], φ25 [0.984], φ32 [1.260], φ40 [1.575]

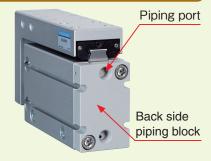
#### Linear guide is mounted to save space and for non-rotating accuracy





#### Back side piping is possible





Back side piping is possible as standard for  $\phi 8$  [0.315] to  $\phi$ 25 [0.984] models.

Back side piping is possible for  $\phi$  32 [1.260] and  $\phi$  40 [1.575] models by selecting back side piping block.

Note: Linear guides use low dust grease.

## **NEW Scraper specification**

## **NEW** Clean system compatible cylinders







## **Step 1 variations**

#### Double acting type 3 Page

 $\phi$ 6 [0.236] to  $\phi$ 125 [4.9] ( $\phi$ 6 [0.236],  $\phi$ 8 [0.315],  $\phi$ 10 [0.394],  $\phi$ 12 [0.472],  $\phi$ 16 [0.630],  $\phi$ 20 [0.787],  $\phi$ 25 [0.984],  $\phi$ 32 [1.260],  $\phi$ 40 [1.575],  $\phi$ 50 [1.969],  $\phi$ 63 [2.480],  $\phi$ 80 [3.150],  $\phi$ 100 [3.9],  $\phi$ 125 [4.9]) \*Double acting type has excellent low-speed operation (range of speeds: 10 to 500 mm/s [0.394 to 19.7 in/sec]).



#### Single acting push type 3 Page

 $\phi$ 6 [0.236] to  $\phi$ 50 [1.969]  $(\phi 6 \ [0.236], \ \phi 8 \ [0.315], \ \phi 10 \ [0.394], \ \phi 12 \ [0.472], \ \phi 16 \ [0.630], \ \phi 20$  $[0.787],\ \phi 25\ [0.984],\ \phi 32\ [1.260],\ \phi 40\ [1.575],\ \phi 50\ [1.969])$ 



#### Single acting pull type 3 Page

 $\phi$ 6 [0.236] to  $\phi$ 50 [1.969]  $(\phi 6 \ [0.236], \ \phi 8 \ [0.315], \ \phi 10 \ [0.394], \ \phi 12 \ [0.472], \ \phi 16 \ [0.630], \ \phi 20 \ [0.787],$ φ25 [0.984], φ32 [1.260], φ40 [1.575], φ50 [1.969])



## **Double rod end cylinders Page**

 $\phi$ 6 [0.236] to  $\phi$ 125 [4.9]  $(\phi 6 \; [0.236], \; \phi 8 \; [0.315], \; \phi 10 \; [0.394], \; \phi 12 \; [0.472], \; \phi 16 \; [0.630], \; \phi 20 \; [0.787], \; \phi 25 \; [0.984], \; \phi 32 \; [1.260], \; \phi 10 \; [0.884], \; \phi 10 \; [0.8$  $\phi$ 40 [1.575],  $\phi$ 50 [1.969],  $\phi$ 63 [2.480],  $\phi$ 80 [3.150],  $\phi$ 100 [3.9],  $\phi$ 125 [4.9])



## Cylinder with guides 95 Page

 $\phi$ 8 [0.315] to  $\phi$ 40 [1.575] ( $\phi$ 8 [0.315],  $\phi$ 12 [0.472],  $\phi$ 16 [0.630],  $\phi$ 20 [0.787],  $\phi$ 25 [0.984],  $\phi$ 32 [1.260], φ40 [1.575])









# **NEW** Step 2 variations

#### Corrosion resistant specification -

- · Snap ring: Electroless nickel plated
- · Guide: H1 grease · Packing: NBR

#### **Compatible cylinders**

- **Double acting type** φ6 [0.236] to φ125 [4.9] **23** Page
- Single acting push type, single acting pull type  $\phi$  6 [0.236] to  $\phi$  50 [1.969] 23 Page
- **Double rod end cylinders**  $\phi$  6 [0.236] to  $\phi$  125 [4.9]  $\phi$  Page
- lue Cylinder with guide  $\phi$  6 [0.236] to  $\phi$  40 [1.575] lue Page



#### Heat resistant specification -

Up to a maximum of 150°C [302°F].

· Packing: fluoro rubber Note: Sensor switch cannot be attached.

#### Compatible cylinders

- Double acting type φ6 [0.236] to φ125 [4.9] ② Page
- Cylinder with guide  $\phi$  8 [0.315] to  $\phi$  40 [1.575] Page





Double acting type

Cylinder with guide

#### Scraper specification -

Compatible with environments where dust and water droplets are present.

#### Compatible cylinders

**Double acting type**  $\phi$  10 [0.394] to  $\phi$  125 [4.9] (No  $\phi$  6 [0.236] and  $\phi$  8 [0.315]) 23 Page



#### Clean system compatible cylinders

With dust collection port: Class 5 equivalent Without dust collection port: Class 6 equivalent

#### **Compatible cylinders**

- Double acting type (With dust collection port) φ6 [0.236] to φ63 [2.480] **(** Page
- Double acting type (Without dust collection) port)  $\phi$  10 [0.394] to  $\phi$  63 [2.480]  $\bigcirc$  Page
- Cylinder with guide (Without dust collection) port) φ8 [0.315] to φ40 [1.575] (2) Page









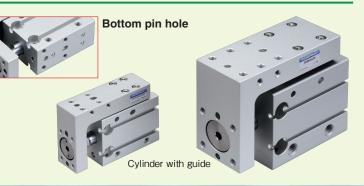
With dust collection port

## With locating pin hole (option) -

Cylinder body: Pin holes in three sides Table: Pin holes in two sides

#### **Compatible cylinders**

• Cylinder with guide  $\phi$ 8 [0.315] to  $\phi$ 40 [1.575] 95 (2) Page



# **Guide to recommended related products!**

For details, see our homepage. http://www.koganei.co.jp

## F series solenoid valves (F10•F15•F18)

Low-current type and single/double dual-use valves offer energy savings and a low price.

- Switch the manual override button to select single solenoid valve or double solenoid valve functions on the 2-position valve of the F series.
- Different tube sizes for piping are possible with dual-use different size fittings.



## iB-Cyclone

#### High-speed cyclone type water separator!

- Half the volume ratio and 99% higher moisture separation rate when compared with equivalent equipment.
- ●No element used for maintenance-free operation.
- Auto drain function (NC and NO) available.
- Specifications for ozone resistance, NCU specifications (copper free) compatible as standard.



## Smaller size FRZB filter regulator

#### FRZB filter regulator with moisture and fluid removal function!

- Compact size with short face-to-face dimensions.
- With drain cock and easy to use moisture and fluid removal function.
- Auto drain function (NC and NO) available.
- Bowl guard available.



### FRZ Series Air filter · Oil mist filter · Micromist filter

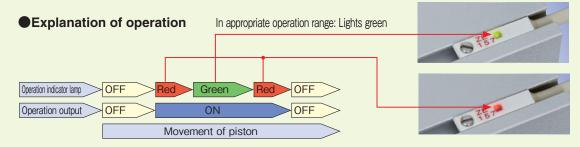
#### Downsized! Short face-to-face dimensions! Visible filter element!

- Compact size with short face-to-face dimensions.
- It is easy to check the state of the filter element.
- Auto drain function (NC and NO) available.



## **Two-color LED sensor switches**

Two-color LED sensor switches that can be easily positioned and adjusted. Appropriate operation range can be determined by the color of the LED indicator!



## MTV Series water removal valves

Our answer to counteracting condensation! Prevent condensation from developing inside the piping to pneumatic grippers and small cylinders!

Simply connect it in the pipes! Easy mounting!



## **iB-Flow** Digital flow controller

Constantly monitors cylinder tact times and adjusts automatically!

- Digitally set cylinder tact times (operation cycle times).
- Tact time controller is always monitoring and adjusting.
- Safety mechanism prevents needle from loosening.
- Numeric setting of needle opening (0 to 100%).



## **Quick fitting series**

Wide range of variations such as many types of quick fittings and speed controllers with quick fittings!

- Standard types, mini types, and SUS specifications available.
- Diverse variations available such as quick fittings with stop valves, hand valves, check valves, throttle valves, and power reducers.



Before selecting and using the products, please read all the safety precautions carefully to ensure proper product use.

The safety precautions described below are to help you use the product safely and correctly, and to prevent injury or damage to you, other people, and assets. Always observe these safety precautions and the following safety regulations: ISO4414 (Pneumatic fluid power - General rules and safety requirements for systems and their components) and JIS B 8370 (General rules relating to systems).

The directions are ranked according to degree of potential danger or damage: "DANGER", "WARNING!", "CAUTION!", and "ATTENTION!".

<b>ANGER</b>	Indicates situations that can be clearly predicted as dangerous.  Death or serious injury may result if the situation is not avoided.  It could also result in damage or destruction of assets.
<b>⚠</b> WARNING	Indicates situations that, while not immediately dangerous, could become dangerous.  Death or serious injury may result if the situation is not avoided.  It could also result in damage or destruction of assets.
<b>A</b> CAUTION	Indicates situations that, while not immediately dangerous, could become dangerous.  Failure to avoid the situation creates the risk of minor or semi-serious injury.  It could also result in damage or destruction of assets.
ATTENTION	While there is no chance of injury, these points should be observed for appropriate use of the product.

#### ■This product was designed and manufactured for use in general industrial machinery.

- ■When selecting and handling equipment, the system designer or another person with sufficient knowledge and experience should always read the safety precautions, catalog and other literature before commencing operation. Improper handling is dangerous.
- After reading the catalog, and other documentation, always place them in a location that allows easy availability for reference to users of this product.
- ■Whenever transferring or lending the product to another person, always attach the catalog, and other information to the product where they are easily visible in order to ensure that the new user can use the product safely and properly.
- ■The danger, warning and caution items listed under these safety precautions do not cover all possible contingencies. Read the catalog carefully, and always keep safety first.

## **DANGER**

- Do not use the product for the purposes listed below:
  - 1. Medical equipment related to maintenance or management of human lives or bodies
  - 2. Machines or equipment designed for the purpose of moving or transporting people
  - 3. Critical safety components in mechanical devices This product has not been planned or designed for purposes that require high levels of safety. Using the product in any of the ways described above creates the risk of loss of human
- Do not use the product in locations with or near dangerous substances such as flammable or ignitable substances. This product is not explosion-proof. Doing so creates the risk of ignition and fire.
- When mounting the product and workpiece, always make sure they are firmly supported and secured in place. Falling, dropping, or abnormal operation of the product creates the risk of personal injury.
- Persons using a pacemaker or other similar medical devices should maintain a distance of at least one meter [3.28 ft] away from the product. Getting too close to the product creates the risk of malfunction of a pacemaker due to the strong magnet built into the product.
- Never attempt to modify the product in any way. Doing so creates the risk of injury, electric shock, fire, etc. due to abnormal operations.
- Never attempt inappropriate disassembly, assembly or repair of the product relating to basic construction, or to its performance or to functions. Doing so creates the risk of injury, electric shock, fire, etc.
- Do not allow water to splash on the product. Water spraying on the product, washing the product, or using the product under water creates the risk of malfunction, leading to injury, electric shock, fire, etc.
- While the product is in operation, avoid touching it with your hands or otherwise approaching too close. Also, do not attempt to make any adjustments to internal or attached mechanisms (sensor switch mounting location, disconnection of piping tubes or plugs, etc.) while the product is in operation. This may cause an unintended cylinder movement resulting in injury.
- When operating the product, always install speed controllers, and gradually loosen the needle valve from a choked state to adjust the increase in speed.
  - Failure to make this adjustment could result in the air supply causing sudden movements, which may put human lives at risk.

- Do not apply excess bending or buckling force to the piston rod. Doing so may cause abnormal wear or damage to the rod or tube and reduce the product's operating life.
- Always link the direction of motion of the load with the axis of the piston rod. If they are not the same, the undue force on the tube and piston rod may cause abnormal wear or damage.

#### **WARNING**

- Do not use the product in excess of its specification ranges. Doing so creates the risk of product breakdown, loss of function, or damage. It could also drastically reduce the product's operating life.
- Before supplying air or electricity to the device and before starting operation, always conduct a safety check of the area where the machine is operating. Unintentional supply of air or electricity creates the risk of electric shock or injury due to contact with moving parts.
- Do not touch terminals or switches while power is turned on. Doing so creates the risk of electric shock and abnormal operation.
- Always check the catalog and other reference materials for correct product wiring and piping. Improper wiring and piping creates the risk of abnormal operation of the cylinder.
- Do not allow the product to be thrown into fire. Doing so creates the risk of explosion and the release of toxic gases.
- Do not sit on the product, place your foot on it, or place other
  - Doing so creates the risk of injury due to tripping or the product tipping over or falling, resulting in product damage, malfunction or runaway operation.
- Before conducting maintenance, inspection, repair, replacement, or any other similar procedure, always completely cut off all air supply and confirm that residual pressure inside the product or in piping connected to the product is zero. In particular, be aware that residual air will still be in the air
- compressor or storage tank. The cylinder may move abruptly, if residual air pressure remains inside the piping, causing injury.
- Do not use the cylinder as a device to absorb the shock or vibration of machinery. Doing so may create the risk of injury or the breakdown of the machinery.
- Do not allow lead wires of sensor switches or other cords to become damaged.
  - Allowing a cord to become damaged, bent excessively, pulled, rolled up, placed under heavy objects, or squeezed between two objects creates the risk of current leaks or defective continuity that can lead to fire, electric shock, or abnormal operation.

- Do not apply external magnetic field to sensor switches while the cylinder is in operation. Unintended operations could damage equipment or cause injury.
- Use the product within the recommended load and operating speed specifications. Using the cylinder in excess of the recommended load and operating speed specifications could damage the cylinder causing damage to equipment or injury.

Use safety circuits or design a system that prevents damage to machinery and personal injury when the machine is shut down due to an emergency stop or electrical power failure, etc.

- Install relief valves or other devices to ensure that the cylinder does not exceed its rated pressure when the pressure is increased by external forces on the cylinder. Excessive pressure could lead to a breakdown and damage.
- When the product has been idle for over 48 hours or has been in storage, it is possible that the contacting parts may have become stuck leading to operating delays or sudden movements. Before initial operations, always run a test to check that operating performance is normal.

Do not use the product near the ocean, in direct sunlight, near mercury vapor lamps, or near equipment that generates ozone. Deterioration of rubber parts caused by ozone may reduce performance and functions or stop functions.

- Because Koganei products may be used under a wide variety of conditions, decisions concerning conformance with a particular system should be made upon the careful evaluation by the person in charge of system design. Assurances concerning expected system performance and safety are the responsibility of the designer who decides system conformity. Be sure to use the latest catalogs and technical materials to study and evaluate specification details, to consider the possibility of machine breakdown, and to configure a system that ensures fail-safe safety and reliability.
- Do not apply force to cylinder rods and tables outside the ranges of allowable lateral load, allowable kinetic energy, allowable moment, and other values shown in the catalog and other documentation. Doing so may cause wear or damage to the rod or tube and reduce the product's operating life.

#### / CAUTION

- Do not use the product in locations subject to direct sunlight (ultraviolet radiation), in locations with dust, salt, or iron particles, or in locations with media and/or ambient atmosphere that include organic solvents, phosphate ester type hydraulic oil, sulfur dioxide gas, chlorine gas, acids, etc. Such uses could lead to loss of functions within a short period, sudden degradation in performance, or reduced operating life. For details on materials used in the product, refer to the description of materials used in major parts.
- When mounting the product, leave room for adequate working space around it. Failure to do so will make it more difficult to conduct daily inspections or maintenance, which could eventually lead to system shutdown or damage to the product.
- When transporting or mounting a heavy product, firmly support the product using a lift or support, or use multiple people to ensure personal safety.
- Do not bring any magnetic media or memory within one meter [3.28 ft] of the product. Doing so creates the risk of damage to data on the magnetic media due to magnetism.
- Do not use the sensor switch in locations subject to large electrical currents or strong magnetic fields. It could result in erratic operation.
  - Also avoid using magnetic material for any parts used for mounting. Doing so creates the risk of magnetism leakage that causes malfunctions.
- Do not bring the product too close to magnetic material. The sensor switch may malfunction or operate erratically if the product is located near a magnet or where a magnetic field is generated.
- Never use another companies' sensor switches with these
  - Doing so may cause malfunctions or runaway operation.
- Do not scratch, dent, or deform the actuator by sitting or standing on the product, or by placing objects on it. Doing so creates the risk of damage to or breakage of the product, resulting in operational shutdown or degraded performance.

- Always post an "operations in progress" sign for installations, adjustments, or other operations, to avoid unintentional supplying of air or electrical power, etc. Unintended power or air supply can cause electric shock and sudden cylinder movement, creating the risk of personal injury.
- Do not subject any cords, such as the sensor switch lead wires, to excessive loads by pulling on them, lifting the product by them, or placing heavy objects on them. Doing so may cause current leakage or defective continuity leading to fire, electric shock, or abnormal operation.
- Using extremely dry air with a dew point lower than -20°C [-4°F], may affect the quality of the lubricating oil used. This may cause loss of functions, shorter operating life, degraded performance or other problems.
- Be sure to wash your hands thoroughly after touching the heat resistant specification and clean room specification grease. Smoking a cigarette with hands soiled with grease creates the risk of emission of toxic gas when grease adhering to the cigarette burns. (Though the grease is very stable at normal temperature, it emits toxic gas when its temperature exceeds 260°C [500°F].)

#### ATTENTION

- Whenever considering use of this product in situations or environments not specifically noted in the catalog, or in applications where safety is an important requirement such as in aircraft facilities, combustion equipment, leisure equipment, safety equipment, and other places where human life or assets may be greatly affected, take adequate safety precautions such as allowing plenty of margin for ratings and performance, or fail-safe measures.
  - Be sure to contact Koganei before use in such applications.
- Moving parts of machinery should be isolated with protective covers so as not to come into direct contact with human bodies.
- Do not configure controls that would allow workpieces to fall if power fails.
  - Configure the control system to prevent workpieces or tables from falling if the machinery stops during an emergency stop or power outage.
- When handling the product, wear protective gloves, safety glasses, safety shoes, and other protective clothing whenever
- When the product can no longer be used or is no longer necessary, dispose of it appropriately as industrial waste.
- Pneumatic equipment can exhibit degraded performance and function over its operating life. Always conduct daily inspections of the pneumatic equipment, and confirm that all requisite system functions are satisfied, to prevent accidents from happening.
- For inquiries about the product, consult your nearest Koganei sales office or Koganei Overseas Department. The addresses and telephone numbers are shown on the back cover of this catalog.

## Other

- Always observe the following items.
  - 1. When using this product in pneumatic systems, always use genuine Koganei parts or compatible parts (recommended
    - When conducting maintenance and repairs, always use genuine Koganei parts or compatible parts (recommended parts).
    - Always observe the prescribed methods and procedures.
  - 2. Never attempt inappropriate disassembly or assembly of the product in relation to its basic construction, performance, or functions.

Koganei cannot be held responsible for any problems that occur as a result of these safety precautions not being properly observed.



#### **Design and selection**

#### **∴** WARNING

#### 1. Check the specifications.

Read the specifications carefully to ensure correct use within the product's specified voltage, current, temperature, and shock ranges, failure to do so could result in a breakdown or defective operation.

#### 2. Be careful when mounting cylinders in close proximity to each other.

Refer to page 49 if you are mounting more than two cylinders, with sensor switches, in parallel. The magnetic field interference may cause the sensor switches to malfunction.

#### 3. Be careful of how long the sensor switch is on when detecting the position in mid-stroke.

Be aware that, when the sensor switch is mounted at an intermediate point of the cylinder stroke to detect the passing of the piston, if the piston is moving too fast, the length of time the sensor switch operates is too short to delete the piston passing (so loads such as programmable controllers are not operated). The highest detectable cylinder speed is

V mm/s [in/sec]=

Sensor switch operating range mm [in]

×1000

Time required for load operation [ms]

#### 4. Keep wiring as short as possible.

Lead wires for solid state sensor switches should be within 30 m [98 ft] as stipulated by EN standards. For reed sensor switches, longer wiring (10 m [33 ft] or longer) will lead to a larger capacitive surge, which reduces the operating life of sensor switches. When longer wiring cannot be avoided, provide the protective circuit described in the catalog. For details, see page 3.

If the load is inductive or capacitive, provide the appropriate protective circuit as described in the catalog. For details, see

## 5. Avoid repeated bending or excessive pulling of lead

Applying repeated bending stress or tension force on the lead wires could break them.

#### 6. Check for leakage current.

With 2-lead wire solid-state sensor switches, current (leakage current) flows to the load to activate the internal circuit even when turned off. Ensure that the circuit satisfies the following inequality.

Input off current of programmable controller > Leakage current If the above inequality cannot be satisfied, select a 3-lead wire solid state sensor switch. And, if n sensor switches are connected in parallel, the leakage current increases by n times.

7. Do not use reed sensor switches at low speeds below 30 mm/s [1.2 in/sec]. Doing so may cause erratic operation or loss of functions.

#### **⚠** CAUTION

#### 1. Check for internal voltage drop of sensor switches.

Connecting reed sensor switches with indicator lamps, or 2-lead wire solid state sensor switches, in series causes increasing internal voltage drop and the load may fail to activate. Connecting n switches will drop the internal voltage by n times as much.

Ensure that the circuit satisfies the following inequality:

Supply voltage – Internal voltage drop x n > Minimum operating voltage of the load In relays with rated voltage of less than 24 VDC, check that the above inequality is satisfied even when n=1.

If the above inequality cannot be satisfied, select a reed sensor switch without an indicator lamp.

#### 2.Do not use Koganei sensor switches with other companies' cylinders.

The sensor switches are designed for use with Koganei cylinders only. They may not function correctly if used with other companies' cylinders.



#### Installation and adjustment

#### **⚠ WARNING**

#### 1. Do not apply an external magnetic field to the sensor switch while the cylinder is in operation.

This may cause unintended operation, thereby damaging the device or causing injury.

#### **⚠** CAUTION

#### 1. Be aware of the environment in which you install the sensors and cylinders.

Do not use the sensor switch in locations subject to large electrical currents or strong magnetic fields. It could result in erratic operation.

Also avoid using magnetic material for any parts used for mounting. It could result in erratic operation.

## 2. Install sensor switches in the center of their operating

Adjust the mounting position of a sensor switch so that the piston stops in the center of its operating range (the range while the sensor is ON). Operations will be unstable if mounted at the end of the operating range (at the boundary near on and off). Also be aware that the operating range will vary with changes in temperature.

#### 3. Follow the tightening torque guidelines for mounting sensor switches.

Over-tightening beyond the allowed tightening torque may damage the mounting threads, mounting brackets, sensor switches and other components. However, insufficient tightening torque may cause the sensor switch position to change, resulting in unstable operation. Follow the instructions on page (1) concerning the tightening torque.

#### 4. Do not carry the cylinder by its mounted sensor switch's lead wires.

After mounting a sensor switch on the cylinder, do not carry the cylinder by grabbing the lead wires. Never do this, as it may damage not only the lead wires but may also apply stress to the inside of the sensor switch that may damage internal elements.

#### 5. Do not drop the sensor switches or bump them against other objects.

While handling sensor switches, do not subject them to excessive shock (294.2 m/s<sup>2</sup> [30 G] or larger) by hitting, dropping or bumping them.

In the case of reed sensor switches, such behavior may cause the contact to malfunction, thereby giving a signal output or turning off the signal instantaneously. And, this may change the contact interval, thereby deteriorating the sensor switch's sensitivity. As such, this may cause the device to malfunction. Even if the sensor switch case is not damaged, the inside of the sensor switch may be damaged, causing erratic operation.

#### Safety Precautions (Sensor Switches)



Wiring

#### **⚠** DANGER

1. Prevent nearby moving objects from coming into contact with sensor switches.

When cylinders equipped with sensor switches are moving or when moving objects are nearby, do not let them come into contact with each other. In particular, lead wires may become worn or damaged causing unstable operation of the sensor switch. In the worst case, this may result in current leaks or electrical shock.

2. Always turn off the power before doing wiring work. Doing wiring work while the power is on may result in electric shock. Also, incorrect wiring could damage the sensor switch in an instant. Turn on the power only after the wiring work is complete.

#### **∴** WARNING

1. Check the catalog and other materials to ensure that the sensor switch is wired correctly.

Incorrect wiring may result in abnormal operation.

- 2. Do not share wiring with power or high voltage lines. Avoid wiring in parallel to or in the same conduit with power lines and high-voltage lines. Noise from such wiring could cause the sensor switch and control circuit to operate erratically.
- 3. Avoid repeated bending or excessive pulling of lead

Applying repeated bending stress or tension force on the lead wires could break them.

4. Check the wiring polarity.

Be sure that the wiring connections are correct for sensor switches that specify polarity (+, -, output). Incorrect polarity could result in damage to sensor switches.

#### **⚠** CAUTION

1. Avoid short circuiting loads.

Turning on the sensor switch while the load is short-circuited causes overcurrent, which will damage the sensor switch in an instant.

Example of short-circuit load: Sensor switch's output lead wire is directly connected to the power supply.

2. Position sensor switches in the center of their operating range.

Operating output may be unstable, depending on the operating environment, if positioned at the edge of the operating range.

- 3. Solid state sensor switches that are compliant with the EMC standards (EN61000-6-2 and EN60947-5-2) are not resistant to surges from lightning. Use countermeasures on the machine to protect them from lightning surges.
- 4. Use an internal element to absorb surges for direct activation of loads that generate surges.

#### **Handling Instructions and Precautions**



#### **General precautions**

#### **Piping**

Before installing piping to the cylinder, thoroughly flush the inside of the pipes (with compressed air). Machining chips, sealing tape, rust and other debris remaining from the piping work may result in air leaks and malfunctions.

#### Air supply

- 1. Use air as the medium. For the use of any other medium, consult your nearest Koganei sales office.
- 2. Air used for the cylinder should be clean air that contains no degraded compressor oil, etc. Install an air filter (filtration of  $40^{\circ} \mu \, \mathrm{m}$  or less) near the cylinder or valve to remove dust and accumulated liquid. Also drain the air filter periodically. If liquid or dust gets into the cylinder, it may cause defective operation.

#### Lubrication

The cylinder can be used without lubrication, however, if lubrication, such as a lubricator, is used, use turbine oil type 1 (ISO VG32) or an equivalent. Avoid using spindle oil or machine oil.

#### **Environment**

- 1. Cover the unit when using it in locations where it might be subject to excessive dust, dripping water, dripping oil, etc.
- 2. Do not use the cylinder in environments which may be corrosive. Using the cylinder in these types of environments may result in damage or defective operation
- 3. Do not use it in excessively dry conditions.
- 4. Do not use the cylinder if the ambient temperature is over 60°C [140°F], doing so may result in damage or defective operation. Also, consider anti-freezing measures if the temperature is less than 5°C [41°F], because moisture may freeze and result in damage or defective operation.

#### Handling

- 1. Do not place your hands in the way of the cylinder when it is operating.
- 2. Be careful that no part of your body is pinched between the end plate and the cylinder body when the cylinder is retracting.
- 3. Confirm that there is no pressurized air in the cylinder before starting maintenance work.
- 4. Use the cylinder within its operating speed range. Even if the speed is within the allowable range, install an external stopper to prevent directly impacting the cylinder, if the load is large or the allowable kinetic energy is exceeded.
- 5. Use a separate cushioning device, such as a shock absorber, if noise or vibration is an issue.

#### **Warranty and General Disclaimer**

1. Warranty Period

The warranty period for Koganei products is 180 days from the date of delivery.

- 2. Scope of Warranty and General Disclaimer
- (1) The Koganei product warranty covers individual products. When a product purchased from Koganei or from an authorized Koganei distributor malfunctions during the warranty period in a way that is attributable to Koganei responsibility, Koganei will repair or replace the product free of charge. Even if a product is still within the warranty period, its durability is determined by its operation cycles and other factors. Contact your nearest Koganei sales office or the Koganei overseas department for details.
- (2) Koganei shall not be held responsible for any losses or for any damage to other machinery caused by breakdown, loss of function, or loss of performance of Koganei products
- (3) Koganei shall not be held responsible for any losses due to use or storage of the product in a way that is outside of the product specifications prescribed in Koganei catalogs and instruction manuals, and/or due to actions that violate the mounting, installation, adjustment, maintenance or other safety precautions.
- (4) Koganei shall not be held responsible for any losses caused by breakdown of the product due to factors outside the responsibility of Koganei, including but not limited to fire, natural disaster, the actions of third parties, and intentional actions or errors by you.



#### General precautions

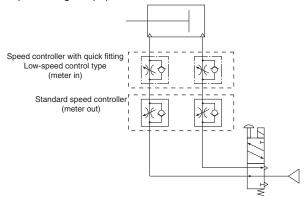
#### Other

The piston of the single acting type may not retract (return) even when the air is exhausted if air is continuously supplied to the piping port so that its spring is left compressed for a long period (more than 48 hours). Use a double acting cylinder if it will be left unused for long periods such as this.

#### About the circuit to prevent rod pop-out

Rod pop-out prevention circuit

Using the cylinder in combination with the speed controller shown in the following diagram is effective for controlling speed and preventing rod pop-out.



Note: Install the speed controller as close as possible to the cylinder.



#### Mounting

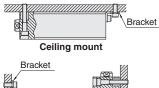
#### Mounting

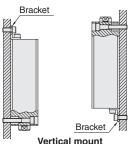
- 1. The cylinder can be mounted in any orientation, but the mounting surface must be flat. If the cylinder twists or bends when mounted, not only will it be inaccurate, but there may be air leaks and defective operation.
- 2. Note that a mounting surface that is scratched or dented can adversely affect flatness.
- 3. If the cylinder is subject to large impacts, use a support structure, such as brackets, to hold the cylinder body in addition to the mounting bolts.
- 4. Be sure that the cylinder body and the mounting bolts are of sufficient strength.
- 5. In cases where loosening of screws due to impact and/or vibration may be a factor, consider looseness prevention
- 6. Do not scratch or dent the sliding parts of the piston rod. Doing so could damage the packing and cause air leaks.
- 7. The piston rod and linear guides are coated with grease, do not wipe it off. Doing so may cause defective operation. If you cannot see the lubricant, apply some grease.
  - The grease to be used depends on the specification. Contact Koganei for details.
- 8. Note that you cannot use the tapped holes on the front-surface (rod side) of the cylinder if you mount it using the counterbored holes on the cylinder body.
  - (Double acting type, single acting push type, single acting pull type, and double acting double rod end type from  $\phi$  10 [0.394 in] to  $\phi$  32 [1.260 in])
- 9. If you are using a combination of a cylinder and guide, use cylinder joints for flexible connections.

#### Mounting with brackets

We recommend using brackets for mounting if you are using the cylinder in the following conditions. (BCZ-BK□ or -BK)

- : If using a cylinder with a longer than standard Stroke stroke.
- Mounting: If using a vertical or ceiling mount for a cylinder with a long stroke (guideline: Products with bore of  $\phi$  20 [0.787 in] or greater and stroke of 50 mm [1.97 in] or longer).
- Process : If using a cylinder for large static loads, such as for pressing processes.
- Other : If using a cylinder in a location subject to extreme vibrations.





#### **Tightening torque lists**

#### Fittings

	N•m [in•lbf]
Thread size	Tightening torque
M3×0.5	0.7 [6.196]
M5×0.8	1.0 to 1.5 [8.851 to 13.277]
R1/8	7 to 9 [61.957 to 79.659]
R1/4	12 to 14 [106.212 to 123.914]
R3/8	22 to 24 [194.722 to 212.424]

Workpiece mounting (Cylinder with guide)

	N•m  in•lbt
Thread size	Tightening torque
M3×0.5	0.63 [5.576]
M4×0.7	1.5 [13.277]
M5×0.8	3.0 [26.553]
M6×1	5.2 [46.025]

## Plugs (Cylinder with guide)

	[וטויוון ווויוון
Thread size	Tightening torque
M3×0.5	0.3 [2.655]
M5×0.8	0.4 [3.540]

Cylinder & bracket mounting			
		N•m [in•lbf]	
Thread size	Tightening torque		
Tilleau Size	Cylinder	Bracket	
M3×0.5	1.2	[10.621]	
M4×0.7	2.7	[23.898]	
M5×0.8	5.4	[47.795]	
M6×1	9.2	[81.429]	
M8×1.25	22 [1	94.722]	
M10×1.5	44 [389.444] 76 [672.676]		
M12×1.75			
M16×2	190 [1	681.7]	
M20×2.5	370 [3	274.9]	

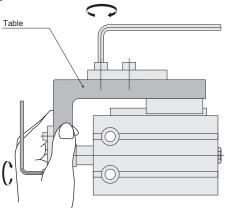
<sup>\*</sup>For both mounting to cylinder or to a mating surface.

#### Sensor switch mounting

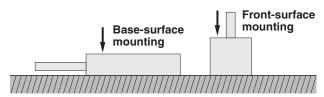
Screw tightening torque: 0.1 N·m to 0.2 N·m [0.885 in·lbf to 1.770 in • lbf]

#### Mounting workpiece to cylinder with guide

- NOTE
  - The table is supported by the linear guide, so be careful to avoid strong impact and excess moment when mounting workpieces.
  - 2. Hold the table when securing the workpiece to the table with bolts. If you hold the body when tightening the bolts, it reduces the precision by applying too large moment on the guide.



#### List of recommended mounting bolts



#### **■**Base-surface mounting

■ Double acting type ■ Single acting type (push, pull) ■ Double rod ■ With guide

	mm [in]
Cylinder bore mm [in]	Recommended mounting bolts
6 [0.236]	M3×12 [0.472]
8 [0.315]	M3×12 [0.472]
10 [0.394]	M3×16 [0.630]
12 [0.472]	M4×16 [0.630]
16 [0.630]	M4×20 [0.787]
20 [0.787]	M5×25 [0.984]
25 [0.984]	M5×30 [1.181]
32 [1.260]	M6×35 [1.378]
40 [1.575]	M8×45 [1.772]
50 [1.969]	M10×55 [2.165]
63 [2.480]	M12×65 [2.559]
80 [3.150]	M12×80 [3.150]
100 [3.937]	M16×110 [4.331]
125 [4.921]	M20×130 [5.118]

Use bolts longer than those in the table above when fastening the cylinder.

#### ■Front-surface mounting

■ Double acting type ■ Single acting type (push, pull) ■ Double rod

Cylinder bore	Recommended mounting bolts			
mm [in]	Double acting type	Single acting type	Double rod	
50 [1.969]	M6×35 [1.378] + stroke	M6×55 [2.165] + stroke	M6×45 [1.772] + stroke	
63 [2.480]	M8×40 [1.575] + stroke	-	M8×50 [1.969] + stroke	
80 [3.150]	M10×45 [1.772] + stroke	-	M10×55 [2.165] + stroke	
100 [3.937]	M10×55 [2.165] + stroke	-	M10×55 [2.165] + stroke	
125 [4.921]	M12×55 [2.165] + stroke	-	M12×55 [2.165] + stroke	

Use bolts longer than those in the table above when fastening the cylinder.

#### Allowable kinetic energy (except cylinder with guide)

Use less kinetic energy on the cylinder than indicated in the table below.

Cylinder bore	Allowable kinetic energy J [ft•lbf]		
mm [in]	Double acting, double rod	Single acting (push & pull)	
6 [0.236]	0.008 [0.006]	0.004 [0.003]	
8 [0.315]	0.014 [0.010]	0.007 [0.005]	
10 [0.394]	0.022 [0.016]	0.012 [0.009]	
12 [0.472]	0.032 [0.024]	0.017 [0.013]	
16 [0.630]	0.057 [0.042]	0.03 [0.022]	
20 [0.787]	0.09 [0.066]	0.05 [0.037]	
25 [0.984]	0.14 [0.103]	0.08 [0.059]	
32 [1.260]	0.23 [0.170]	0.13 [0.096]	
40 [1.575]	0.36 [0.266]	0.21 [0.155]	
50 [1.969]	0.56 [0.413]	0.32 [0.236]	
63 [2.480]	0.89 [0.656]	_	
80 [3.150]	1.4 [1.033]	<u> </u>	
100 [3.937]	2.2 [1.623]	_	
125 [4.921]	3.5 [2.582]	_	

Use the following equation to calculate the kinetic energy of loads.

$$\mathsf{E} \mathsf{x} = \frac{\mathsf{m}}{2} \ v^2 \qquad \qquad \mathsf{E}' \mathsf{x} = \frac{\mathsf{w}'}{2\mathsf{g}'} \ v'^2$$

Ex : Kinetic energy (J) E'x : Kinetic energy [ft-lbf]

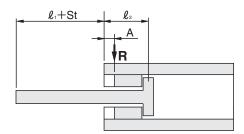
m: Mass of load (kg) w': Load weight [lb]
v: Piston speed (m/s) v': Piston speed [ft/sec]
g': Gravity acceleration 32.2 [ft/sec²]

#### Allowable lateral load (except cylinder with guide)

Apply less than the maximum lateral load to the cylinder than indicated in the table below.

Equation

- $lack \phi$  6 [0.236] to  $\phi$ 12 [0.472],  $\phi$ 50 [1.969] to  $\phi$ 125 [4.9] Maximum allowable lateral load  $W \leqq \frac{\ell_2 A}{\ell_1 + \ell_2 + St} \cdot R$
- $lack \phi$ 16 [0.630] to  $\phi$ 40 [1.575] Maximum allowable lateral load  $W \leq \frac{\ell_2}{\ell_1 + \ell_2 + St} \cdot R$

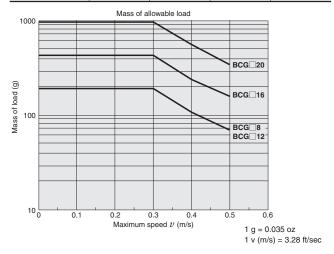


Cylinder bore mm [in]	Allowable lateral load R N [lbf]	ℓ ¹ mm [in]	ℓ ² mm [in]	A mm [in]
6 [0.236]	1.0 [0.225]	4.0 [0.157]	13.8 [0.543]	3.8 [0.150]
8 [0.315]	1.8 [0.405]	4.0 [0.157]	14.3 [0.563]	4.3 [0.169]
10 [0.394]	2.7 [0.607]	4.0 [0.157]	14.4 [0.567]	4.3 [0.169]
12 [0.472]	4.0 [0.899]	5.0 [0.197]	14.0 [0.551]	3.5 [0.138]
16 [0.630]	7.0 [1.574]	5.0 [0.197]	15.0 [0.591]	_
20 [0.787]	11.0 [2.473]	6.0 [0.236]	17.5 [0.689]	_
25 [0.984]	17.2 [3.867]	6.0 [0.236]	18.0 [0.709]	_
32 [1.260]	28.1 [6.317]	7.0 [0.276]	18.5 [0.728]	_
40 [1.575]	44.0 [9.892]	7.0 [0.276]	23.0 [0.906]	_
50 [1.969]	68.7 [15.444]	8.0 [0.315]	27.3 [1.075]	8.0 [0.315]
63 [2.480]	109.1 [24.5]	8.0 [0.315]	33.0 [1.299]	8.0 [0.315]
80 [3.150]	175.9 [39.5]	10.0 [0.394]	32.5 [1.280]	8.0 [0.315]
100 [3.937]	274.9 [61.8]	12.0 [0.472]	44.5 [1.752]	9.0 [0.354]
125 [4.921]	429.5 [96.6]	16.0 [0.630]	50.0 [1.969]	9.0 [0.354]

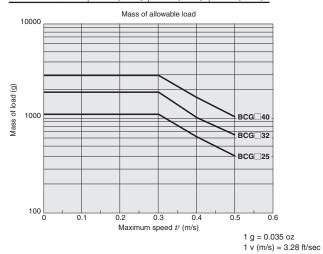
#### **Handling Instructions and Precautions**

#### Cylinder with guide, allowable kinetic energy

① $\phi$ 8 [0.315] to $\phi$ 20 [0.787]				
Model	BCG□8	BCG□12	BCG□16	BCG□20
Allowable kinetic energy J [ft+lbf]	0.0084 [0.006]	0.0084 [0.006]	0.020 [0.015]	0.044 [0.032]

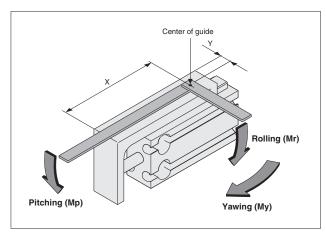


②φ25 [0.984] to φ	J [ft∙lbf		
Model	BCG□25	BCG□32	BCG□40
Allowable kinetic energy J [ft*bf]	0.051 [0.038]	0.082 [0.060]	0.134 [0.099]



#### Allowable bending moment for cylinder with guide

Applying more than the allowable bending moment causes the guide to rattle, reduces precision, and has a bad effect on operating life.



Use the center of the guide as shown in the diagram as the reference for the center of moment.

<ul> <li>Dimensions of center of guide mm [in]</li> </ul>					
Model	Υ				

Model	Stroke	Х	Υ		
	5	31.5			
	10	[1.240]			
	15	41.5			
	20	[1.634]			
	25	51.5			
BCG□8	30	[2.028]	6		
вса∟о	35	61.5	[0.236]		
	40	[2.421]	-		
	45	71.5			
	50	[2.815]			
	55	81.5			
	60	[3.209]			
	5	32.5			
	10	[1.280]			
	15	42.5			
	20	[1.673]			
	25	52.5			
200740	30	[2.067]	7.5		
BCG□12	35	62.5	[0.295]		
	40	[2.461]	[0.200]		
	45	72.5			
	50	[2.854]			
	55	82.5			
	60	[3.248]			
	5	37.5			
	10	[1.476]			
-	15	47.5			
	20	[1.870]			
-	25	57.5			
<b>500</b> 740	30	[2.264]	9.5		
BCG□16	35	67.5	[0.374]		
	40	[2.657]	[]		
	45	77.5			
	50	[3.051]			
	55	87.5			
	60	[3.445]			
	5	44			
	10	[1.732]			
	15	54			
	20	[2.126]			
	25	64			
DOO TOO	30	[2.520]	11.5		
BCG□20	35	74	[0.453]		
	40	[2.913]	[000]		
	45	84			
	50	[3.307]			
	55	94			

Model	Stroke	Х	mm [in]		
	5	47.5			
	10	[1.870]			
	15	57.5			
	20	[2.264]			
	25	67.5			
BCG□25	30	[2.657]	14.5		
BCG∐23	35	77.5	[0.571]		
	40	[3.051]			
	45	87.5			
	50	[3.445]			
	55	97.5			
	60	[3.839]			
	10	57			
		[2.244]			
	15	67	40		
	20	[2.638]			
	25	77			
BCG□32	30	[3.031]	18		
DOG_02	35	87	[0.709]		
	40	[3.425]			
	45	97			
	50	[3.819]			
	55	107			
	60	[4.213]			
	10	70.5			
	15	[2.776]			
	20				
	25	80.5			
	30	[3.169]	23		
BCG□40	35	90.5	[0.906]		
	40	[3.563]	[0.300]		
	45	100.5			
	50	[3.957]			
	55	110.5			
	60	[4.350]			

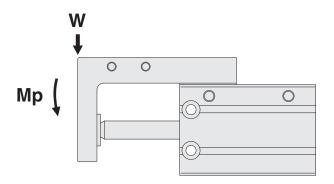
Allowable	Allowable bending moment N·m [in·lbi											
Model	Mp (pitching)	Mr (rolling)	My (yawing)									
BCG□8, BCG□12	0.12 [1.062]	0.12 [1.062]	0.21 [1.859]									
BCG□16	0.4 [3.540]	0.4 [3.540]	0.68 [6.019]									
BCG□20	1.5 [13.277]	1.8 [15.932]	2.2 [19.472]									
BCG□25	2.18 [19.295]	2.18 [19.295]	4.18 [36.997]									
BCG□32	4.46 [39.475]	4.46 [39.475]	7.31 [64.701]									
BCG□40	6.7 [59.302]	8 [70.808]	13.7 [121.259]									

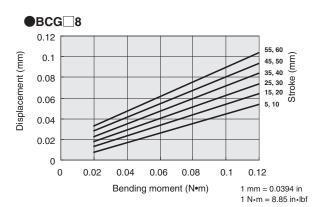
Heat resistant specification N·m [in-lbf]											
Model	Mp (pitching)	Mr (rolling)	My (yawing)								
BCGF8, BCGF12	0.11 [0.974]	0.11 [0.974]	0.18 [1.593]								
BCGF16	0.35 [3.098]	0.35 [3.098]	0.60 [5.311]								
BCGF20	0.88 [7.789]	0.88 [7.789]	1.25 [11.064]								
BCGF25	1.37 [12.126]	1.21 [10.710]	2.30 [20.357]								
BCGF32	3.56 [31.510]	2.99 [26.464]	6.00 [53.106]								
BCGF40	6.32 [55.938]	5.30 [46.910]	11.04 [97.715]								

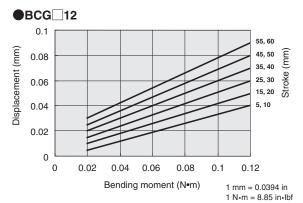
Displacement of table due to bending moment for cylinder with guide (reference values) For heat resistant specification graphs, refer to page 18.

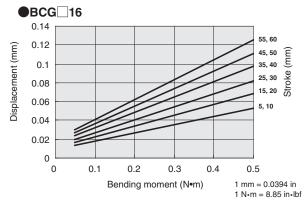
#### Pitching (Mp)

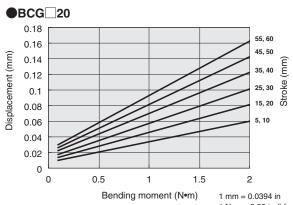
Displacement of edge of table (arrow) when load W is applied at arrow (Precaution: There may be a large increase in the displacement after a large impact load is applied to the table)

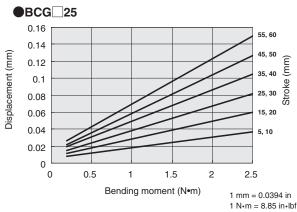


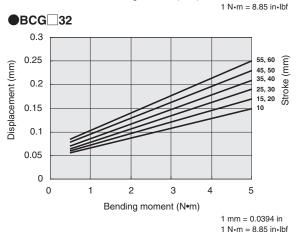


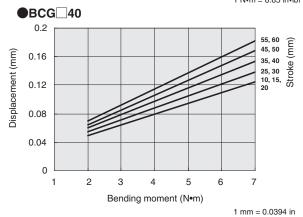








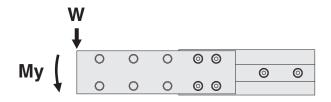


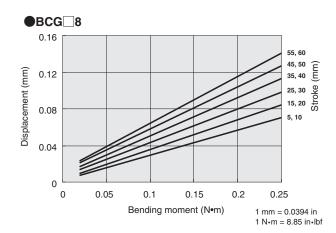


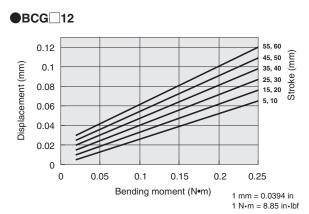
Displacement of table due to bending moment for cylinder with guide (reference values) For heat resistant specification graphs, refer to page 19.

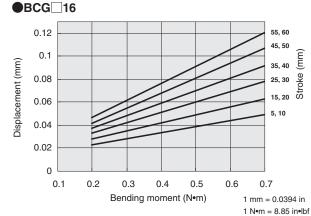
#### Yawing (My)

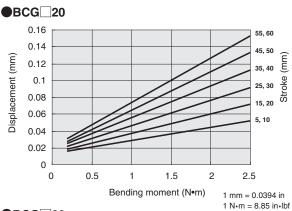
Displacement of edge of table (arrow) when load W is applied at arrow (Precaution: There may be a large increase in the displacement after a large impact load is applied to the table)

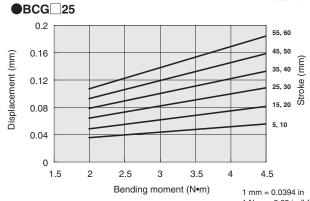


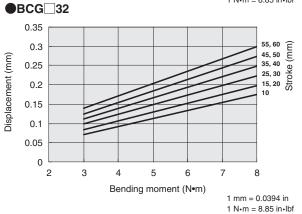


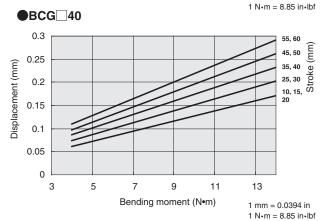








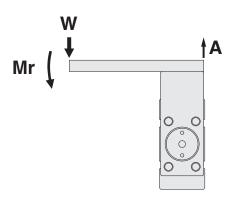


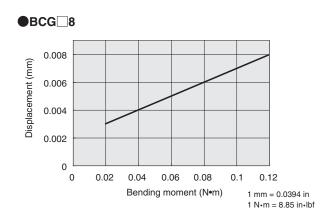


Displacement of table due to bending moment for cylinder with guide (reference values) For heat resistant specification graphs, refer to page @ .

#### Rolling (Mr)

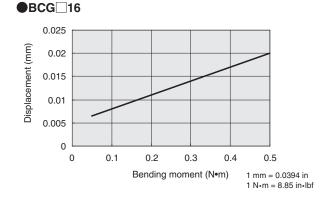
Displacement of edge of table (arrow A) when load W is applied at arrow (Precaution: There may be a large increase in the displacement after a large impact load is applied to the table)

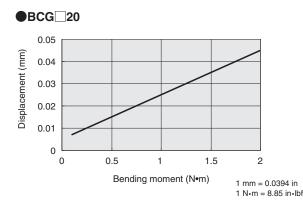


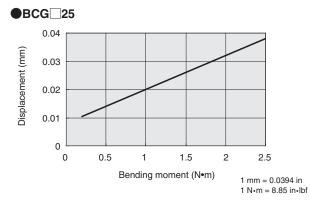


#### **●BCG** 12 0.01 0.008 Displacement (mm) 0.006 0.004 0.002 0 0.02 0.04 0.06 0.08 0.1 0.12 Bending moment (N•m) 1 mm = 0.0394 in

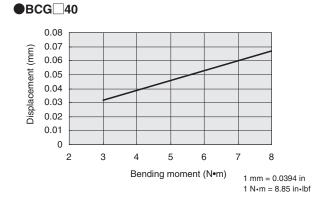
1 N·m = 8.85 in · lbf







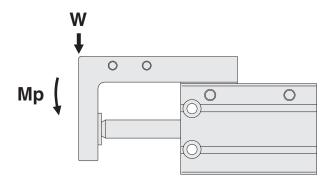


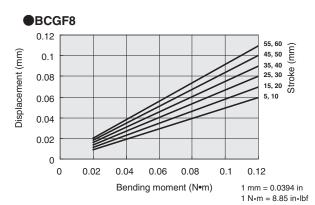


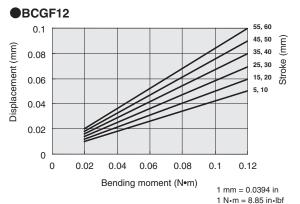
Displacement of table due to bending moment for heat resistant specification cylinder with guide (reference values)

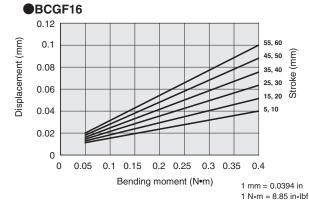
#### Pitching (Mp)

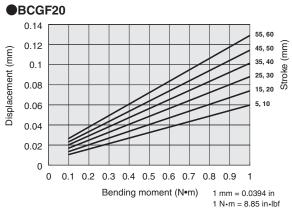
Displacement of edge of table (arrow) when load W is applied at arrow (Precaution: There may be a large increase in the displacement after a large impact load is applied to the table)

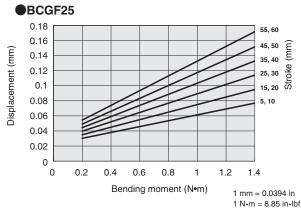


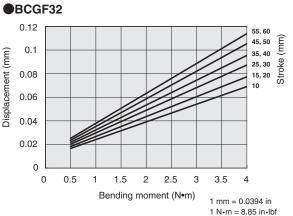


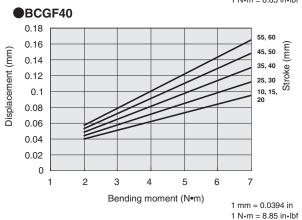








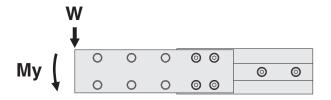


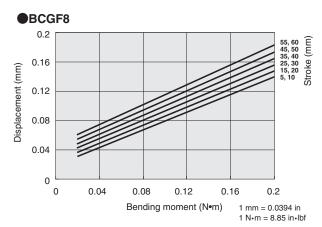


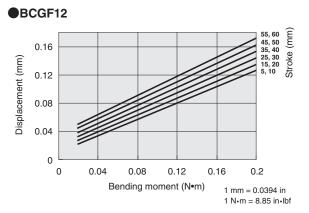
Displacement of table due to bending moment for heat resistant specification cylinder with guide (reference values)

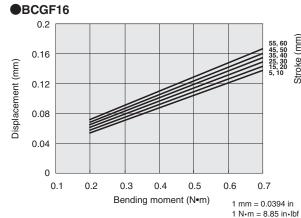
#### Yawing (My)

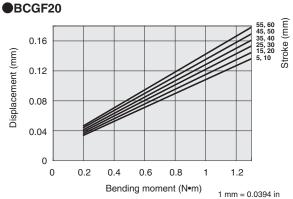
Displacement of edge of table (arrow) when load W is applied at arrow (Precaution: There may be a large increase in the displacement after a large impact load is applied to the table)

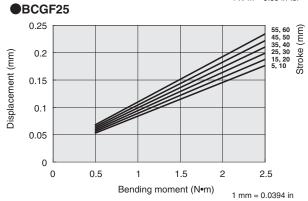


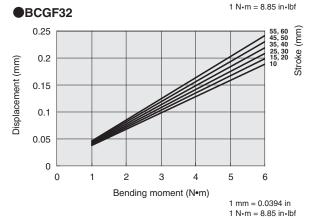


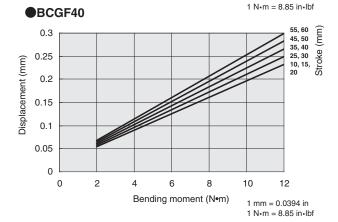












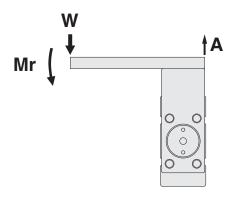
Displacement of table due to bending moment for heat resistant specification cylinder with guide (reference values)

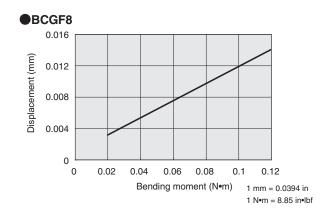
1 mm = 0.0394 in

1 N•m = 8.85 in•lbf

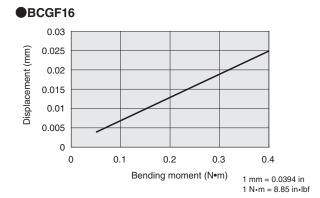
#### Rolling (Mr)

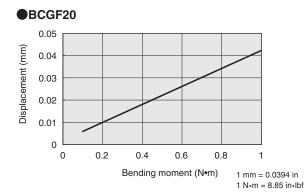
Displacement of edge of table (arrow A) when load W is applied at arrow (Precaution: There may be a large increase in the displacement after a large impact load is applied to the table)

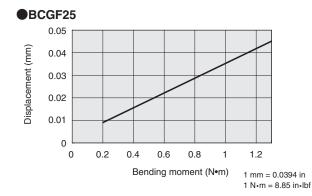


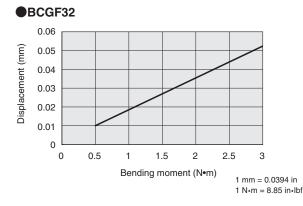


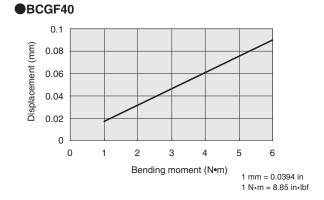
#### ●BCGF12 0.016 Displacement (mm) 0.012 0.008 0.004 0 0 0.02 0.04 0.06 0.08 0.1 0.12 Bending moment (N•m)











#### **Handling Instructions and Precautions**

#### **Thrust**

#### Double acting type

unit: N

Cylinder bore	Piston rod diameter	0	Pressure area			А	ir pressure MF	'a	1	
mm	mm	Operation	mm <sup>2</sup>	0.1	0.2	0.3	0.4	0.5	0.6	0.7
6	4	Push side	28.3	2.8	5.7	8.5	11.3	14.2	17.0	19.8
в	4	Pull side	15.7	1.6	3.1	4.7	6.3	7.9	9.4	11.0
8	5	Push side	50.3	5.0	10.1	15.1	20.1	25.2	30.2	35.2
0	9	Pull side	30.6	3.1	6.1	9.2	12.2	15.3	18.4	21.4
10	5	Push side	78.5	7.9	15.7	23.6	31.4	39.3	47.1	55.0
10	5	Pull side	58.9	5.9	11.8	17.7	23.6	29.5	35.3	41.2
12	6	Push side	113.0	11.3	22.6	33.9	45.2	56.5	67.8	79.1
12		Pull side	84.8	8.5	17.0	25.4	33.9	42.4	50.9	59.4
16	8	Push side	201.0	20.1	40.2	60.3	80.4	100.5	120.6	140.7
		Pull side	150.0	15.0	30.0	45.0	60.0	75.0	90.0	105.0
20	10	Push side	314.0	31.4	62.8	94.2	125.6	157.0	188.4	219.8
20	10	Pull side	235.5	23.6	47.1	70.7	94.2	117.8	141.3	164.9
25	12	Push side	490.6	49.1	98.1	147.2	196.2	245.3	294.4	343.4
	12	Pull side	377.6	37.8	75.5	113.3	151.0	188.8	226.6	264.3
32	16	Push side	803.8	80.4	160.8	241.1	321.5	401.9	482.3	562.7
	10	Pull side	602.9	60.3	120.6	180.9	241.2	301.5	361.7	422.0
40	16	Push side	1256.0	125.6	251.2	376.8	502.4	628.0	753.6	879.2
	10	Pull side	1055.0	105.5	211.0	316.5	422.0	527.5	633.0	738.5
50	20	Push side	1962.5	196.3	392.5	588.8	785.0	981.3	1177.5	1373.8
	20	Pull side	1648.5	164.9	329.7	494.6	659.4	824.3	989.1	1154.0
63	20	Push side	3115.7	311.6	623.1	934.7	1246.3	1557.9	1869.4	2181.0
	20	Pull side	2801.7	280.2	560.3	840.5	1120.7	1400.9	1681.0	1961.2
80	25	Push side	5024.0	502.4	1004.8	1507.2	2009.6	2512.0	3014.4	3516.8
- 00	20	Pull side	4533.4	453.3	906.7	1360.0	1813.4	2266.7	2720.0	3173.4
100	30	Push side	7850.0	785.0	1570.0	2355.0	3140.0	3925.0	4710.0	5495.0
	30	Pull side	7143.5	714.4	1428.7	2143.1	2857.4	3571.8	4286.1	5000.5
125	35	Push side	12265.6	1226.6	2453.1	3679.7	4906.3	6132.8	7359.4	8585.9
123	35	Pull side	11304.0	1130.4	2260.8	3391.2	4521.6	5652.0	6782.4	7912.8

## ■ Single acting type

unit: N

Operating	Cylinder bore	Piston rod diameter	Pressure area			Air press	ure MPa			Spring return force	
type	mm	mm	mm <sup>2</sup>	0.2	0.3	0.4	0.5	0.6	0.7	(at end of stroke)	
	6	4	28.3	2.5	5.3	8.1	11.0	13.8	16.6	3.16	
	8	5	50.3	3.6	8.6	13.6	18.7	23.7	28.7	6.5	
	10	5	78.5	8.5	16.4	24.2	32.1	39.9	47.8	7.17	
<u> </u>	12	6	113.0	12.7	24.0	35.3	46.6	57.9	69.2	9.9	
Single	16	8	201.0	23.8	43.9	64.0	84.1	104.2	124.3	16.4	
acting push type	20	10	314.0	46.4	77.8	109.2	140.6	172.0	203.4	16.4	
pusit type	25	12	490.6	77.8	126.9	175.9	225.0	274.1	323.1	20.3	
	32	16	803.8	127.8	208.1	288.5	368.9	449.3	529.7	33	
	40	16	1256.0	211.7	337.3	462.9	588.5	714.1	839.7	39.5	
	50	20	1962.5	338.8	535.1	731.3	927.6	1123.8	1320.1	53.7	
	6	4	15.7	_	1.3	2.8	4.4	6.0	7.5	3.45	
	8	5	30.6	_	2.0	5.1	8.1	11.2	14.3	7.17	
	10	5	58.9	4.6	10.5	16.4	22.3	35.3	34.2	7.17	
<u>.</u> . [	12	6	84.8	7.1	15.5	24.0	32.5	41.0	49.5	9.9	
Single	16	8	150.0	13.6	28.6	43.6	58.6	73.6	88.6	16.4	
acting pull type	20	10	235.5	30.7	54.3	77.8	101.4	124.9	148.5	16.4	
pan type	25	12	377.6	55.2	93.0	130.7	168.5	206.3	244.0	20.3	
	32	16	602.9	87.6	147.9	208.2	268.5	328.7	389.0	33	
	40	16	1055.0	171.5	277.0	382.5	488.0	593.5	699.0	39.5	
	50	20	1648.5	276.0	440.9	605.7	770.6	935.4	1100.3	53.7	

#### Double acting type

unit: lbf

Cylinder bore	Piston rod diameter	0	Pressure area				Air pressure p	si		
in	in	Operation	in <sup>2</sup>	15	29	44	58	73	87	102
0.236	0.157	Push side	0.044	0.629	1.281	1.911	2.540	3.192	3.822	4.451
0.236	0.157	Pull side	0.024	0.360	0.697	1.057	1.416	1.776	2.113	2.473
0.315	0.197	Push side	0.078	1.124	2.271	3.395	4.519	5.665	6.789	7.913
0.315	0.197	Pull side	0.047	0.697	1.371	2.068	2.743	3.440	4.136	4.811
0.394	0.197	Push side	0.122	1.776	3.530	5.305	7.059	8.835	10.589	12.364
0.394	0.197	Pull side	0.091	1.326	2.653	3.979	5.305	6.632	7.936	9.262
0.472	0.236	Push side	0.2	2.540	5.081	7.621	10.161	12.702	15.242	17.782
0.472	0.236	Pull side	0.131	1.911	3.822	5.710	7.621	9.532	11.443	13.354
0.630	0.315	Push side	0.3	4.519	9.037	13.556	18.075	22.6	27.1	31.6
0.630	0.315	Pull side	0.2	3.372	6.744	10.116	13.489	16.861	20.233	23.6
0.787	0.394	Push side	0.5	7.059	14.118	21.177	28.2	35.3	42.4	49.4
0.767	0.394	Pull side	0.4	5.305	10.589	15.894	21.177	26.5	31.8	37.1
0.984	0.472	Push side	0.8	11.038	22.054	33.1	44.1	55.1	66.2	77.2
	0.472	Pull side	0.6	8.498	16.973	25.5	33.9	42.4	50.9	59.4
1,260	0.630	Push side	1.2	18.075	36.1	54.2	72.3	90.4	108.4	126.5
1.200	0.630	Pull side	0.9	13.556	27.1	40.7	54.2	67.8	81.3	94.9
1.575	0.630	Push side	2	28.2	56.5	84.7	112.9	141.2	169.4	197.7
1.575	0.630	Pull side	2	23.7	47.4	71.2	94.9	118.6	142.3	166.0
1.969	0.787	Push side	3	44.1	88.2	132.4	176.5	220.6	265	309
1.505	0.767	Pull side	3	37.1	74.1	111.2	148.2	185.3	222.4	259
2.480	0.787	Push side	5	70.1	140.1	210.1	280	350	420	490
2.400	0.767	Pull side	4	63.0	126.0	189.0	252	315	378	441
3.150	0.984	Push side	8	112.9	226	339	452	565	678	791
3.130	0.304	Pull side	7	101.9	203.8	306	408	510	611	713
3.9	1.181	Push side	12	176.5	353	529	706	882	1059	1235
3.9	1.101	Pull side	11	160.6	321	482	642	803	964	1124
4.9	1.378	Push side	19	276	551	827	1103	1379	1654	1930
4.9	1.370	Pull side	18	254	508	762	1016	1271	1525	1779

## ■ Single acting type

unit: lbf

Operating	Cylinder bore	Piston rod diameter	Pressure area			Air pres	sure psi			Spring return force
type	in	in	in <sup>2</sup>	29	44	58	73	87	102	(at end of stroke)
	0.236	0.157	0.044	0.562	1.191	1.821	2.473	3.102	3.732	0.710
	0.315	0.197	0.078	0.809	1.933	3.057	4.204	5.328	6.452	1.461
	0.394	0.197	0.122	1.911	3.687	5.440	7.216	8.970	10.746	1.612
0	0.472	0.236	0.2	2.855	5.395	7.936	10.476	13.016	15.557	2.226
Single	0.630	0.315	0.3	5.350	9.869	14.388	18.906	23.4	27.9	3.687
acting push type	0.787	0.394	0.5	10.431	17.490	24.5	31.6	38.7	45.7	3.687
pusit type	0.984	0.472	0.8	17.490	28.5	39.5	50.6	61.6	72.6	4.564
	1.260	0.630	1.2	28.7	46.8	64.9	82.9	101.0	119.1	7.419
	1.575	0.630	2	47.6	75.8	104.1	132.3	160.5	188.8	8.880
	1.969	0.787	3	76.2	120.3	164.4	208.5	253	297	12.072
	0.236	0.157	0.024	_	0.292	0.629	0.989	1.349	1.686	0.776
	0.315	0.197	0.047	_	0.450	1.147	1.821	2.518	3.215	1.612
	0.394	0.197	0.091	1.034	2.360	3.687	5.013	7.936	7.688	1.612
a	0.472	0.236	0.131	1.596	3.485	5.395	7.306	9.217	11.128	2.226
Single acting	0.630	0.315	0.2	3.057	6.430	9.802	13.174	16.546	19.918	3.687
pull type	0.787	0.394	0.4	6.902	12.207	17.490	22.8	28.1	33.4	3.687
pull type	0.984	0.472	0.6	12.409	20.907	29.4	37.9	46.4	54.9	4.564
	1.260	0.630	0.9	19.693	33.2	46.8	60.4	73.9	87.5	7.419
	1.575	0.630	2	38.6	62.3	86.0	109.7	133.4	157.1	8.880
	1.969	0.787	3	62.0	99.1	136.2	173.2	210.3	247	12.072

## **Basic Cylinders**

## Clean system compatible cylinders Cylinder with guide

#### **Symbol**





#### Specifications (clean room specification)

Item	Cylinder bore	8 [0.315]	12 [0.472]	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]	40 [1.575]	
Operating type					Double acting type	9			
Medium					Air				
Operating pressure	range MPa [psi]	0.2 to 0.7 [29 to 102]	0.1 to 0.7	[15 to 102]		0.08 to 0.7	[12 to 102]		
Proof pressure	MPa [psi]				1.05 [152]				
Operating temperature	range °C [°F]				0 to 60 [32 to 140]				
Operating speed range	mm/s [in/sec]	50 to 300 [1.969 to 11.8]							
Cushion		Rubber bumper							
Lubrication		No							
Port size		M3×0.5	M3×0.5 M5×0.8 Rc1/8						
Running parallelism	mm [in]				0.1 [0.004] or less				
Allassable second	Pitching	0.12 [	1.062]	0.40 [3.540]	1.50 [13.277]	2.18 [19.295]	4.46 [39.475]	6.70 [59.302]	
Allowable moment	Rolling	0.12 [	1.062]	0.40 [3.540]	1.80 [15.932]	2.18 [19.295]	4.46 [39.475]	8.00 [70.808]	
N•m [in•lbf]	Yawing	0.21 [	1.859]	0.68 [6.019]	2.20 [19.472]	4.18 [36.997]	7.31 [64.701]	13.70 [121.259]	
Clean room ratingNot	e 1		С	lass 6 equivalent	FED-STD Class 1	000 equivalent)Not	te 2		

Note 1: Koganei standard. Dust collection port not available.

#### Linear guide being used

Cylinder bore	Rail width	Manufacturer			
φ8 [0.315], φ12 [0.472]	5 [0.197]				
φ 16 [0.630]	7 [0.276]				
φ <b>20</b> [0.787]	9 [0.354]	THK			
φ <b>25</b> [0.984]	12 [0.472]	IUV			
φ <b>32</b> [1.260]	15 [0.591]				
φ <b>40</b> [1.575]	20 [0.787]				

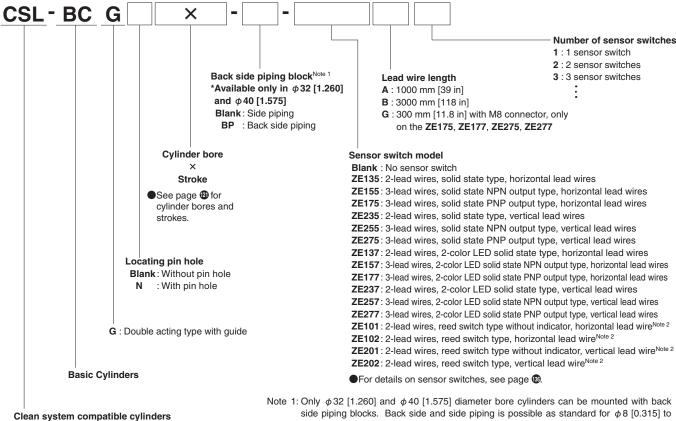
#### Cylinder bore and stroke

Cylinder bore	Standard stroke				
8, 12, 16, 20, 25 [0.315, 0.472, 0.630, 0.787, 0.984]	5 <sup>Note</sup> , 10, 15 <sup>Note</sup> , 20, 25 <sup>Note</sup> , 30, 35 <sup>Note</sup> , 40, 45 <sup>Note</sup> , 50, 55 <sup>Note</sup> , 60				
32 [1.260]	10, 15 <sup>Note</sup> , 20, 25 <sup>Note</sup> , 30, 35 <sup>Note</sup> , 40, 45 <sup>Note</sup> , 50, 55 <sup>Note</sup> , 60				
40 [1.575]	10 <sup>Note</sup> , 15 <sup>Note</sup> , 20, 25 <sup>Note</sup> , 30, 35 <sup>Note</sup> , 40, 45 <sup>Note</sup> , 50, 55 <sup>Note</sup> , 60				

Note: Collar stopper is used in this stroke.

<sup>2:</sup> FED-STD was abolished as of November 2001, and it is designed here for reference purposed.

#### Cylinder with guide



side piping blocks. Back side and side piping is possible as standard for  $\phi$ 8 [0.315] to  $\phi$ 25 [0.984] models. 2: Reed type sensor switches cannot be attached to cylinders that have  $\phi$ 8 [0.315] and  $\phi$ 

2: Heed type sensor switches cannot be attached to cylinders that have  $\phi \in [0.315]$  and  $\phi = 12[0.472]$  cylinder bores.

#### Mass

#### Cylinder with guide

(Without dust collection port)

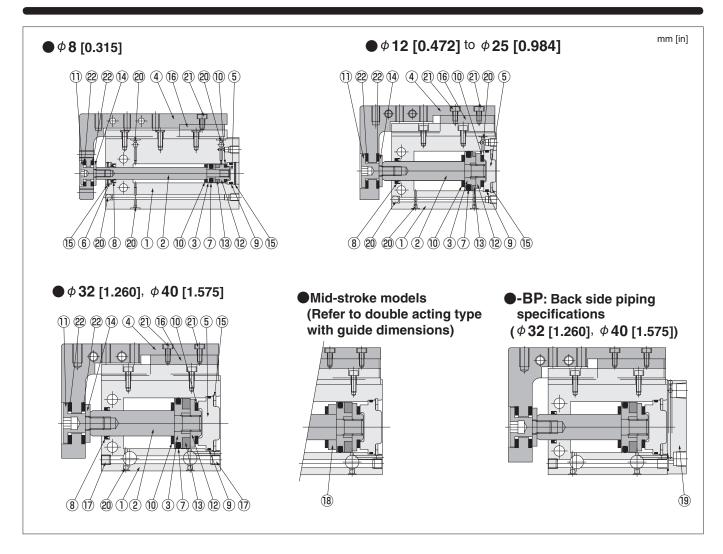
g [oz]

Model		Stroke mm [in]											
Model	5 [0.197]	10 [0.394]	15 [0.591]	20 [0.787]	25 [0.984]	30 [1.181]	35 [1.378]	40 [1.575]	45 [1.772]	50 [1.969]	55 [2.165]	60 [2.362]	
CSL-BCG8	56 [1.975]	54 [1.905]	68 [2.399]	66 [2.328]	80 [2.822]	78 [2.751]	92 [3.245]	90 [3.175]	104 [3.7]	102 [3.6]	116 [4.1]	114 [4.0]	
CSL-BCG12	82 [2.892]	81 [2.857]	96 [3.386]	95 [3.351]	110 [3.9]	109 [3.8]	124 [4.4]	123 [4.3]	138 [4.9]	137 [4.8]	152 [5.4]	151 [5.3]	
CSL-BCG16	133 [4.7]	131 [4.6]	155 [5.5]	153 [5.4]	178 [6.3]	176 [6.2]	200 [7.1]	198 [7.0]	222 [7.8]	220 [7.8]	245 [8.6]	243 [8.6]	
CSL-BCG20	207 [7.3]	205 [7.2]	236 [8.3]	234 [8.3]	265 [9.3]	263 [9.3]	294 [10.4]	292 [10.3]	323 [11.4]	321 [11.3]	352 [12.4]	350 [12.3]	
CSL-BCG25	321 [11.3]	317 [11.2]	366 [12.9]	362 [12.8]	411 [14.5]	407 [14.4]	456 [16.1]	452 [15.9]	501 [17.7]	497 [17.5]	546 [19.3]	542 [19.1]	
CSL-BCG32	_	597 [21.1]	675 [23.8]	669 [23.6]	746 [26.3]	740 [26.1]	818 [28.9]	812 [28.6]	889 [31.4]	883 [31.1]	961 [33.9]	955 [33.7]	
CSL-BCG40	_	1031 [36]	1025 [36]	1019 [36]	1122 [40]	1116 [39]	1219 [43]	1213 [43]	1316 [46]	1310 [46]	1413 [50]	1407 [50]	

In the case of back side piping specifications, mass is 76 g [2.68 oz] for a  $\phi$  32 [1.260] cylinder bore and 108 g [3.8 oz] for a  $\phi$  40 [1.575] cylinder bore.

#### Additional mass of sensor switches

**ZE A**, **ZE G**: 15 g [0.53 oz] **ZE B**: 35 g [1.23 oz]

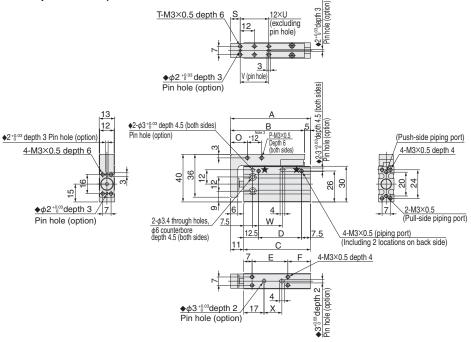


#### Major parts and materials (clean room specification)

	1													
No.	Name	φ8 [0.315]	$\phi$ 12 [0.472]	φ <b>16</b> [0.630]	φ <b>20</b> [0.787]	φ <b>25</b> [0.984]	φ32 [1.260]	φ <b>40</b> [1.575]						
	Cylinder body			Aluminum alle	oy (special anti-abra	asion treated)								
2	Piston rod				Stainless steel									
3	Piston	Stainles	ss steel		Alur	minum alloy (anodi:	zed)							
4	Table			Aluı	minum alloy (anodiz	zed)								
(5)	Head cover			Aluı	minum alloy (anodiz	zed)								
6	Seal holder	Aluminum alloy (Anodized)	_	_	_	_	_	_						
7	★ Piston seal	Synthetic rubber (NBR)												
8	★ Rod seal	Synthetic rubber (NBR)												
9	★ O-ring			Sy	nthetic rubber (NB	R)								
10	Bumper			Sy	nthetic rubber (NB	R)								
11)	End bolt				Stainless steel									
(12)	Support			Aluı	minum alloy (anodiz	zed)								
13)	Magnet		ı	Neodymium magne	t		Plastic	magnet						
14)	Bolt retainer				Stainless steel									
(15)	★ Retaining ring	Stainless steel			Steel (electroles	ss nickel plated)								
16)	Linear guide				Stainless steel									
17)	Plug	_	_	_	_	_	Stainle	ss steel						
(18)	Collar			Aluı	minum alloy (anodiz	zed)								
19	★ Back side piping block	_	_	_	_	-	Aluminum all	oy (anodized)						
20	Steel ball				Stainless steel									
<u>21</u> )	Bolt				Stainless steel									
22	Bumper				Urethane rubber									

Items indicated by a ★ are available as additional parts or in packing sets. For order codes, see page @ and @.

#### ●CSL-BCG 8 (clean room specification)



Stroke	Α	В	С	D	Е	F	0	Р	S	Т	U	٧	W	Χ
5, 10	47	42	36	16	15	14	10	2	5	4	-	12	15	10
15, 20	57	52	46	26	20	19	14	4	8	4	-	12	15	15
25, 30	67	62	56	36	30	19	14	4	8	6	2	24	25	15
35, 40	77	72	66	46	40	19	14	4	8	8	3	24	25	25
45, 50	87	82	76	56	50	19	14	4	8	10	4	36	35	35
55, 60	97	92	86	66	60	19	14	4	8	12	5	36	35	45

Note 1: This product cannot use reed switch type sensor switches.

Note 2:5, 15, 25, 35, 45, and 55 stroke has a collar stopper. Note 3: Dimensions indicated by \* are for strokes longer than 15.

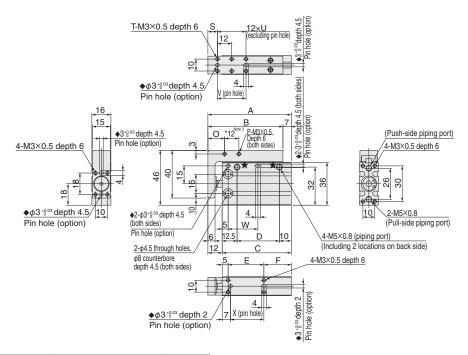
Note 4: All piping ports are assembled with plugs, except those indicated

by ★.

Note 5: Apply grease to o-rings when changing plug assemblies.

Note 6: Pin holes indicated by ◆ are provided only when selected as an option (N).

#### ●CSL-BCG□12 (clean room specification)



Stroke	Α	В	С	D	Е	F	0	Р	S	Т	U	V	W	Х
5, 10	50	43	38	15.5	15	18	10	2	5	4	-	12	15	13
15, 20	60	53	48	25.5	20	23	14	4	8	4	-	12	15	18
25, 30	70	63	58	35.5	30	23	14	4	8	6	2	24	25	28
35, 40	80	73	68	45.5	40	23	14	4	8	8	3	24	25	38
45, 50	90	83	78	55.5	50	23	14	4	8	10	4	36	35	48
55, 60	100	93	88	65.5	60	23	14	4	8	12	5	36	35	58

Note 1: This product cannot use reed switch type sensor switches.

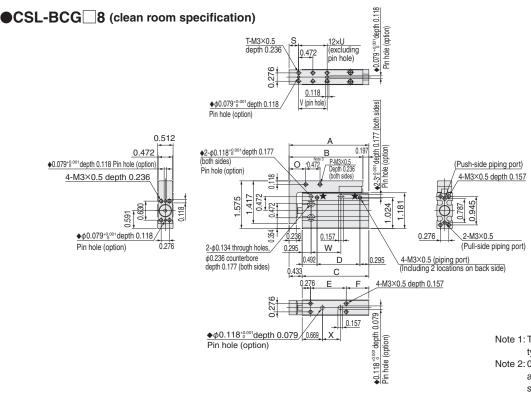
Note 2: 5, 15, 25, 35, 45, and 55 stroke has a collar stopper.

Note 3: Dimensions indicated by  $^{\star}$  are for strokes longer than 15.

Note 4: All piping ports are assembled with plugs, except those indicated by  $\bigstar$ .

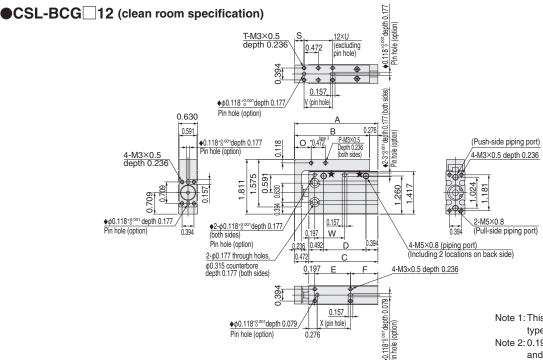
Note 5: Apply grease to o-rings when changing plug assemblies.

Note 6: Pin holes indicated by ◆ are provided only when selected as an option (N).



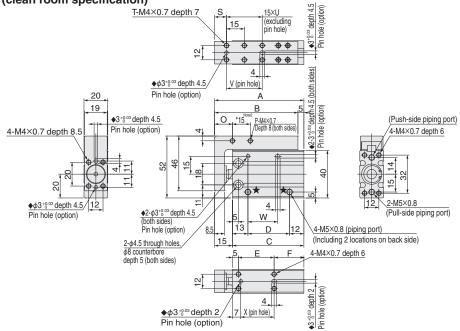
Stroke В С D Ε F 0 Р S Т U V W Χ Α 5 mm, 10 mm [0.197, 0.394] 1.654 1.417 0.630 0.591 0.551 0.394 0.079 0.197 0.157 0.472 0.591 0.394 1.850 **15 mm, 20 mm [0.591, 0.787]** 2.244 2.047 1.811 1.024 0.787 0.748 0.551 0.157 0.315 0.157 0.472 0.591 0.591 25 mm, 30 mm [0.984, 1.181] 2.638 0.236 0.945 0.591 2.441 2.205 1.417 1.181 0.748 0.551 0.157 0.315 0.079 0.984 35 mm, 40 mm [1.378, 1.575] 3.031 0.984 2.835 2.598 1.811 1.575 0.748 0.551 0.157 0.315 0.315 0.118 0.945 0.984 45 mm, 50 mm [1.772, 1.969] 3.425 3.228 2.992 2.205 1.969 0.748 0.551 0.157 0.315 0.394 0.157 1.417 1.378 1.378 55 mm, 60 mm [2.165, 2.362] 3.819 2.362 0.315 0.472 0.197 3.622 3.386 2.598 0.748 0.551 0.157 1.417 1.378 1.772

- Note 1: This product cannot use reed switch type sensor switches.
- Note 2: 0.197, 0.591, 0.984, 1.378, 1.772, and 2.165 stroke has a collar stopper.
- Note 3: Dimensions indicated by \* are for strokes longer than 0.591.
- Note 4: All piping ports are assembled with plugs, except those indicated by ★.
- Note 5: Apply grease to o-rings when changing plug assemblies.
- Note 6: Pin holes indicated by ♠ are provided only when selected as an option (N).



- С Е F 0 Р S U ٧ W Х Stroke В D Т 5 mm, 10 mm [0.197, 0.394] 1.693 1.496 0.610 0.591 0.709 0.394 0.079 0.197 0.157 0 472 0.591 0.512 1.969 15 mm, 20 mm [0.591, 0.787] 2.362 2.087 1.890 1.004 0.787 0.906 0.551 0.157 0.315 0.157 0.472 0.591 0.709 25 mm, 30 mm [0.984, 1.181] 2.756 2.480 2.283 1.398 1.181 0.906 0.551 0.157 0.315 0.236 0.079 0.945 0.984 1.102 35 mm, 40 mm [1.378, 1.575] 3.150 2.874 2.677 1.791 1.575 0.906 0.551 0.157 0.315 0.315 0.118 0.945 0.984 1.496 45 mm, 50 mm [1.772, 1.969] 1.890 3.543 3.268 3.071 2.185 1.969 0.906 0.551 0.157 0.315 0.394 0.157 1.417 1.378 55 mm, 60 mm [2.165, 2.362] 3.937 3.661 3.465 2.579 2.362 0.906 0.551 0.157 0.315 0.472 0.197 1.417 1.378 2.283
- Note 1: This product cannot use reed switch type sensor switches.
- Note 2: 0.197, 0.591, 0.984, 1.378, 1.772, and 2.165 stroke has a collar stopper.
- Note 3: Dimensions indicated by \* are for strokes longer than 0.591.
- Note 4: All piping ports are assembled with plugs, except those indicated by ★
- Note 5: Apply grease to o-rings when changing plug assemblies.
- Note 6: Pin holes indicated by ♠ are provided only when selected as an option (N).



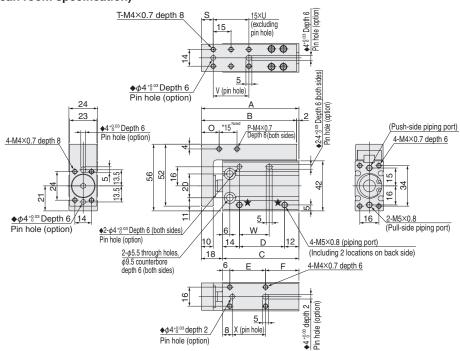


Stroke	Α	В	С	D	Е	F	0	Р	S	Т	U	V	W	Х
5, 10	55	50	40	15	15	20	12	2	5	4	-	15	15	13
15, 20	65	60	50	25	20	25	15	4	10	4	-	15	15	18
25, 30	75	70	60	35	30	25	15	4	10	6	2	30	25	28
35, 40	85	80	70	45	40	25	15	4	10	6	2	30	25	38
45, 50	95	90	80	55	50	25	15	4	10	8	3	45	35	48
55, 60	105	100	90	65	60	25	15	4	10	10	4	45	35	58

Note 1:5, 15, 25, 35, 45, and 55 stroke support collar stopper.

- Note 2: Dimensions indicated by \* are for strokes longer than 15.
- Note 3: All piping ports are assembled with plugs, except those indicated by  $\bigstar$ .
- Note 4: Apply grease to o-rings when changing plug assemblies.
- Note 5: Pin holes indicated by ◆ are provided only when selected as an option (N).

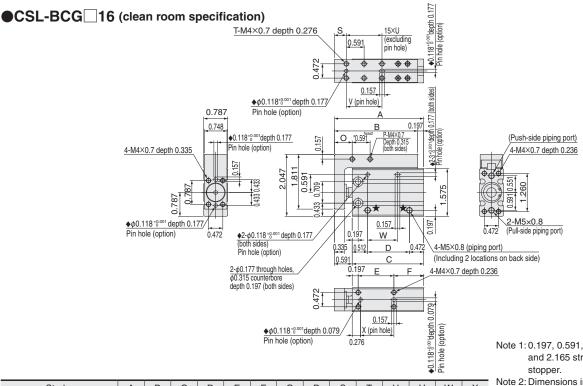
#### ●CSL-BCG 20 (clean room specification)



Stroke	Α	В	С	D	Е	F	0	Р	S	Т	U	V	W	Х
5, 10	62	60	44	18	15	23	12	2	5	4	-	15	15	13
15, 20	72	70	54	28	20	28	15	4	10	4	-	15	15	18
25, 30	82	80	64	38	30	28	15	4	10	6	2	30	25	28
35, 40	92	90	74	48	40	28	15	4	10	6	2	30	25	38
45, 50	102	100	84	58	50	28	15	4	10	8	3	45	35	48
55, 60	112	110	94	68	60	28	15	4	10	10	4	45	35	58

Note 1: 5, 15, 25, 35, 45, and 55 stroke support collar stopper.

- Note 2: Dimensions indicated by  $^{\star}$  are for strokes longer than 15.
- Note 3: All piping ports are assembled with plugs, except those indicated by  $\bigstar$ .
- Note 4: Apply grease to o-rings when changing plug assemblies.
- Note 5: Pin holes indicated by ◆ are provided only when selected as an option (N).



Stroke Α В С D Ε F 0 Р S U V W Χ 5 mm, 10 mm [0.197, 0.394] 1.969 1.575 0.591 0.591 0.787 0.472 0.079 0.197 0.157 0.591 0.591 0.512 2.165 15 mm, 20 mm [0.591, 0.787] 2.362 1.969 0.984 0.787 0.984 0.591 0.157 0.394 0.157 0.591 0.591 0.709 25 mm, 30 mm [0.984, 1.181] 2.953 2.756 2.362 1.378 1.181 0.984 0.591 0.157 0.394 0.236 0.079 1.181 0.984 1.102 35 mm, 40 mm [1.378, 1.575] 0.394 0.984 1.496 3.150 2.756 1.772 1.575 0.984 0.591 0.157 0.236 0.079 1.181 0.118 45 mm, 50 mm [1.772, 1.969] 3.150 2.165 0.984 0.591 0.157 0.394 0.315 1.772 1.378 1.890 1.378 2.283 **55 mm, 60 mm [2.165, 2.362]** 4.134 0.394 3.937 3.543 2.559 2.362 0.984 0.591 0.157 0.394 0.157 1.772

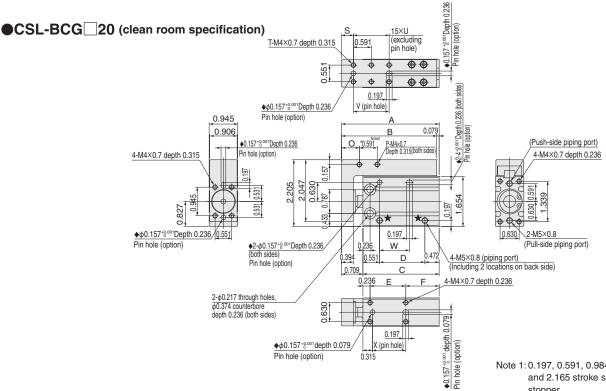
Note 1: 0.197, 0.591, 0.984, 1.378, 1.772, and 2.165 stroke support collar

Note 2: Dimensions indicated by \* are for strokes longer than 0.591.

Note 3: All piping ports are assembled with plugs, except those indicated by \*

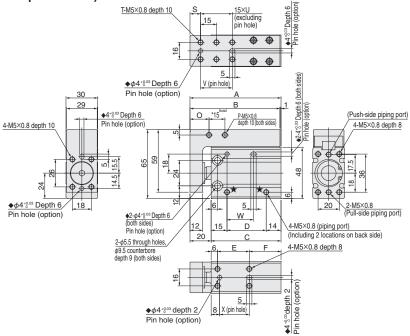
Note 4: Apply grease to o-rings when changing plug assemblies.

Note 5: Pin holes indicated by ◆ are provided only when selected as an option (N).



- W Stroke В С D F F 0 Р S Т U V Χ 5 mm, 10 mm [0.197, 0.394] 2 441 2.362 1.732 0.709 0.591 0.906 0.472 0.079 0.197 0.157 0.591 0.591 0.512 15 mm, 20 mm [0.591, 0.787] 2.835 2.756 2.126 1.102 0.787 1.102 0.591 0.157 0.394 0.591 0.591 0.709 0.157 25 mm, 30 mm [0.984, 1.181] 3.228 3.150 2.520 1.496 1.181 1.102 0.591 0.157 0.394 0.236 0.079 1.181 0.984 1.102 35 mm, 40 mm [1.378, 1.575] 1.575 1.496 3.622 3.543 2.913 1.890 1.102 0.591 0.157 0.394 0.236 0.079 1.181 0.984 45 mm, 50 mm [1.772, 1.969] 4.016 3.937 3.307 2.283 1.969 1.102 0.591 0.157 0.394 0.315 0.118 1.772 1.378 1.890 55 mm, 60 mm [2.165, 2.362] 4.409 0.394 4.331 3.701 2.677 2.362 1.102 0.591 0.157 0.394 0.157 1.772 1.378 | 2.283
- Note 1: 0.197, 0.591, 0.984, 1.378, 1.772, and 2.165 stroke support collar stopper.
- Note 2: Dimensions indicated by \* are for strokes longer than 0.591.
- Note 3: All piping ports are assembled with plugs, except those indicated by \*.
- Note 4: Apply grease to o-rings when changing plug assemblies.
- Note 5: Pin holes indicated by are provided only when selected as an option (N).

#### ●CSL-BCG 25 (clean room specification)



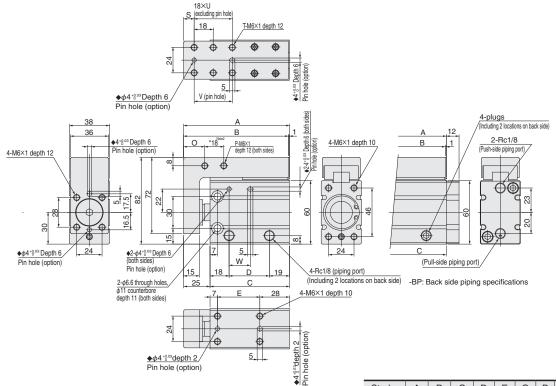
Stroke	Α	В	С	D	Е	F	0	Р	S	Т	U	V	W	Х
5, 10	66	65	46	17	15	25	12	2	5	4	-	15	15	15
15, 20	76	75	56	27	20	30	18	4	10	4	-	15	15	18
25, 30	86	85	66	37	30	30	18	4	10	6	2	30	25	28
35, 40	96	95	76	47	40	30	18	4	10	6	2	30	25	38
45, 50	106	105	86	57	50	30	18	4	10	8	3	45	35	48
55, 60	116	115	96	67	60	30	18	4	10	10	4	45	35	58

Note 1:5, 15, 25, 35, 45, and 55 stroke support collar stopper. Note 2: Dimensions indicated by \* are for strokes longer than 15.

Note 3: All piping ports are assembled with plugs, except those indicated by

Note 4: Apply grease to o-rings when changing plug assemblies. Note 5: Pin holes indicated by ◆ are provided only when selected as an option (N).

#### ●CSL-BCG 32 (clean room specification)



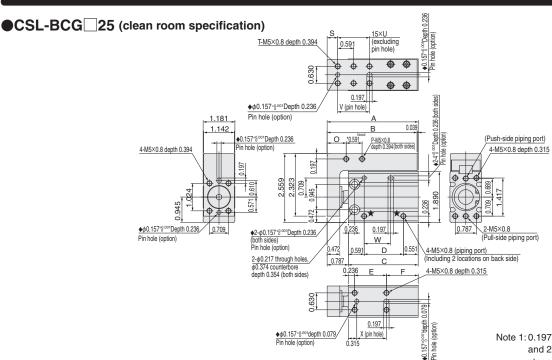
Note 1:15, 25, 35, 45, and 55 stroke support collar stopper.

Note 4: Pin holes indicated by  $\spadesuit$  are provided only when selected as an option (N).

Stroke	Α	В	С	D	Е	0	Р	S	Т	U	٧	W
10	80	79	55	18	20	16	2	6	4	-	18	20
15, 20	90	89	65	28	30	20	2	10	4	-	18	20
25, 30	100	99	75	38	40	20	4	10	6	2	36	30
35, 40	110	109	85	48	50	20	4	10	6	2	36	30
45, 50	120	119	95	58	60	20	4	10	8	3	54	40
55, 60	130	129	105	68	70	20	4	10	8	3	54	40

Note 2: Dimensions indicated by \* are for strokes longer than 25.

Note 3: Plugs are included for specifications other than back side piping specifications. Assemble using sealant, etc.



С 0 Р S ٧ W Χ Stroke В D Е F Т U 5 mm, 10 mm [0.197, 0.394] 2 598 2 559 1.811 0.669 0.591 0.984 0.472 0.079 0.197 0.157 0.591 0.591 0.591 15 mm, 20 mm [0.591, 0.787] 2.992 2.953 2.205 1.063 0.787 1.181 0.709 0.157 0.394 0.157 0.591 0.591 0.709 25 mm, 30 mm [0.984, 1.181] 3.386 3.346 2.598 1.457 1.181 1.181 0.709 0.157 0.394 0.236 0.079 1.181 0.984 1.102 35 mm, 40 mm [1.378, 1.575] 3.780 3.740 2.992 1.850 1.575 1.181 0.709 0.157 0.394 0.236 0.079 1.181 0.984 1.496 1.890 45 mm, 50 mm [1.772, 1.969] 4.173 4.134 3.386 2 244 1.969 1.181 0.709 0.157 0.394 0.315 0.118 1.772 1.378 **55 mm, 60 mm [2.165, 2.362]** 4.567 4.528 3.780 2.638 2.362 1.181 0.709 0.157 0.394 0.394 0.157 1.772 1.378 | 2.283

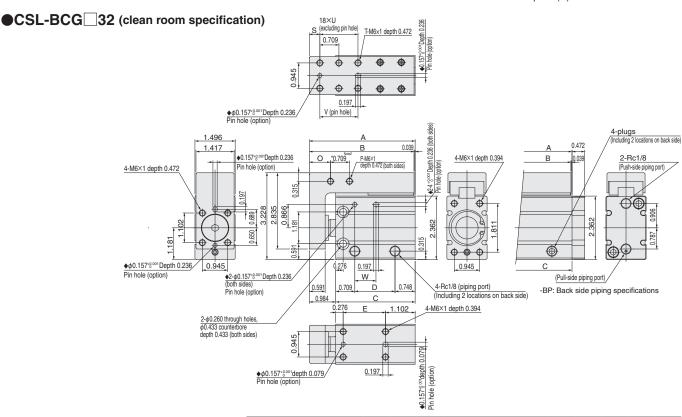
Note 1: 0.197, 0.591, 0.984, 1.378, 1.772, and 2.165 stroke support collar stopper.

Note 2: Dimensions indicated by \* are for strokes longer than 0.591.

Note 3: All piping ports are assembled with plugs, except those indicated by ★.

Note 4: Apply grease to o-rings when changing plug assemblies.

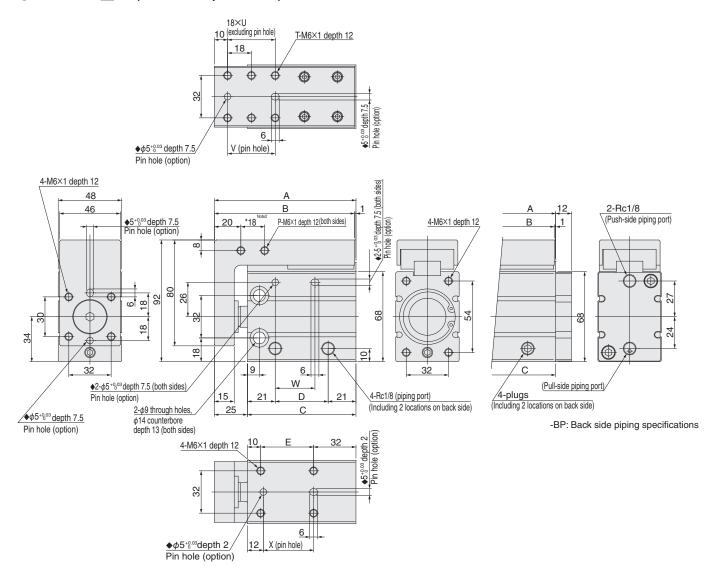
Note 5: Pin holes indicated by ♠ are provided only when selected as an option (N).



- Note 1: 0.591, 0.984, 1.378, 1.772, and 2.165 stroke support collar stopper.
- Note 2: Dimensions indicated by \* are for strokes longer than 0.984.
- Note 3: Plugs are included for specifications other than back side piping specifications. Assemble using sealant, etc.
- Note 4: Pin holes indicated by ◆ are provided only when selected as an option (N).

Stroke	Α	В	С	D	Е	0	Р	S	Т	U	V	W
10 mm [0.394]	3.150	3.110	2.165	0.709	0.787	0.630	0.079	0.236	0.157	-	0.709	0.787
15 mm, 20 mm [0.591, 0.787]	3.543	3.504	2.559	1.102	1.181	0.787	0.079	0.394	0.157	-	0.709	0.787
25 mm, 30 mm [0.984, 1.181]	3.937	3.898	2.953	1.496	1.575	0.787	0.157	0.394	0.236	0.079	1.417	1.181
35 mm, 40 mm [1.378, 1.575]	4.331	4.291	3.346	1.890	1.969	0.787	0.157	0.394	0.236	0.079	1.417	1.181
45 mm, 50 mm [1.772, 1.969]	4.724	4.685	3.740	2.283	2.362	0.787	0.157	0.394	0.315	0.118	2.126	1.575
55 mm, 60 mm [2.165, 2.362]	5.118	5.079	4.134	2.677	2.756	0.787	0.157	0.394	0.315	0.118	2.126	1.575

#### ●CSL-BCG 40 (clean room specification)

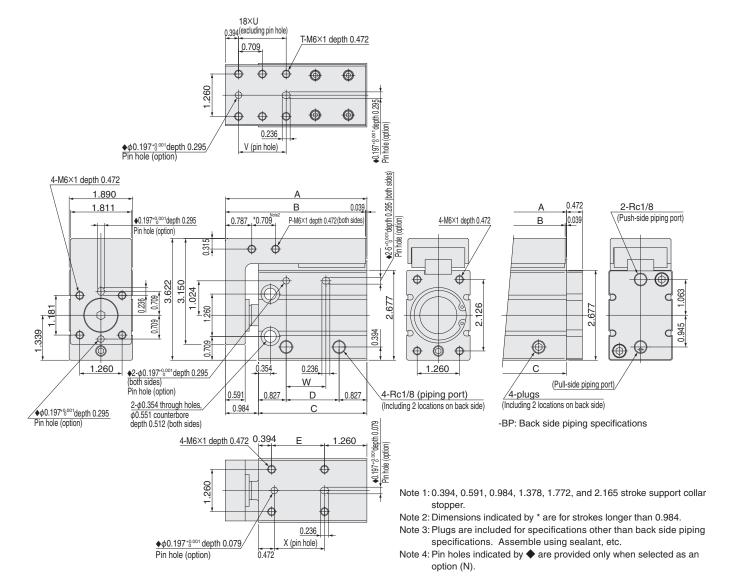


Stroke	Α	В	С	D	Е	Р	Т	U	V	W	Х
10, 15, 20	97	96	72	30	30	2	4	-	18	25	28
25, 30	107	106	82	40	40	4	6	2	36	30	38
35, 40	117	116	92	50	50	4	6	2	36	30	48
45, 50	127	126	102	60	60	4	8	3	54	40	58
55, 60	137	136	112	70	70	4	8	3	54	40	68

- Note 1:10, 15, 25, 35, 45, and 55 stroke support collar stopper.
- Note 2: Dimensions indicated by \* are for strokes longer than 25.
- Note 3: Plugs are included for specifications other than back side piping specifications. Assemble using sealant, etc.

Note 4: Pin holes indicated by ◆ are provided only when selected as an option (N).

#### ●CSL-BCG 40 (clean room specification)



Stroke	Α	В	С	D	Е	Р	T	U	٧	W	Χ
10 mm, 15 mm, 20 mm [0.394, 0.591, 0.787]	3.819	3.780	2.835	1.181	1.181	0.079	0.157	-	0.709	0.984	1.102
25 mm, 30 mm [0.984, 1.181]	4.213	4.173	3.228	1.575	1.575	0.157	0.236	0.079	1.417	1.181	1.496
35 mm, 40 mm [1.378, 1.575]	4.606	4.567	3.622	1.969	1.969	0.157	0.236	0.079	1.417	1.181	1.890
45 mm, 50 mm [1.772, 1.969]	5.000	4.961	4.016	2.362	2.362	0.157	0.315	0.118	2.126	1.575	2.283
55 mm, 60 mm [2,165, 2,362]	5.394	5.354	4.409	2.756	2.756	0.157	0.315	0.118	2.126	1.575	2.677

## **Bracket**

#### Order codes for brackets only mm [in]



Cylinder bore 10:For φ10 [0.394] 40:For φ40 [1.575] 12:For φ 12 [0.472] 50:For φ 50 [1.969] 63:For φ63 [2.480] 16:For  $\phi$  16 [0.630] 20:For φ20 [0.787] 80:For φ80 [3.150] 25:For φ 25 [0.984] 100:For φ100 [3.9]

32:For φ32 [1.260]

Note: Cannot be mounted on cylinders with guides (BCG  $\square$  ).

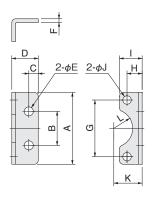
125:For φ125 [4.9]

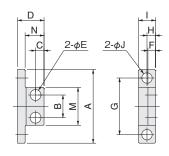
#### Bracket dimensions mm [in]

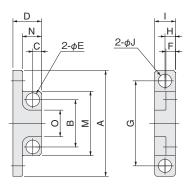
• φ 10 [0.394] to φ 32 [1.260]

• φ **40** [1.575] to φ **80** [3.150]

 $\bullet \phi$  100 [3.9] to  $\phi$  125 [4.9]







#### • Mounting bolt (2 pieces)



Material: Stainless steel (only M16 is steel)

Bore	Α	В	С	D	Е	F	G	Н	I	J	K	L	М	N	0	Р	Q	S	Т	Materials	Mass g[oz]
10 [0.394]	22 [0.866]	16 [0.630]	3 [0.118]	10 [0.394]	3.8 [0.150]	1 [0.039]	16 [0.630]	7 [0.276]	9.3 [0.366]	3.4 [0.134]	8 [0.315]	R5 [0.197]	-	-	-	5 [0.197]	3 [0.118]	4.5 [0.177]	M3 × 0.5	Stainless steel	4 [0.141]
12 [0.472]	26 [1.024]	14 [0.551]	4 [0.157]	13 [0.512]	4.8 [0.189]	1 [0.039]	19 [0.748]	8 [0.315]	11 [0.433]	4.5 [0.177]	8 [0.315]	R5 [0.197]	_	-	-	4 [0.157]	4 [0.157]	5.5 [0.217]	M4 × 0.7	Stainless steel	6 [0.212]
16 [0.630]	28 [1.102]	14 [0.551]	4 [0.157]	13 [0.512]	4.8 [0.189]	1.5 [0.059]	22 [0.866]	7 [0.276]	10 [0.394]	3.5 [0.138]	11 [0.433]	R7 [0.276]	_	-	-	5 [0.197]	3 [0.118]	5.5 [0.217]	M3 × 0.5	Stainless steel	7 [0.247]
20 [0.787]													_	_	_	8 [0.315]	4 [0.157]	7 [0.276]	M4 × 0.7	Stainless steel	12 [0.423]
25 [0.984]	ഹര	40		4.4	1 10		20		10	1 4 5	15 [0.591]	R10	_	-	-	8 [0.315]	4 [0.157]	7 [0.276]	M4 × 0.7	Stainless steel	14 [0.494]
32 [1.260]											19 [0.748]	R12 [0.472]	_	_	-	8 [0.315]	5 [0.197]	8.5 [0.335]	M5 × 0.8	Stainless steel	24 [0.847]
40 [1.575]	52 [2.047]	18 [0.709]	6	20	6.8	5	40	/	13 [0.512]	6.5	_	_	28 [1.102]	14 [0.551]	-	12 [0.472]	6 [0.236]	10 [0.394]	M6 × 1	Aluminum alloy	25 [0.882]
50 [1.969]	00	0.4	7 [0.276]	24 [0.945]	9.5 [0.374]	5 [0.197]	52 [2.047]	7 [0.276]	15 [0.591]	9 [0.354]	-	_	37 [1.457]	18 [0.709]	-	12 [0.472]	8 [0.315]	13 [0.512]	M8 × 1.25	Aluminum alloy	45 [1.587]
63 [2.480]	l 70 l	24	9	28	11.5	8	60	9	18	11	-	-	40 [1.575]	20 [0.787]	-	16 [0.630]	10 [0.394]	16 [0.630]	M10 × 1.5	Aluminum alloy	80 [2.822]
80 [3.150]	90 [3.543]	30 [1.181]	10 [0.394]	36 [1.417]	14.5 [0.571]	8 [0.315]	70 [2.756]	10 [0.394]	20 [0.787]	14 [0.551]	_	_	48 [1.890]	28 [1.102]	_	20 [0.787]	12 [0.472]	18 [0.709]	M12 × 1.75	Aluminum alloy	128 [4.5]
100 [3.9]	112 [4.4]	50 [1.969]	9 [0.354]	30 [1.181]	14.5 [0.571]	10 [0.394]	90 [3.543]	11 [0.433]	22 [0.866]	14 [0.551]	_	_	68 [2.677]	20 [0.787]	28 [1.102]	20 [0.787]	12 [0.472]	18 [0.709]	M12 × 1.75	Aluminum alloy	167 [5.9]
125 [4.9]	140 [5.5]	58 [2.283]	14 [0.551]	42 [1.654]	18.5 [0.728]	14 [0.551]	110 [4.331]	15 [0.591]	30 [1.181]	18 [0.709]	-	_	82 [3.228]	30 [1.181]	30 [1.181]	35 [1.378]	16 [0.630]	24 [0.945]	M16 × 2	Aluminum alloy	410 [14.5]

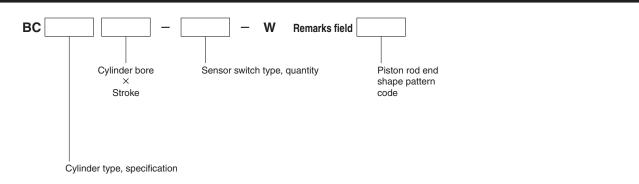
Note: Mass includes mass of 2 supplied bolts



## Piston rod end shape pattern diagrams

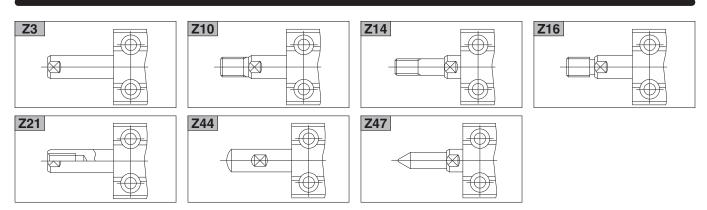
There are seven patternized piston rod end shapes. A non-standard end shaped cylinder can be order made by simply filling in the items on the order that has the required shape drawn on it. This applies to all types of basic cylinders. Contact Koganei for order forms with pattern shaped drawn on them.

#### Order code example



Note: For clean room specifications, CS- or CSL- is appended before BC. For details, see the pages for the corresponding order codes.

#### Piston rod end shape pattern diagrams (7 types)



# **Additional Parts**

```
Note 1: \phi 6 [0.236], \phi 8 [0.315] and \phi 10 [0.394] cannot be disassembled.
     2: Be careful that the steel balls do not fall out from the linear guide when doing maintenance on cylinders
with guides.
Packing set for double acting type (including models with guides)
  BCZ-PK-
                   (For standard specification)
            Cylinder bore
                                                * 1 rod seal, 1 piston seal, 1 o-ring and retaining ring
             12: For BC12, BCG(N)12
             16: For BC16, BCG(N)16
             20: For BC20, BCG(N)20
             25: For BC25, BCG(N)25
             32: For BC32, BCG(N)32
             40: For BC40, BCG(N)40
             50: For BC50
             63: For BC63
             80: For BC80
            100: For BC100
            125: For BC125
  BCZ-PK-R-
                       (For corrosion resistant, clean room specifications)
               Cylinder bore
                                                                                 * 1 rod seal, 1 piston seal, 1 o-ring and retaining ring
                12: For BCR12, CS(L)-BC12, BCG(N)R12, CSL-BCG(N)12
                16: For BCR16, CS(L)-BC16, BCG(N)R16, CSL-BCG(N)16
                20: For BCR20, CS(L)-BC20, BCG(N)R20, CSL-BCG(N)20
                25: For BCR25, CS(L)-BC25, BCG(N)R25, CSL-BCG(N)25
                32: For BCR32, CS(L)-BC32, BCG(N)R32, CSL-BCG(N)32
                40: For BCR40, CS(L)-BC40, BCG(N)R40, CSL-BCG(N)40
                50: For BCR50, CS(L)-BC50
                63: For BCR63, CS(L)-BC63
                80: For BCB80
               100: For BCR100
               125: For BCR125
  BCZ-PK-F-
                       (For heat resistant specification)
               Cylinder bore
                                                 * 1 rod seal, 1 piston seal, 1 o-ring and retaining ring
                12: For BCF12, BCG(N)F12
                16: For BCF16, BCG(N)F16
                20: For BCF20, BCG(N)F20
                25: For BCF25, BCG(N)F25
                32: For BCF32, BCG(N)F32
                40: For BCF40, BCG(N)F40
                50: For BCF50
                63: For BCF63
                80: For BCF80
               100: For BCF100
               125: For BCF125
  BCZ-PK-Y-
                       (For scraper specification)
               Cylinder bore
                                                * 1 rod seal, 1 piston seal, 1 o-ring, 1 scraper, 1 retaining ring
                12: For BCY12
                16: For BCY16
                20: For BCY20
                25: For BCY25
                32: For BCY32
                40: For BCY40
                50: For BCY50
                63: For BCY63
                80: For BCY80
               100: For BCY100
               125: For BCY125
```

NOTE

The grease used when you purchase a packing set for disassembly and re-assembly depends on the specification. Contact Koganei for details.



Products that have been disassembled and reassembled are not covered by the warranty.

# **Additional Parts**

Note:  $\phi$  6 [0.236],  $\phi$  8 [0.315] and  $\phi$  10 [0.394] cannot be disassembled.

Packing set for double acting double rod end type BCZ-PK-D (For standard specification) BCZ-PK-R-D (For corrosion resistant specification) Cylinder bore Cylinder bore \* 2 rod seals, 1 piston seal, 1 o-ring and retaining ring 12: For BCD12 12: For BCDR12 16: For BCD16 16: For BCDR16 20: For BCD20 20: For BCDR20 25: For BCD25 25: For BCDR25 32: For BCD32 32: For BCDR32 40: For BCD40 40: For BCDR40 50: For BCD50 **50:** For BCDR50 63: For BCD63 63: For BCDR63 80: For BCD80 80: For BCDR80 100: For BCDR100 100: For BCD100 125: For BCD125 125: For BCDR125 ●Packing set for single acting push and pull type **BCZ-PK-S** (For standard specification) BCZ-PK-R-S (For corrosion resistant specification) Cylinder bore Cylinder bore \* 1 rod seal, 1 piston seal, 1 o-ring, retaining ring 12: For BCSA12, BCTA12 12: For BCSAR12, BCTAR12 and 1 spring 16: For BCSA16, BCTA16 16: For BCSAR16, BCTAR16 20: For BCSA20, BCTA20 20: For BCSAR20, BCTAR20 25: For BCSA25, BCTA25 25: For BCSAR25, BCTAR25 32: For BCSA32, BCTA32 32: For BCSAR32, BCTAR32 40: For BCSA40, BCTA40 40: For BCSAR40, BCTAR40 50: For BCSA50, BCTA50 50: For BCSAR50, BCTAR50 Piping port plugs for cylinders with guides **BCZ-PM** (For standard, corrosion resistant, clean room specifications) Thread size 3: For M3(For BCG(N)8, BCG(N)R8, CSL-BCG(N)8) 5: For M5(For BCG(N)12, BCG(N)R12, CSL-BCG(N)12, BCG(N)16, BCG(N)R16, CSL-BCG(N)16, BCG(N)20, BCG(N)R20, CSL-BCG(N)20, BCG(N)25, BCG(N)R25, CSL-BCG(N)25) \*4 plugs assembled with o-rings in each bag BCZ-F-PM (For heat resistant specification) Thread size 3: For M3(For BCG(N)F8) **5**: For M5(For BCG(N)F12, BCG(N)F16, BCG(N)F20, BCG(N)F25) Back side piping block for cylinders with guides (For standard specification) BCZ-R-BP **BCZ-BP** (For corrosion resistant, clean room specifications) Cylinder bore Cylinder bore 32: For BCG(N)R32, CSL-BCG(N)32 32: For BCG(N)32 40: For BCG(N)40 40: For BCG(N)R40, CSL-BCG(N)40 BCZ-F-BP (For heat resistant specification) 1 back side piping block with press fitted steel balls Cylinder bore 1 each of two types of o-rings, 2 32: For BCG(N)F32 mounting bolts 40: For BCG(N)F40 The grease used when you purchase a packing set for disassembly and re-assembly depends on the specification. Contact Koganei for details. Products that have been disassembled and reassembled are not covered by the warranty.



# **Sensor switches**

# Solid state type, reed switch type

#### Robot cable is standard equipment

Lead wire flexibility is excellent because the conductor used is the same as for robot cables.

# **Specifications**

# Solid State Type

Item Model	ZE135	ZE155	ZE175	ZE235	ZE255	ZE275		
Wiring method	2-lead wire	3-lead wire with NPN output	3-lead wire with PNP output	2-lead wire	3-lead wire with NPN output	3-lead wire with PNP output		
Lead wire direction	Horiz	ontal		Ver	tical			
Power supply voltage	_	4.5 to 2	28 VDC	_	4.5 to 2	8 VDC		
Load voltage	10 to 28 VDC	4.5 to 2	28 VDC	10 to 28 VDC	4.5 to 2	8 VDC		
Load current	2.5 to 20 mA (at 25°C [77°F], and 10 mA at 60°C [140°F])	40 m <i>A</i>	A max.	2.5 to 20 mA (at 25 $^{\circ}$ C [77 $^{\circ}$ F ], and 10 mA at 60 $^{\circ}$ C [140 $^{\circ}$ F ])	40 mA	max.		
Consumption current	_	8 mA max. (24 VDC)	10 mA max.(24 VDC)	_	8 mA max. (24 VDC)	10 mA max.(24 VDC)		
Internal voltage drop <sup>Note 1</sup>	4 V max.	2 V max. (0.8 V max if I	oad is less than 10 mA)	4 V max.	2 V max. (0.8 V max if lo	oad is less than 10 mA)		
Leakage current	0.7 mA max. (24 VDC, 25°C [77 °F ])	50 μ A ma:	x. (24 VDC)	0.7 mA max. (24 VDC, 25°C [77 °F ])	50 μ A max	c. (24 VDC)		
Response time	1 ms max.							
Insulation resistance	100	O M Ω min. (at 50	0 VDC megger, b	etween case and lead wire termina	l)			
Dielectric strength		500 VAC (50/60 H	lz) 1 minute (betw	veen case and lead wire terminal)				
Shock resistanceNote 2			294.2 m/s <sup>2</sup> [30 G]	(non-repeated)				
Vibration resistanceNote 2		88.3 m/s <sup>2</sup> [9 G]	total amplitude of	1.5 mm [0.059 in], 10 to 55 Hz)				
Protection from environment		IP67 (IE	C standard), JIS	C0920 (watertight type)				
Operation indicators			Red LED indica	tor lit when on				
Lead wires	PCCV0.2SQ x 2-lead (brown and blue) x & Note 3 PCCV0.1SSQ x 3-lead (brown, blue, and black) x & Note 3 PCCV0.2SQ x 2-lead (brown and blue) x & Note 3 PCCV0.1SSQ x 3-lead (brown, blue, and black) x &							
Ambient temperature	0 to 60°C [32 to 140°F]							
Storage temperature range			-10 to 70°C [1	14 to 158°F]				
Mass	15 g [0.53 oz] (for lead wire length A: 1000 mm [39 in]), 35 g [1.23 oz] (for lead wire length B: 3000 mm [118 in]), 15 g [0.53 oz] (for lead wire length 300 mm [11.8 in] with M8 connector)							

Note 1: Internal voltage drop changes with the load current.

# Reed Switch Type

Item Model	ZE1	01 🗌	ZE1	02□	ZE2	01 🗌	ZE202		
Wiring method				2-lead	d wire				
Lead wire direction		Horiz	ontal			Vert	tical		
Load voltage	5 to 28 VDC	85 to 115 VAC (rms)	10 to 28 VDC	85 to 115 VAC (rms)	5 to 28 VDC	85 to 115 VAC (rms)	10 to 28 VDC	85 to 115 VAC (rms)	
Load current	40 mA max.	20 mA max.	5 to 40 mA 5 to 20 mA		40 mA max.	20 mA max.	5 to 40 mA	5 to 20 mA	
Internal voltage drop <sup>Note 1</sup>	0.1 V max. (for load	current of 40 mA DC)	3.0 V	max.	0.1 V max. (for load	current of 40 mA DC)	3.0 V	max.	
Leakage current				0n	nA				
Response time				1 ms	max.				
Insulation resistance		10	00 M Ω min. (at 5	00 VDC megger, b	oetween case and	l lead wire termina	al)		
Dielectric strength			1500 VAC (50/60	Hz) 1 minute (bet	tween case and le	ead wire terminal)			
Shock resistance <sup>Note 2</sup>				294.2 m/s <sup>2</sup> [30 G	i] (non-repeated)				
Vibration resistance <sup>Note 2</sup>		88.3 m/s <sup>2</sup> [9 G] (1	total amplitude of	1.5 mm [0.059 in]	, 10 to 55 Hz), re	sonance frequenc	y 2570 ±250 Hz		
Protection from environment			IP67 (I	EC standard), JIS	C0920 (watertigl	nt type)			
Operation indicators	No	one	Red LED indic	ator lit when on	No	ne	Red LED indic	ator lit when on	
Lead wires		PCCV0.2SQ x 2-lead (brown and blue) x $\ell$ Note 3							
Ambient temperature	0 to 60°C [32 to 140°F]								
Storage temperature range	-10 to 70°C [14 to 158°F]								
Contact protection measure	Required (see page @ under contact protection.)								
Mass	15	15 g [0.53 oz] (for lead wire length A: 1000 mm [39 in]), 35 g [1.23 oz] (for lead wire length B: 3000 mm [118 in])							

Note 1: Internal voltage drop changes with the load current.

2: According to Koganei test standards. 3: Lead wire length  $\ell$ : A; 1000 mm [39 in], B; 3000mm [118 in]

<sup>2:</sup> According to Koganei test standards.

<sup>3:</sup> Lead wire length  $\ell$ : A; 1000 mm [39 in], B; 3000 mm [118 in], G; 300 mm [11.8 in] with M8 connector only on the ZE175 $\square$  and ZE275 $\square$ 

# **Sensor switches**

# Two-color LED solid state type

#### Robot cable is standard equipment

Lead wire flexibility is excellent because the conductor used is the same as for robot cables.

# **Specifications**

#### Two-color LED solid state type

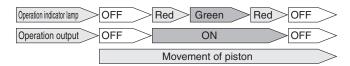
Item Model	ZE137□	ZE157	ZE177	ZE237□	ZE257	ZE277		
Wiring method	2-lead wire	3-lead wire with NPN output	3-lead wire with PNP output	2-lead wire	3-lead wire with NPN output	3-lead wire with PNP output		
Lead wire direction	Horiz	ontal		Ver	tical			
Power supply voltage	_	4.5 to 2	28 VDC	_	4.5 to 2	8 VDC		
Load voltage	10 to 28 VDC	4.5 to 2	28 VDC	10 to 28 VDC	4.5 to 2	8 VDC		
Load current	2.5 to 20 mA (at 25°C [77°F], and 10 mA at 60°C [140°F])	40 m	A max.	2.5 to 20 mA (at 25°C [77°F ], and 10 mA at 60°C [140°F ])	40 mA	max.		
Consumption current	_	8 mA max. (24 VDC)	10 mA max.(24 VDC)	_	8 mA max. (24 VDC)	10 mA max.(24 VDC)		
Internal voltage drop <sup>Note 1</sup>	4 V max.	2 V max. (0.8 V max if I	oad is less than 10 mA)	4 V max.	2 V max. (0.8 V max if lo	oad is less than 10 mA)		
Leakage current	0.7 mA max. (24 VDC, 25°C [77 °F ])	50 μ A ma	x. (24 VDC)	0.7 mA max. (24 VDC, 25°C [77 °F ])	50 μ A max	c. (24 VDC)		
Response time	1 ms max.							
Insulation resistance	100	O M Ω min. (at 50	0 VDC megger, b	etween case and lead wire termina	l)			
Dielectric strength		500 VAC (50/60 H	dz) 1 minute (betw	veen case and lead wire terminal)				
Shock resistanceNote 2			294.2 m/s <sup>2</sup> [30 G]	(non-repeated)				
Vibration resistanceNote 2		88.3 m/s <sup>2</sup> [9 G]	(total amplitude of	1.5 mm [0.059 in], 10 to 55 Hz)				
Protection from environment		IP67 (IE	C standard), JIS (	C0920 (water-proof type)				
Operation indicators	Appropriate operation range: Green LED indicator lit when on, operation range: Red LED indicator lit when on							
Lead wires	PCCV0.2SQ x 2-lead (brown and blue) x & Note 3 PCCV0.1SSQ x 3-lead (brown, blue, and black) x & Note 3 PCCV0.2SQ x 2-lead (brown and blue) x & Note 3 PCCV0.1SSQ x 3-lead (brown, blue, and black) x &							
Ambient temperature	0 to 60°C [32 to 140°F]							
Storage temperature range			-10 to 70°C [1	4 to 158°F]				
Mass	15 g [0.53 oz] (for lead wire length A: 1000 mm [39 in]), 35 g [1.23 oz] (for lead wire length B: 3000 mm [118 in]), 15 g [0.53 oz] (for lead wire length 300 mm [11.8 in] with M8 connector)							

Note 1: Internal voltage drop changes with the load current.

# Operation

# Explanation of operation of two-color LED solid state type

**ZE137**□, **ZE157**□, **ZE177**□, **ZE237**□, **ZE257**□, **ZE277**□



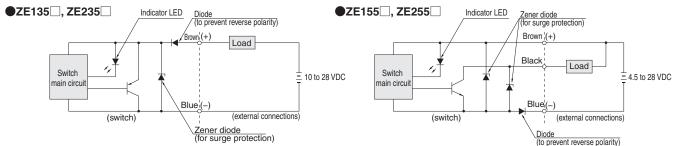
Note: The operating output may become unstable, due to the effects of the operating and installation environments, even if the appropriate operating range (green LED indicator lit) is fixed.

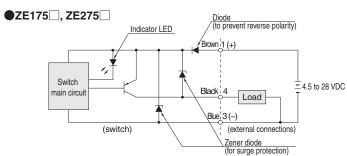
<sup>2:</sup> According to Koganei test standards.

<sup>3:</sup> Lead wire length ℓ: A; 1000 mm [39 in], B; 3000 mm [118 in], G; 300 mm [11.8 in] with M8 connector only on the ZE177□ and ZE277□

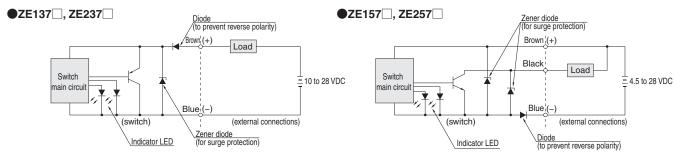
# Diagram of inner circuits

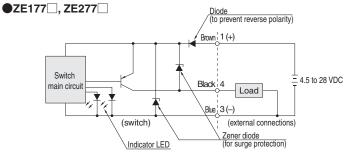
# Solid State Type



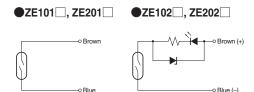


# ■ Two-color LED solid state type

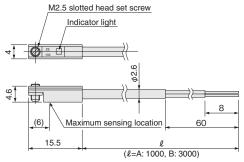


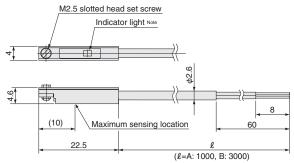


# Reed Switch Type

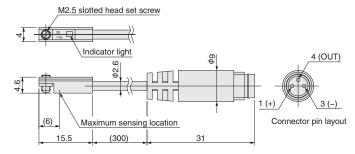


#### Horizontal lead wire





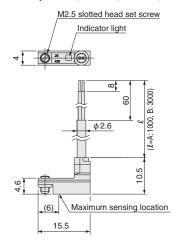
Solid state (ZE175G, ZE177G)



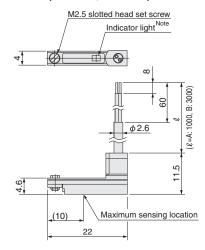
Note: Not available with the ZE101  $\square$  .

#### Vertical lead wire

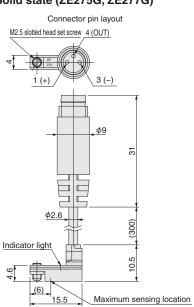
**●**Solid state (ZE235□, ZE255□, ZE275□, ZE237□, ZE257□, ZE277□)



#### ● Reed switch (ZE201 □, ZE202 □)



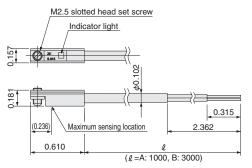
● Solid state (ZE275G, ZE277G)



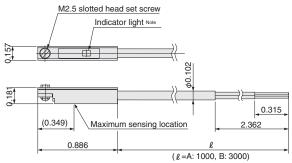
Note: Not available with the ZE201  $\square$  .

#### Horizontal lead wire

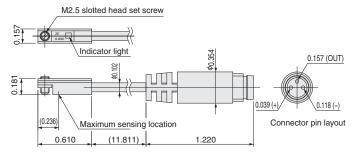
● Solid state (ZE135□, ZE155□, ZE175□, ZE137□, ZE157□, ZE177□)



●Reed switch (ZE101□, ZE102□)



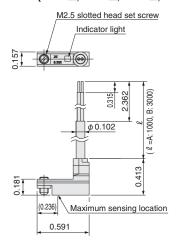
Solid state (ZE175G, ZE177G)



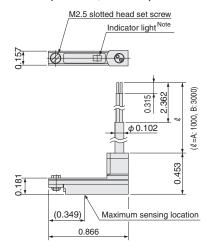
Note: Not available with the ZE101  $\square$  .

#### Vertical lead wire

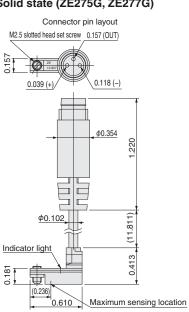
**●** Solid state (ZE235□, ZE255□, ZE275□, ZE237□, ZE257□, ZE277□)



● Reed switch (ZE201 □, ZE202 □)



Solid state (ZE275G, ZE277G)

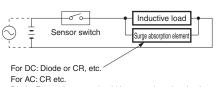


Note: Not available with the ZE201  $\square$  .

# Contact Protection for Reed Switch Type Sensor Switch

In order to use the reed switch type sensor switch safely, take the contact protection measures listed below.

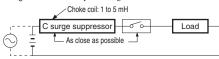
# For connecting an inductive load (electromagnetic relay)



Diode: Forward current should be more than the circuit current, and for reverse direction, dielectric strength should be 10 times greater or more than the circuit voltage.

#### For capacitive surges

(When the lead wire length exceeds 10 m [32.808 ft])



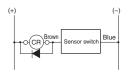
# Wiring instructions for the solid state sensor switches

#### 2-lead wire

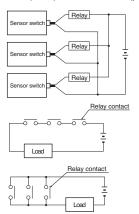
#### Basic connection



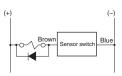
#### Connection to relays



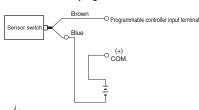
AND (series) connection and OR (parallel) connection



#### Connection to solenoid valve

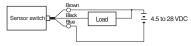


#### Connection to programmable controller

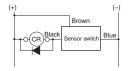


# 3-lead wire with NPN output type

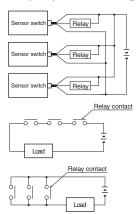
#### Basic connection



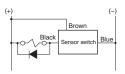
#### Connection to relays



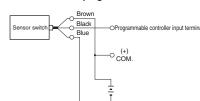
AND (series) connection and OR (parallel) connection



#### Connection to solenoid valve



#### Connection to programmable controller

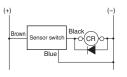


#### 3-lead wire with PNP output type

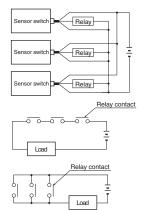
#### Basic connection



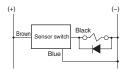
#### Connection to relays



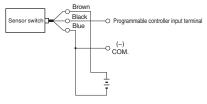
AND (series) connection and OR (parallel) connection



#### Connection to solenoid valve



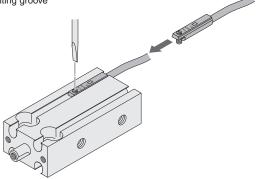
# Connection to programmable controller



- 1. Connect the lead wires according to their color. Incorrect wiring will cause damage to the sensor switch.
- 2. The use of a surge protection diode is recommended with the inductive load such as an electromagnetic relay.
- 3. Avoid the use of AND (series) connections because the circuit voltage will drop in proportion to the number of sensor switches.
- 4. When using an OR (parallel) connection, it is possible to connect sensor switch outputs directly (ex: using corresponding black lead wires). Be aware of load return errors since current leakage increases with the number of switches.
- 5. Because the sensor switches are magnetically sensitive, avoid using them in locations subject to strong external magnetic fields or bringing them in close proximity to power lines and areas where large electric currents are present. Also avoid using magnetic material for any parts used for mounting. It could result in erratic operation.
- 6. Do not excessively pull on or bend the lead wires.
- 7. Avoid using the switches in environments where chemicals or gas are present.
- 8. Consult the nearest Koganei sales office for use in environments subject to water or oil.

# **Moving Sensor Switch**

- Loosening the screw allows the sensor switch to be moved along the switch mounting groove
  of the cylinder tube.
- The tightening torque for the screws is 0.1 to 0.2 N•m [0.86 to 1.77 in•lbf].



# Sensor Switch Operating Range, Response Differential, and Maximum Sensing Location

#### Operating range: &

The range from where the piston turns the switch on and the point where the switch is turned off as the piston travels in the same direction.

Response differential: C

The distance between the point where the piston turns the switch on and the point where the switch is turned off as the piston travels in the opposite direction.

#### Solid State Type

Unit: mm														
Item <u>Diameter</u>	6	8	10	12	16	20	25	32	40	50	63	80	100	125
Operating range: $\ell$	1.5	to 5		2 to 5 2 to 6				3 to 7	3 to 7 3 to 11					
Response differential: C		0.3 or less												
Maximum sensing location Note							(	6						

Note: The values in the table above are reference values. Note: The value from the opposite end of the lead wire. (shown by arrow)

unit: in

Item Diameter	0.236	0.315	0.394	0.472	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9
Operating range: $\ell$	0.059 to	0.197	0.07	9 to 0	.197	0.07	'9 to 0	.236	0.118 to 0.276		0.11	8 to 0.	433	
Response ifferential: C		0.012 or less												
Maximum sensing location Note		0.236												

Note: The values in the table above are reference values. Note: The value from the opposite end of the lead wire. (shown by arrow)

#### Reed Switch Type

unit. min											
Item Diameter	16	20	25	32	40	50	63	80	100	125	
Operating range: $\ell$	3 to 9		4 to 12		6 to 14		7 to 18		8 to 19	8 to 24	
Response differential: C		0.3 or less									
Maximum sensing location Note	10										

Note: The values in the table above are reference values. Note: The value from the opposite end of the lead wire. (shown by arrow)

unit: in

Item Diameter	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9
Operating renges (	0.118 to	0.1	0.157 to 0.470			0.0	0.276 to 0.709			0.315 to
Operating range: &	0.354	0.157 to 0.472			0.551	0.2	76 10 0.7	09	0.748	0.945
Response differential: C		0.012 or less								
Maximum sensing location Note		0.394								

Note: The values in the table above are reference values. Note: The value from the opposite end of the lead wire. (shown by arrow)

#### ■ Two-color LED solid state type

unit: mm

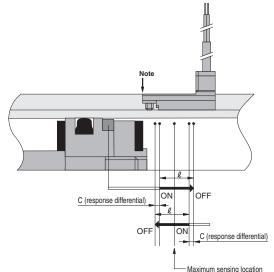
Item Diameter	6	8	10	12	16	20	25	32	40	50	63	80	100	125
Operating range: $\ell$	1.5	to 5	2 to 6			3 to 8				5 to 12				
Response differential: C			0.5 or less											
Maximum sensing location Note		6												

Note: The values in the table above are reference values. Note: The value from the opposite end of the lead wire. (shown by arrow)

unit: in

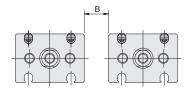
Item Diameter	0.236	0.315	0.394	0.472	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9
Operating range: &	0.05 0.1		0	0.079 to 0.236			0.11	8 to 0	.315	C	0.197 to 0.472			
Response differential: C		0.020 or less												
Maximum sensing location <sup>Note</sup>		0.236												

Note: The values in the table above are reference values. Note: The value from the opposite end of the lead wire. (shown by arrow)



# When Mounting the Cylinders with Sensor Switches in Close Proximity

When using it connected to a cylinder, use under conditions using values greater than those shown in the table below.



Note: Install a shield plate (at least 1 mm [0.039 in] thick magnetic material) between two cylinders to use them in close proximity. However, magnetic materials cannot be used in magnetized environments.

#### Reed Switch Type

		unit: mm
Cylinder bore	Α	В
16		
20		
25		
32		
40	10	0
50	12	U
63		
80		
100		
125		

#### Solid State Type

		unit: mm
Cylinder bore	Α	В
6		
8		
10		
12		
16		
20		
25	14	0
32	14	U
40		
50		
63		
80		
100		
125		

# ■ Two-color LED Solid State Type

		unit: mm
Cylinder bore	Α	В
6		
8		
10		
12		
16		
20		
25	23	0
32	23	0
40		
50		
63		
80		
100		
125		

		unit: i
Cylinder bore	Α	В
0.630		
0.787		
0.984		
1.260	0.472	
1.575		0
1.969	0.472	0
2.480		
3.150		
3.9		
4.9		

		unit: in
Cylinder bore	Α	В
0.236		
0.315		
0.394		
0.472		
0.630		
0.787		
0.984	0.551	0
1.260	0.551	U
1.575		
1.969		
2.480		
3.150		
3.9		
40		

		unit: in
Cylinder bore	Α	В
0.236		
0.315		
0.394		
0.472		
0.630		
0.787		
0.984	0.906	0
1.260	0.900	0
1.575		
1.969		
2.480		
3.150		
3.9		
4.9		

# For cylinder with guide

# Reed Switch Type

		unit: mm
Cylinder bore	Α	В
16		
20		
25	11	0
32		
40		

#### Solid State Type

- coma ota	, po	
		unit: mn
Cylinder bore	Α	В
8		
12		
16		
20	23	0
25		
32		
40		

#### ● Two-color LED Solid State Type

•		otato . y po
		unit: mm
Cylinder bore	Α	В
8		
12		
16		
20	15	0
25		
32		
40		

		unit: ir
Cylinder bore	Α	В
0.630		
0.787		
0.984	0.433	0
1.260		
1.575		

		unit: in
Cylinder bore	Α	В
0.315		
0.472		
0.630		
0.787	0.906	0
0.984		
1.260		
1.575		

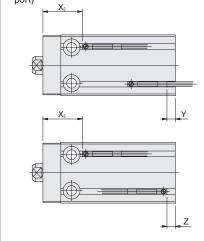
		unit: in
Cylinder bore	Α	В
0.315		
0.472		
0.630		
0.787	0.591	0
0.984		
1.260		
1.575		

# Mounting Position of the End of Stroke Detection Sensor Switch

Mounting the sensor switch in the locations shown (reference values in diagram), the sensor magnet comes to the maximum sensing location of the sensor switch at the end of the stroke.

# X Y Y

- Scraper specification
- Clean room specification (with dust collection port)



\* When the Y dimension is negative, the sensor switch protrudes from the cylinder body.

# ■ Double acting type ■ Single acting push type ■ Single acting pull type.

Solid stat	Solid state type (2-color LED included) unit: mm														
Item	ore	6	8	10	12	16	20	25	32	40	50	63	80	100	125
Double	Х	10.5	11	11	11	12	15 (20)	16 (21)	17.5	22.5	27.5	33.5	34.5	46.5	53
	$\chi_2$	_	_	21	21	22	25 (30)	26 (31)	32.5	37.5	42.5	53.5	*54.5	*66.5	*73
acting	Υ	0	-0.5	0.5	1.5	2.5	3.5	4.5	7	9	10	12	14	18	19.5
type	Z	3.5	3	4	5	6	7	8	10.5	12.5	13.5	15.5	17.5	21.5	23
Push	Х	25.5	26	26	26	27	30	31	32.5	37.5	47.5	_	_	_	_
Single	Υ	0	-0.5	0.5	1.5	2.5	3.5	4.5	7	9	10	_	_	_	_
acting type	Z	3.5	3	4	5	6	7	8	10.5	12.5	13.5	_	_	_	_
Pull	Х	25.5	26	26	26	27	30	31	32.5	37.5	47.5	_	_	_	_
Single	Υ	0	-0.5	0.5	1.5	2.5	3.5	4.5	7	9	10	_	_	_	_
acting type	Z	3.5	3	4	5	6	7	8	10.5	12.5	13.5	_	_	_	_

Note: Dimensions in ( ) parentheses are for 5 mm dimensions for scraper specification only.

Reed Sw	Reed Switch Type unit: mm														
Item	ore	6	8	10	12	16	20	25	32	40	50	63	80	100	125
Double	Х	_	_	_	_	8	11 (16)	12 (17)	13.5	18.5	23.5	29.5	30.5	42.5	49
acting	<b>X</b> 2	_	_	_	_	18	21 (26)	22 (27)	28.5	33.5	38.5	49.5	*50.5	*62.5	*69
Ü	Υ	_	_	_	_	-0.5	0.5	1.5	4	6	7	9	11	15	16.5
type	Z	_	_	_	_	2	3	4	6.5	8.5	9.5	11.5	13.5	17.5	19
Push	Х	_	_	_	_	23	26	27	28.5	33.5	43.5	_	_	_	_
Single	Υ	_	_	_	_	-0.5	0.5	1.5	4	6	7	_	_	_	_
acting type	Z	_	_	_	_	2	3	4	6.5	8.5	9.5	_	_	_	_
Pull	Χ	_	_	_	_	8	11	12	13.5	18.5	23.5	_	_	_	_
Single acting type	Υ	_	_	_	_	14.5	10.5	11.5	14	16	27	_	_	_	_
	Z	_	_	_	_	17	13	14	16.5	18.5	29.5	_	_	-	_

Note: Dimensions in ( ) parentheses are for 5 mm stroke models.\* \* Indicates dimensions for scraper specification only.

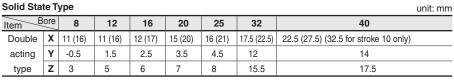
#### Double acting double rod end type

Solid state type (2-color LED included) unit: mm															
Item	ore	6	8	10	12	16	20	25	32	40	50	63	80	100	125
Double	X	10.5	11	11	11	12	15	16	17.5	22.5	27.5	33.5	34.5	46.5	53

Double	X	10.5	11	11	11	12	15	16	17.5	22.5	27.5	33.5	34.5	46.5	53
acting	Υ	4	4.5	5.5	6.5	7.5	8.5	9.5	12	14	20	22	24	18	19.5
type	Z	7.5	8	9	10	11	12	13	15.5	17.5	23.5	25.5	27.5	21.5	23
Reed Switch Type unit: mm															

i icca owi	tori	Type												ui	
Item	ore	6	8	10	12	16	20	25	32	40	50	63	80	100	125
Double	X	_	_	_	_	8	11	12	13.5	18.5	23.5	29.5	30.5	42.5	49
acting	Υ	_	_	_	_	4.5	5.5	6.5	9	11	17	19	21	15	16.5
type	Z	_	_	_	_	7	8	9	11.5	13.5	19.5	21.5	23.5	17.5	19

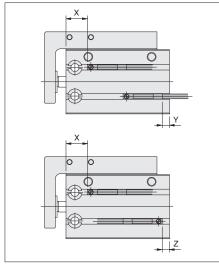
# Double acting type with guide



Note: Dimensions in ( ) parentheses are for mid-stroke models (stroke 5, 15, 25, 35, 45, and 55).

Reed Switch Type unit: mm												
Item	ore	8	12	16	20	25	32	40				
Double	Х	_	_	8 (13)	11 (16)	12 (17)	13.5 (18.5)	18.5 (23.5) (28.5 for stroke 10 only)				
acting	Υ	_	_	-0.5	0.5	1.5	9	11				
type	z	-	_	2	3	4	11.5	13.5				

Note: Dimensions in ( ) parentheses are for mid-stroke models (stroke 5, 15, 25, 35, 45, and 55).

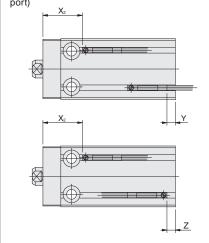


<sup>\*</sup> When the Y dimension is negative, the sensor switch protrudes from the cylinder body.

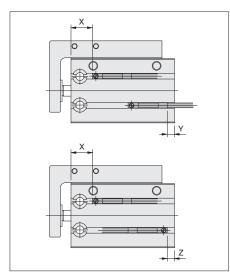
Mounting the sensor switch in the locations shown (reference values in diagram), the sensor magnet comes to the maximum sensing location of the sensor switch at the end of the stroke.

# Z

- · Scraper specification
- Clean room specification (with dust collection port)



\* When the Y dimension is negative, the sensor switch protrudes from the cylinder body.



\* When the Y dimension is negative, the sensor switch protrudes from the cylinder body.

# ■ Double acting type ■ Single acting push type ■ Single acting pull type.

Solid stat	on a state type (2 color 222 mended)													unit: in	
Item	ore	0.236	0.315	0.394	0.472	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9
Double	х	0.413	0.433	0.433	0.433	0.472	0.591 (0.787)	0.630 (0.827)	0.689	0.886	1.083	1.319	1.358	1.831	2.087
acting	<b>X</b> 2	-	-	0.827	0.827	0.866	0.984 (1.181)	1.024 (1.220)	1.280	1.476	1.673	2.106	*2.146	*2.618	*2.874
type	Υ	0	-0.020	0.020	0.059	0.098	0.138	0.177	0.276	0.354	0.394	0.472	0.551	0.709	0.768
	Z	0.138	0.118	0.157	0.197	0.236	0.276	0.315	0.413	0.492	0.531	0.610	0.689	0.846	0.906
Push	Х	1.004	1.024	1.024	1.024	1.063	1.181	1.220	1.280	1.476	1.870	_	_	-	-
Single	Υ	0	-0.020	0.020	0.059	0.098	0.138	0.177	0.276	0.354	0.394	_	_	-	-
acting type	Z	0.138	0.118	0.157	0.197	0.236	0.276	0.315	0.413	0.492	0.531	_	_	-	-
Pull	Х	1.004	1.024	1.024	1.024	1.063	1.181	1.220	1.280	1.476	1.870	-	_	-	_
Single	Υ	0	-0.020	0.020	0.059	0.098	0.138	0.177	0.276	0.354	0.394	-	_	_	_
acting type	Z	0.138	0.118	0.157	0.197	0.236	0.276	0.315	0.413	0.492	0.531	_	_	_	

Note: Dimensions in ( ) parentheses are for 0.197 in stroke models.\* \* Indicates dimensions for scraper specification only.

#### Reed Switch Type

unit: in

Item	ore	0.236	0.315	0.394	0.472	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9
Double	х	-	-	-	-	0.315	0.433 (0.630)	0.472 (0.669)	0.531	0.728	0.925	1.161	1.201	1.673	1.929
acting	<b>X</b> 2	_	_	ı	_	0.709	0.827 (1.024)	0.866 (1.063)	1.122	1.319	1.516	1.949	*1.988	*2.461	*2.717
type	Υ	-	_	_	_	-0.020	0.020	0.059	0.157	0.236	0.276	0.354	0.433	0.591	0.650
	Z	_	-	_	-	0.079	0.118	0.157	0.256	0.335	0.374	0.453	0.531	0.689	0.748
Push	Х	-	_	_	_	0.906	1.024	1.063	1.122	1.319	1.713	_	-	-	-
Single	Υ	_	_	_	_	-0.020	0.020	0.059	0.157	0.236	0.276	_	_	-	-
acting type	Z	_	_	_	_	0.079	0.118	0.157	0.256	0.335	0.374	_	_	-	-
Pull	Х	_	_	_	_	0.315	0.433	0.472	0.531	0.728	0.925	_	-	-	_
Single	Υ	_	_	_	_	0.571	0.413	0.453	0.551	0.630	1.063	_	_	-	-
acting type	Z	_	_	_	_	0.669	0.512	0.551	0.650	0.728	1.161	_	-	-	_

Note: Dimensions in ( ) parentheses are for 0.197 in stroke models.\*\* Indicates dimensions for scraper specification only.

# Double acting double rod end type

#### Solid state type (2-color LED included)

Item	ore	0.236	0.315	0.394	0.472	0.630	0.787	0.984	1.260	1.575	1.969	2.480	3.150	3.9	4.9
Double	Х	0.413	0.433	0.433	0.433	0.472	0.591	0.630	0.689	0.886	1.083	1.319	1.358	1.831	2.087
acting	Υ	0.157	0.177	0.217	0.256	0.295	0.335	0.374	0.472	0.551	0.787	0.866	0.945	0.709	0.768
type	Z	0.295	0.315	0.354	0.394	0.433	0.472	0.512	0.610	0.689	0.925	1.004	1.083	0.846	0.906

#### **Reed Switch Type** unit: in Bore 0.236 0.315 0.394 0.472 0.630 0.787 0.984 1.260 1.575 1.969 2.480 3.150 3.9 4.9 Double 0.315 0.433 0.472 0.531 0.728 0.925 1.161 1.201 1.673 1.929 acting 0.177 0.354 0.433 0.669 0.748 0.827 0.650 0.217 0.256 0.591 z 0.315 0.846 0.276 0.354 0.453 0.531 0.768 0.748 type 0.925 0.689

# Double acting type with guide

#### Solid State Type

		· ·						uriit. iii
Item	ore	0.315	0.472	0.630	0.787	0.984	1.260	1.575
Double	v	0.433	0.433	0.472	0.591	0.630	0.689	0.886(1.083) (1.280 for stroke 0.394 only)
	_	(0.630)	(0.630)	(0.669)	(0.787)	(0.827)	(0.886)	0.000(1.003) (1.200 for Stroke 0.394 offly)
acting	Υ	-0.020	0.059	0.098	0.138	0.177	0.472	0.551
type	Z	0.118	0.197	0.236	0.276	0.315	0.610	0.689

Note: Dimensions in () parentheses are for mid-stroke models (stroke 0.197, 0.591, 0.984, 1.378, 1.772, and 2.165).

### Reed Switch Type

		. )   0			unit: in			
Item	ore	0.315	0.472	0.630	0.787	0.984	1.260	1.575
Double	х	_	_	0.315 (0.512)	0.433 (0.630)	0.472 (0.669)	0.531 (0.728)	0.728(0.925) (1.122 for stroke 0.394 only)
acting	Υ	_	_	-0.020	0.020	0.059	0.354	0.433
type	Z	_	_	0.079	0.118	0.157	0.453	0.531

Note: Dimensions in ( ) parentheses are for mid-stroke models (stroke 0.197, 0.591, 0.984, 1.378, 1.772, and 2.165).



# **Limited Warranty**

KOGANEI CORP. warrants its products to be free from defects in material and workmanship subject to the following provisions.

**Warranty Period** 

The warranty period is 180 days from the date of delivery.

Koganei Responsibility If a defect in material or workmanship is found during the warranty period, KOGANEI CORP. will replace any part proved defective under normal use free of charge and will provide the service necessary to replace such a part.

Limitations

 This warranty is in lieu of all other warranties, expressed or implied, and is limited to the original cost of the product and shall not include any transportation fee, the cost of installation or any liability for direct, indirect or consequential damage or delay resulting from the defects.

- KOGANEI CORP. shall in no way be liable or responsible for injuries or damage to persons or property arising out of the use or operation of the manufacturer's product.
- This warranty shall be void if the engineered safety devices are removed, made inoperative or not periodically checked for proper functioning.
- Any operation beyond the rated capacity, any improper use or application, or any improper installation of the product, or any substitution upon it with parts not furnished or approved by KOGANEI CORP., shall void this warranty.
- This warranty covers only such items supplied by KOGANEI CORP. The products of other manufacturers are covered only by such warranties made by those original manufacturers, even though such items may have been included as the components.

The specifications are subject to change without notice.

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